

5-7 Outline of Various Train Radio Systems in JR

Table 1 Train Radio System Used in JR Conventional Lines

Line	Purpose	Range of communication	Frequency/ communication system
Yamanote and Keihin-Tohoku lines (started in 1981)	For communications between dispatchers and train drivers, as well as for communications in the event of ATC failure	Driver ↔ Dispatcher	400 MHz band Duplex 1 CH
Joban line (started in 1966)	For emergency communications between wayside and train drivers at accident. Used to prevent secondary accidents, as well as for communications to support ATC.	Driver ↔ Dispatcher (emergency communications) Train ↔ Train Wayside ↔ Train (stop signal for train protection)	150 MHz band Half Duplex 1 CH Protection radio 1 CH
Yokokawa - Karuizawa section (started in 1963)	For communications between drivers in double-header operations in the section	Main engine ↔ Auxiliary engine driver (communications for joint operation) Main engine ↔ Station manager/engine depot manager driver Auxiliary engine driver (emergency communications)	400 MHz band Duplex 2 CH
Aomori - Hakodate ferryboat information service (started in 1962)	For communications between limited express train and wayside for information on ferryboat services	Train conductor — Related office (via switchboard) Reporting the number of train passengers and ferryboat information	150 MHz band Duplex 1 CH

Table 2 Train Radio Systems Used in JR Shinkansen

Category		Tokaido/Sanyo Shinkansen	Tohoku/Joetsu Shinkansen
1	No. of channels ( ) - No. of channels actually used	Dispatcher system (operation) 2 CH Dispatcher system (passenger service) 2 CH Exchange system (service/public) 6 CH Total 10 CH (10 CH)	Dispatcher system (operation) 4 CH Dispatcher system (passenger service) 2 CH Exchange system (service/public) 12 CH Data processing system 6 CH Total 24 CH (15 CH)
	Service area (calling range)	More than 99.9%	More than 99.99%
2	Line quality	S/N 35 dB or more throughout entire line	S/N 40 dB or more throughout 99% of the entire line
	Connection stability (code error rate)	More than 99%	Less than $1 \times 10^{-4}$ for 1,200 bits/sec
3	Radio system	Space wave multiplex (base station only)	LCX
	Frequency	Base station 400 MHz band 3 waves Mobile station 400 MHz band 10 waves	Base station 400 MHz band 1 wave Mobile station 400 MHz band 24 waves
4	Output	Base station 40 W Mobile station 4 W	Base station 2 W Mobile station 4 W
5	Antenna	Base station : Grid parabola, corner reflector, Yagi 8-element Mobile station : Uni-polar array, two-way switching (longitudinal)	Base station : Leakage coaxial cable Mobile station : Slot array 4-element composition
6	Public telephone service	Public telephone service between trains and wayside cities A B: Calling via switchboards	Nationwide public telephone service B A: PB dial calling A B: Calling via switchboard

5-8 Classification and Allocation of the Existing Level Crossings between Ghaziabad and Kanpur

Class		Number
Type	A	12
	B	27
	C	127
	Total	166
Interlocked with gate signal		51

where:

	Train-vehicle units per day
A	More than 14,000
B	More than 6,000
C	More than 5,000

5-9 Comparison among Level Crossing Control Systems

Table 1 Level Crossing Control Systems of India and Japan

Type Item	Japan	India	Improved method
Basic conception	<ol style="list-style-type: none"> <li>1) To warn the passersby on the road of train approach</li> <li>2) Timing of warning : the timing so that a passersby who has entered into the level crossing before the warning begins can safely cross it, and that matches the emergency braking distance of train.</li> <li>3) Automatic barrier operation</li> </ol>	<ol style="list-style-type: none"> <li>1) No warning of train approach to the passersby on the road</li> <li>2) The gatekeeper is informed of the train's approach from the adjacent station by telephone, etc. beforehand.</li> <li>3) The gatekeeper manual closes the gate well in advance of the train's arrival on receipt of the announcement of train approach.</li> </ol>	<ol style="list-style-type: none"> <li>1) To warn the passersby on the road of train approach</li> <li>2) Automatic barrier operation and, in case of accident at level crossing, manual operation by the gate keeper.</li> <li>3) Gate signal is commonly used with the block signal</li> </ol>
Interlocking with signal	<ol style="list-style-type: none"> <li>1) No interlocking</li> <li>2) In the event of accident at level crossing, manual or automatic operation of special warning signal light to inform the train driver.</li> </ol>	<ol style="list-style-type: none"> <li>1) At the level crossing at a busy road, the interlocking between of gate and gate signal makes to allow 'go' to the gate signal after the gate has completely closed.</li> </ol>	<ol style="list-style-type: none"> <li>1) Interlocking between every level crossings and gate signals is provided.</li> </ol>
Safety	<ol style="list-style-type: none"> <li>1) In case of level crossing facilities failure, the safety of passersby is ensured by automatically closing the barrier.</li> <li>2) When a passersby remains within the level crossing after the warning time an accident may occur.</li> </ol>	<ol style="list-style-type: none"> <li>1) Gate signal indicates 'Stop' when the adjacent station fails to make the train approach announcement, or when the gate-keeper foregets the train approach announcement or fails to close the gate.</li> <li>2) 'Stop' is indicated on the gate signal when the gate closing operation is interrupted by passersby or vehicles within the level crossing.</li> </ol>	<ol style="list-style-type: none"> <li>1) 'Stop' is indicated on the gate signal when the gate closing operation is interrupted by passersby or vehicles in the level crossing.</li> <li>2) 'Stop' signal is manually indicated on the gate signal when a passersby remains within the level crossing after the gate has closed.</li> <li>3) Gate is automatically closed for the safety of passersby by the fail-safe operation in case of facilities failure.</li> </ol>

Table 2 Calculation of the Traffic Suspension Ratio by Each System

Item	Type	Japan	India	Improved method
Level crossing		Mainly unmanned level crossing	Manned level crossing	Manned level crossing
Warning and gate barrier closing operation		<p>Start of warning End of warning Time from start of warning till start of barrier closing Time from the gate closing to the train arrival Warning time (Tw) Closing time (Tc)</p>	<p>Closing operation Time from the start of closing to the train arrival Time from the start of closing to the gate opening Closing time (Tc) 1 min 3 km</p>	<p>Time from start of warning till start of barrier closing Time from the gate closing to the train arrival Warning time (Tw) Closing time (Tc)</p>
Warning time (Tw)		<p>Without fixed time control TW = 33 ~ 71 sec.</p> <p>With fixed time control Tw = 33 sec</p>		<p>Without fixed time control TW = 2 ~ 4.3 min</p> <p>With fixed time control TW = 2 min</p>
Closing time (Tc)		<p>Without fixed time control Tc = 1.0 ~ 1.9 min</p> <p>With fixed time control Tc = 1.0 ~ 1.3 min</p>	<p>Tc = 4.1 ~ 5.4 min</p>	<p>Without fixed time control Tc = 2.4 ~ 4.9 min</p> <p>With fixed time control Tc = 2.4 ~ 2.6 min</p>
Road traffic suspension rate (η)		<p>Without fixed time control η = 24.0%</p> <p>With fixed time control η = 19.3%</p>	<p>η = 93.5%</p>	<p>Without fixed time control η = 70.9%</p> <p>With fixed time control η = 47.3%</p>

cf a) η is calculated based on the standard train diagram.  
 b) Gate specifications are based on JRS.22551-1D (A type).  
 c) Closing method is the total closing with one pair of barriers (Full barrier).  
 d) Calculation is made for the train traffic in 2,000.

## 5-10 Speed Indicator and Preliminary Speed Indicator

### 1. Speed Indicator

The speed indicator, installed on the block signal in the rear of the home signal, is to realize safe and efficient train operation by informing a driver of the speed limit at the turnout. One digit is considered sufficient for the indicator. Visibility distance of over 150 meters is necessary allowing a driver 4 ~ 5 seconds to correctly read the numerical figure, who is operating a L. Exp. train in the rear of a signal indicating Y, at a speed of approximately 120 km/h.

### 2. Structure of Speed Indicator

In view of the visibility of 150 meters, use of a light source by LED or optical fiber is not suitable. In this appendix, therefore, a description is provided on a speed indicator using incandescent lamps. An indication part of the indicator is as shown in Fig. 1.

The indicator is equipped with 26 V 8 W incandescent lamps, an indicator board of dark coating, and covered with a transparent polycarbonate plate.

The indicator can be controlled by compact relays or a microcomputer device.

### 3. Preliminary Speed Indicator

In case the speed limit of the turnout is 70 km/h or higher, other trains than L. Exp. and Mail/Exp. are apt to reduce the speed to a greater degree than actually required in the rear of Y signal indication, resulting in a lower operating efficiency. To avoid this, at stations where there is a speed limit higher than 70 km/h, a preliminary speed indicator is installed on the block signal in the rear of that furnished with a speed indicator, to preliminarily indicate that the speed limit is higher than 70 km/h.

The preliminary speed indicator can be of a simple structure, with a single incandescent lamp, for example, but the visibility distance should be over 150 meters so that the driver operating the train at a speed of 160 km/h can acknowledge the indication.

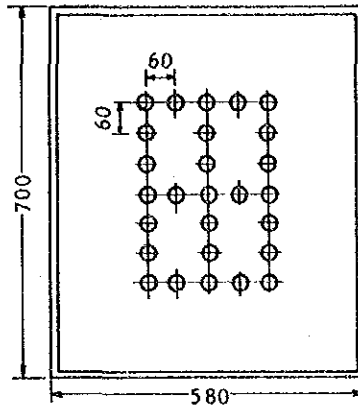


Fig. 1 Array of Lamps for Speed Indicator

5-11 Format of Report on Defective Devices of Shinkansen

Serial No.	Name of equipment room	Date of preparation		Prepared by		Tel. No.	
		Belonging	Center	Electric Maintenance	Branch	Electric Maintenance	Reporter
Name of equipment		A. Track circuit transmitter & receiver B. CTC code modulator & demodulator C. CTC transmitter & receiver D. Signal code transmitter & receiver E. Train number receiver F. Train type receiver G. Train type information accumulator		H. Number of train counter I. Train detector J. Power source devices K. Relay L. Insulation transformer M. Others			
A		Name or type of rack	Unit name	Type			
		Circuit name or track circuit name	Serial No. of device	Date of failure			
		Manufacturer	Date of manufacture	Serial No.			
		Reason for discovery	During regular operation, inspection, repair, others ( )				
		Phenomenon	Not operable, unstable, poor performance, breakdown, wear, overheating, poor insulation, self-recovery, others ( )				
		Remedy	Replacement, field repair, abandonment, others ( )				
		Remarks	(Description)				
		Faulty parts	Transistor, diode, zener diode, resistor, capacitor, coil, transformer, wiring, fuse, solder, PCB, contact point, terminal, others ( )				
		Remedy	Adjustment, replacement, repair, others ( )				
		Condition and location of faulty part (Indicate in circuit diagram.)					
		Inspection data					
		Date of acceptance	Date of preparation by company	Prepared by	Tel. No.		

Note: 1. This report is attached to faulty equipment. Part A should be filled out by an Electric Maintenance Center (Branch). Part B should be filled out by the Manufacturer.  
 2. The Electric Maintenance Center (Branch) should send a copy of this report to the related railway operating division.



#### 5-12-(1) Improvement of Signal Lamp

The original signal lamps were imported from the U.S.A. by Japan National Railways in 1924. Later, the lamps were produced in Japan, and called the A-type lamp. In the 1960's modernization of signalling facilities was progressed, resulting in the rapid increase in number of colorlight signals, and the problem of the life of the signal lamp attracted attention. Studies were done to improve the life and reliability of the A-type signal lamp. Consequently, a life of 2,000 hours was achieved at the rated voltage. However, the special filament structure featured poor productivity, and lamps with a longer life were difficult to produce at low cost. As an alternative, the standard operating voltage was dropped to 90 - 80 percent of the rated value to extend the life to 5,000 hours. In addition, a signal lamp filament burn-out detector was developed in 1966 and mounted in major signals. Since this detector could detect burn-out of a filament in two, a lamp could be replaced before the whole filaments was burned out. In 1970, mass production car headlight bulbs were modified into signal lamps to replace the A-type lamps, and called G-type lamps. The G-type lamp has a filament configuration suitable for mass production. The filament is in two parallel lines arranged at different levels, and is equipped with 3 filament terminals: the main filament terminal, sub filament terminal, and common filament terminal. The life of the G-type lamp is 9,000 hours for the main filament, and 5,000 hours for the sub filament at the rated voltage. Therefore, the probability of simultaneous burn-out of the main and sub filaments is extremely low. In this respect, the filament burn-out detector can be more effectively used, and the reliability of signals has become extremely high.

5-12-(2) Digest of Standards for Signal Lamps

1. Ratings

Table 1

Type	Rating		Standard use voltage V	Major use
	Voltage V	Power consumption W		
A-type	30	40	24 ~ 27	Multiple type colorlight signal
G-type	30	45	24 ~ 27	Multiple type colorlight signal, Route indicator, Hump shunting sign, Train approach indicator for level crossing

2. Performance

2.1 Optical Characteristics

Table 2

Type	Filament	Test voltage V	Initial characteristics			Hold rate of luminous flux (2) %	Life hours
			Power consumption W	Luminous flux Lm	Efficiency (1) Lm/W		
A-type	-	30	40 ± 4	400 ± 80	10	80 or longer	2,000 or longer
G-type	Main filament	27	20 ± 2	140 ± 25	7	80 or longer	9,000 or longer
	Sub filament	27	20 ± 2	160 ± 30	8	80 or longer	5,000 or longer

Note: (1) The figures for efficiency are rounded numbers.

(2) The hold rate of luminous flux is an expression of the ratio in percentage of the luminous flux at 1/2 of the life of the lamp being compared to the luminous flux at the initial characteristics. In the case of G-type, however, the value at 3,000 hours is taken.

## 2.2 Vibration Characteristics

The lamp should withstand the test conditions given in Table 3 over 24 hours.

Table 3

Item	Condition
Frequency Hz	10 ~ 1,000
Acceleration $m/s^2$	9.8 constant
Cycle	6 minutes per 1 cycle
Direction of vibration	Vertical as the lamp is set in the standard position for actual use
Voltage	Test voltage

## 2.3 Adhesiveness

The adhesiveness of the base should be 1 N.m or greater.

## 2.4 Insulating Resistance (only for G-type)

The resistance between the terminals and the metal section should be 10 Mohms or greater at 500 VDC.

## 2.5 Withstand Voltage (only for G-type)

The terminals and metal section should withstand 1,000 V or higher of commercial frequency for over one minute.

## 3. Structure, Shape, and Dimensions

As shown in Fig. 1 and Fig. 2.

#### 4. Test Method

Table 4

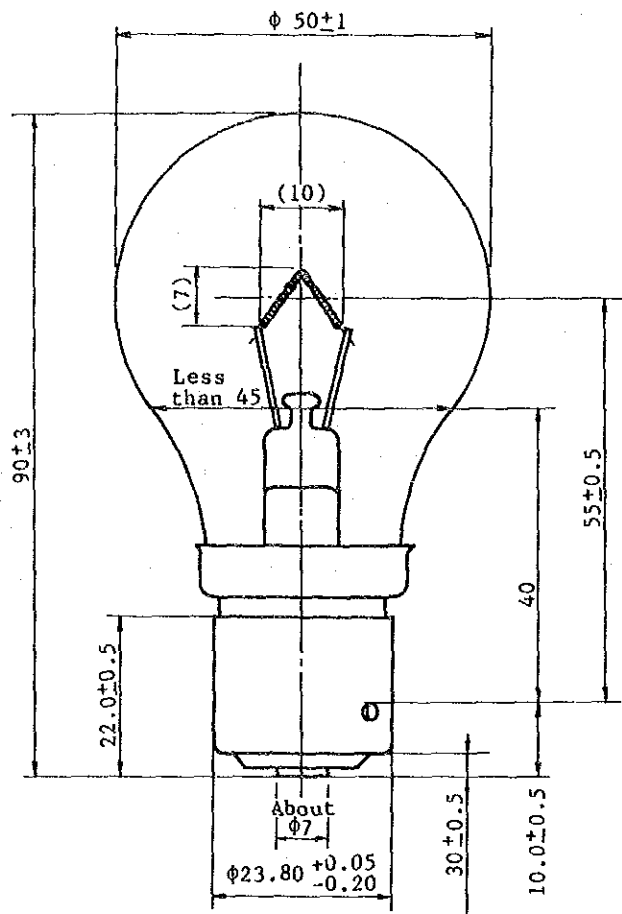
Item	Method
Initial characteristics	Apply 40 minutes aging at 120% of the test voltage till the characteristics become stable. Then, test the lamp for power consumption and total luminous flux.
Hold rate of luminous flux	As shown in Note (2) of Table 2.
Life	Set the lamp with the lamp axis horizontal. Apply no vibration. Measure the time till the filament burns out.
Vibration characteristics	Set the lamp on a vibration tester in the standard position as it is actually used in the field. Apply DC or AC (50 or 60 Hz, close to sine wave) of the specified test voltage. Perform the test under the conditions given in Table 3.
Adhesiveness	Gradually apply a torsional moment between the base and the glass bulb.
Insulation resistance	Measure with a 500 VDC megger
Withstand voltage	Use a withstand voltage tester, and apply 1,000 VAC (50 or 60 Hz).

5. Sampling Test Method

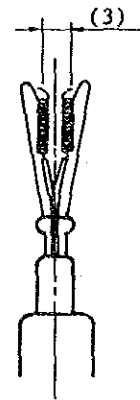
Table 5

Test item	Sample size	Number of specimen for acceptance
Dimensions	10	0
Structure, outlook, indication	20	2(1)
Initial characteristics	10	1
Life	5	0
Base adhesiveness	5	0

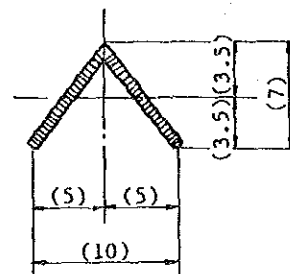
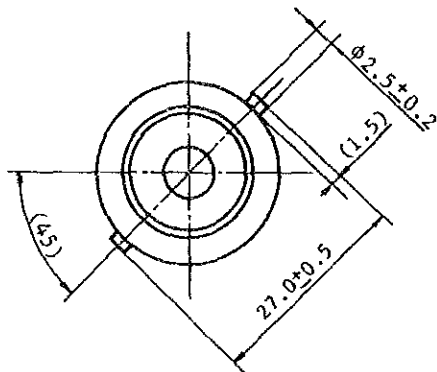
Note: (1) Two specimens shall not have defects in the same test item.



Unit: mm



Enlarged filament shape



Remark: Figures in ( ) are standard values.

Fig. 1 A-type Signal Lamp

Unit: mm

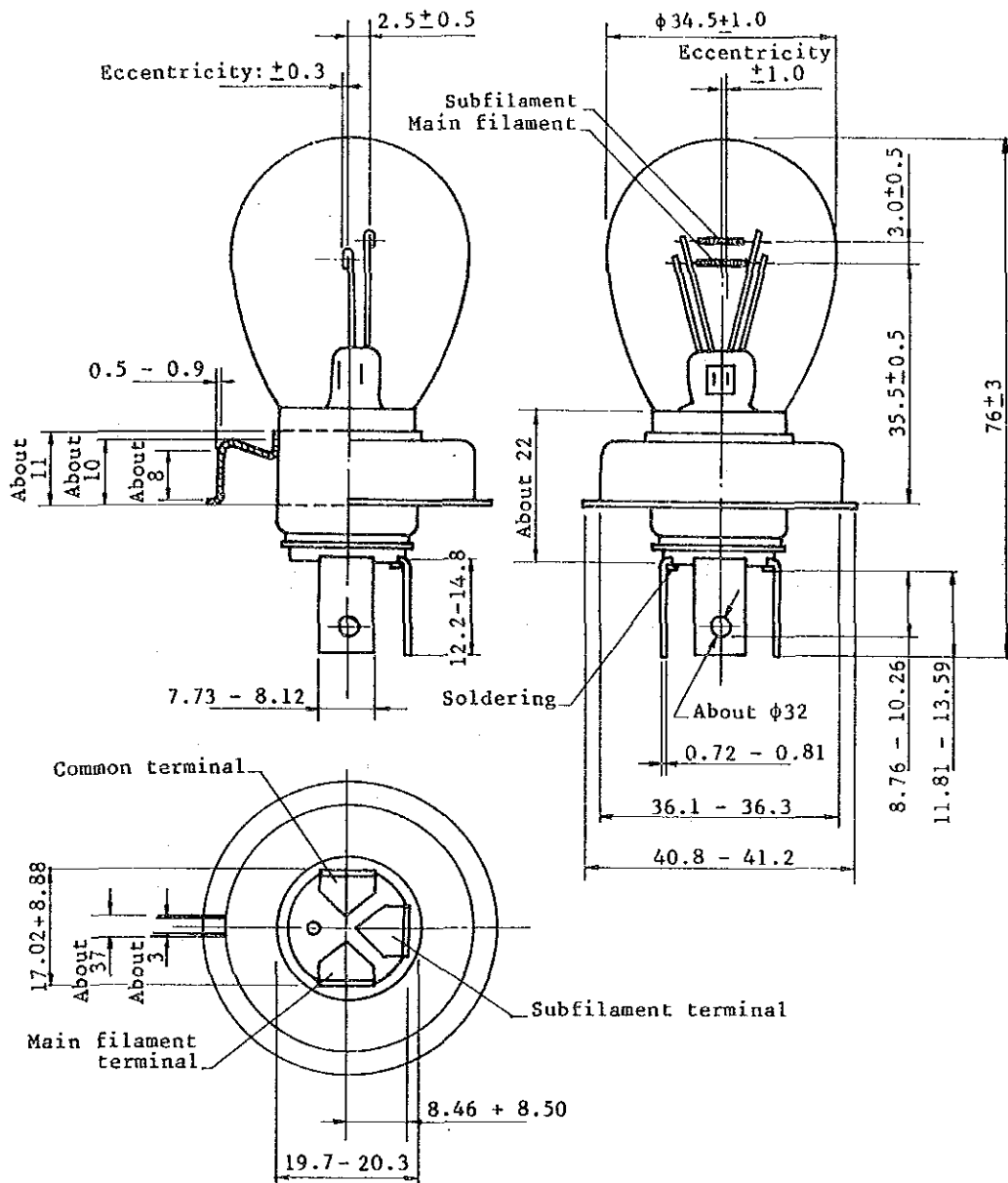


Fig. 2 G-type Signal Lamp

5-13 Outline of Automatic Inspection Car for Electrical Equipment  
(for Shinkansen)

1) Inspection cycle

Basically, an inspection will be executed every 10 days.

2) Inspection crew

Two for signalling and two for telecommunication.

3) Inspection car data processing

At present, the inspection car can run at a speed of 210 km/h and inspect the conditions of ground facilities.

The high accurate data obtained through inspection are processed by a computer. The outline of the processing is as follows.

- a) Analog data and digital data ("Warning data" exceeding permissible values) are printed out on-board. The inspection crew can command a field survey, if necessary.
- b) Collected inspection data (see Table 1) is recorded on MT, and sent to the central control center.
- c) Inspection data on MT is processed the next day, and resultant maintenance data can be provided as lists from each SMIS terminal.



Table 1 Major Inspection Data of Automatic Inspection Car

Common data	Track	Substation	Overhead equipment	Signalling	Telecommunication
<ul style="list-style-type: none"> <li>. 10 km point signal</li> <li>. 1 km point signal</li> </ul>	<ul style="list-style-type: none"> <li>. Unevenness (Transversal)</li> <li>. Twist</li> <li>. Cross level</li> <li>. Alignment</li> <li>. Gauge</li> <li>. (Transversal)</li> <li>. Vehicle shake acceleration (Vertical)</li> <li>. Vehicle shake acceleration (Transversal)</li> <li>. 20 m chord unevenness (Right and left)</li> <li>. 20 m chord alignment (Transversal)</li> <li>. Long wave unevenness (Left)</li> <li>. Axle weight (Transversal)</li> <li>. Lateral pressure (Transversal)</li> <li>. Derailment coefficient Q/P (Transversal)</li> <li>. Noise level</li> <li>. Axle box acceleration (Transversal)</li> </ul>	<ul style="list-style-type: none"> <li>. Changing over time</li> <li>. Changing over total time</li> <li>. Abnormal voltage in feeding circuit</li> <li>. Contact wire voltage</li> </ul>	<ul style="list-style-type: none"> <li>. Contact wire height</li> <li>. Contact wire deviation</li> <li>. Contact wire hard point</li> <li>. Contact wire gradient</li> <li>. Obstacle</li> <li>. Contact loss and contact loss rate</li> <li>. Contact pressure of pantograph</li> <li>. Pole location</li> <li>. Location of overhead wire crossing</li> </ul>	<ul style="list-style-type: none"> <li>. ATC track circuit current</li> <li>. Jointless track circuit current</li> <li>. ATC frequency</li> <li>. Jointless track signal frequency</li> <li>. ATC instantaneous indication change</li> <li>. Unbalance factor of traction current</li> <li>. Additional wire track circuit current</li> <li>. Wayside device for point detection</li> <li>. Track circuit current</li> <li>. Train number coil</li> <li>. Leakage current level of adjacent track circuit</li> </ul>	<ul style="list-style-type: none"> <li>. Field strength</li> <li>. Signal level</li> <li>. Noise level</li> <li>. Pilot level</li> <li>. Radio station characteristics</li> <li>. Combination test</li> <li>. Momentary failure</li> </ul>
			<ul style="list-style-type: none"> <li>. Wear of contact wire and sliding width</li> <li>. Contact wire deviation</li> <li>. Contact wire height</li> </ul>		

5-14 Electrical Equipment Maintenance Control by Shinkansen Management Information System (SMIS)

1) Purpose

The Shinkansen Management Information System (SMIS) provides timely information to the related organizations both in administrative and field sector, greatly contributing to achieve highly efficient maintenance of rolling stock and ground facilities.

2) Fundamental policy of the system

- To employ a general purpose data base, hierarchical structured programming, high-level language, etc. to realize easy design, maintenance and high data security.
- To adopt on-line connection with the automatic centralized monitor system to improve information collection/distribution efficiency.
- To use intelligent terminals to improve operability and enable local data processing.

### 3) System structure

The overall structure of the SMIS is shown in Fig. 1.

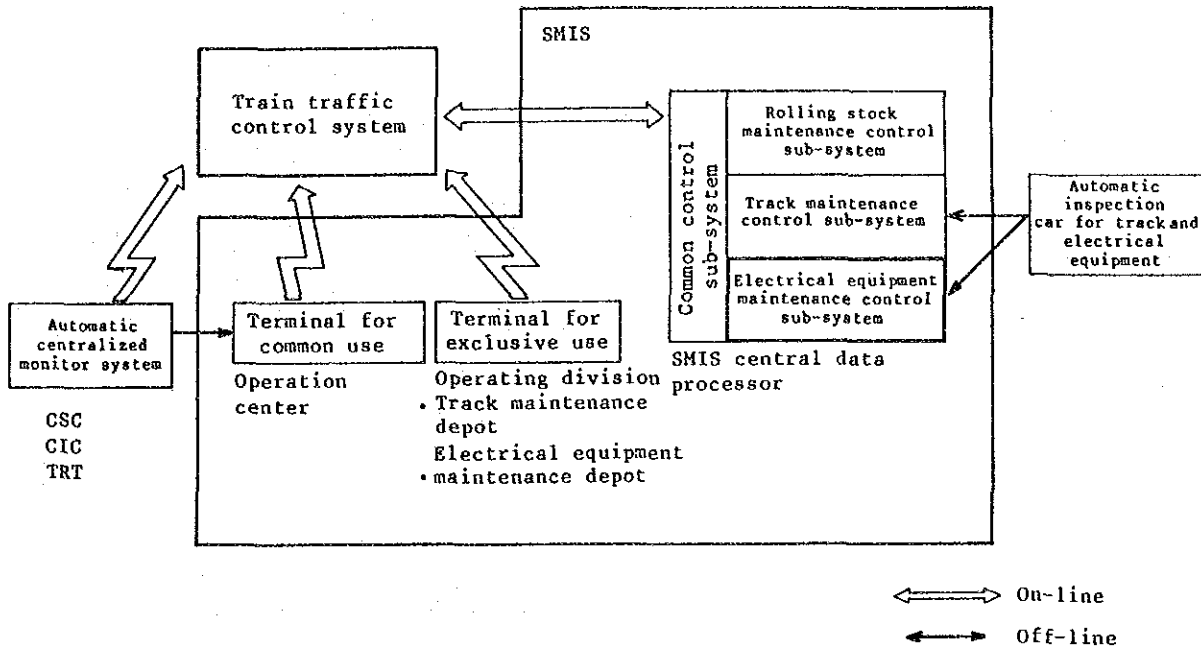


Fig. 1 Overall Structure

### 4) Electrical equipment maintenance control sub-system

The electrical equipment maintenance control sub-system composes one sub-system (for signalling, telecommunication, substation and overhead equipment) of the SMIS. This sub-system analyzes various data supplied by the automatic inspection car and provides various useful data such as statistical and time-sequencial failures data. The construction diagram and the outline of the function of the sub-system are shown in Fig. 2 and Table 1, respectively.

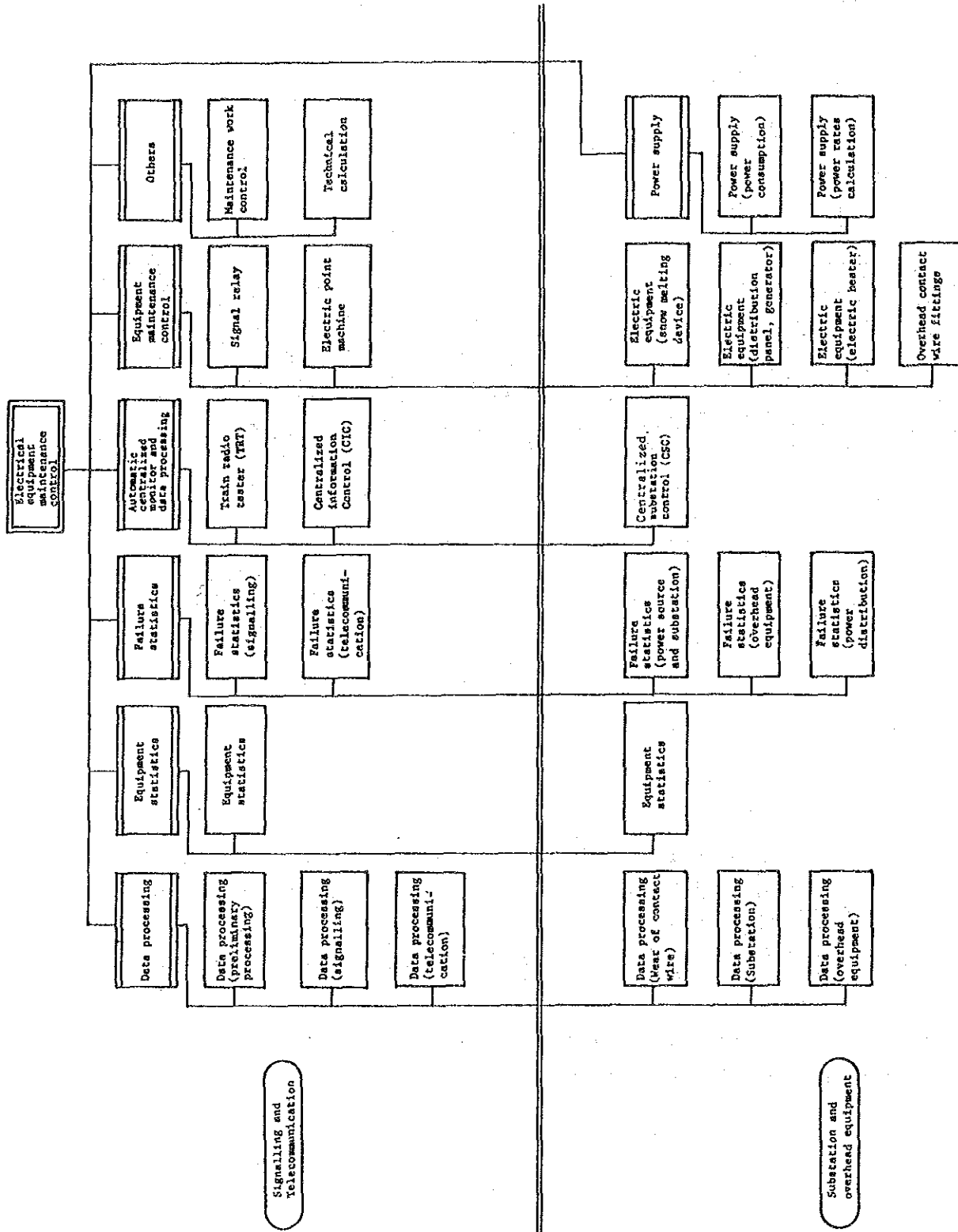


Fig. 2 Structure of Electrical Equipment Maintenance Control System

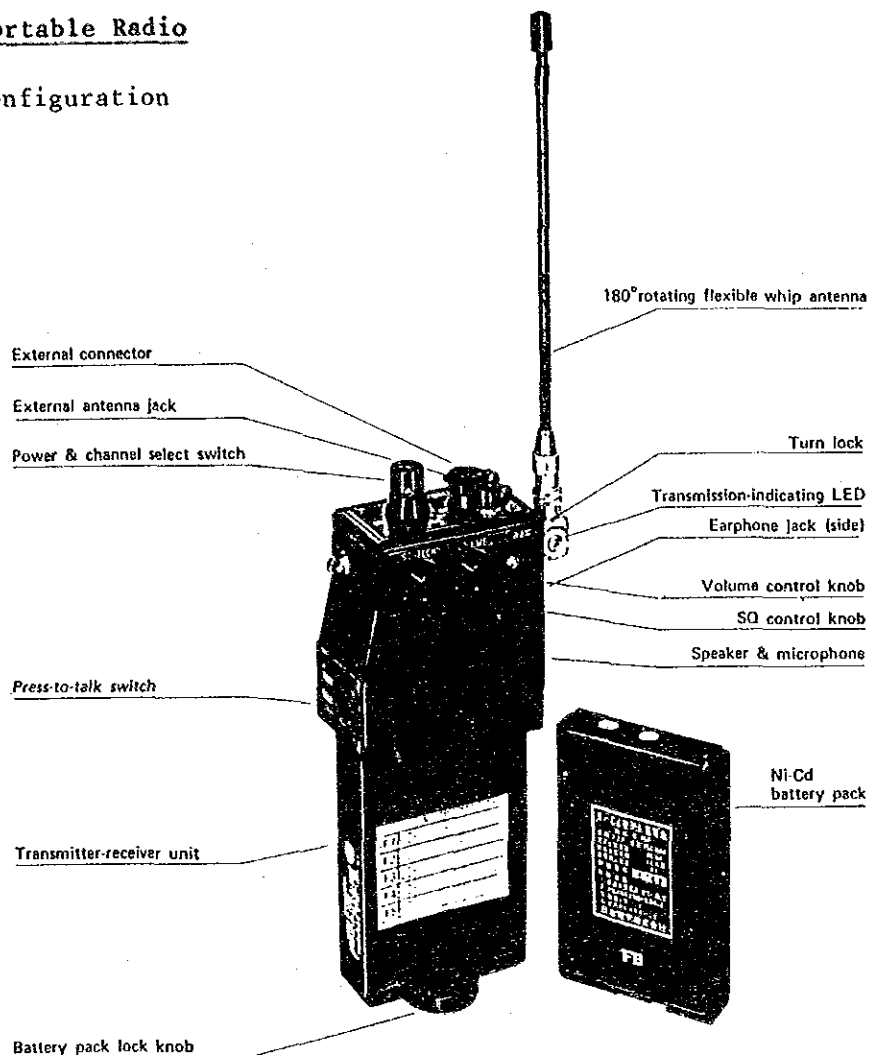
Table 1 Outline of Functions of Electrical Equipment Maintenance Control System

Classification	Detailed classification	Outline
Automatic inspection car data processing	Preliminary processing	Point information (location of 10 km wayside device, tunnel, bridge, and other information needed for each processing) necessary for on-board processing is recorded on a magnetic tape.
	Contact wire wear control	Contact wire wear data obtained by the inspection car is processed; time sequential control of wear data and various maintenance control lists are provided.
	Substations	Changing over time, abnormal voltage in feeding circuit obtained by the inspection car are processed, and various maintenance control lists are provided.
	Overhead equipment	Contact loss rate, contact wire height, and contact wire deviation are processed, and various maintenance control lists are provided. Simultaneously, the contact wire evaluation index for overall judgement is provided.
	Signalling	ATC track circuit current data obtained by the inspection car is processed, and various maintenance control lists are provided.
	Telecommunication	Data related train radio obtained by the inspection car is processed, and various maintenance control list are provided.
Statistical processing	Equipment statistics	The number of equipment is maintained for each increase or decrease to be used for failure statistics processing.
	Failure statistics	Processing of failure data input from a terminal on occurrence of failure is processed, and various maintenance control lists are provided.
Equipment control	Centralized Substation Control (CSC)	Data of operating condition of each substation equipment (number of operation of AC circuit breaker and switch-over breaker, inspection data of remote control system, protection relay, etc., and load current) obtained through CSC are processed, and various maintenance control lists are provided.
	Train radio tester (TRT)	Mobile station failure data and inspection data by train radio tester are processed for each train make-up, and various maintenance control lists are provided.
	Centralized information control (CIC)	Data obtained by Centralized Information Control are processed, and various maintenance control lists are provided.
	Electric equipment control	Replacement data of the electric snow melting device is maintained from terminals, and various maintenance control lists are provided.
	Contact wire fittings control	As to contact wire fittings of a relatively high replacement rate, aging is grasped from replacement data maintained from terminals, and various maintenance materials are provided.
	Signal relay control	Replacement data of signal relays used for interlocking devices are maintained from terminals, individual operation number is obtained, and various maintenance control lists for replacement plan are provided.
	Electric switching machine control	Replacement data of electric switching machine maintained from terminals are processed to obtain individual operation number, and various maintenance control lists for overhaul inspection plan are provided.
Electric power . Power supply		Power index data of substation obtained from Centralized Substation Control is processed, and various maintenance control lists for power consumption are prepared. Electric power rate is also calculated from power supply result from terminals.

Classification	Detailed classification	Outline
Others	Technical calculation	Contact wire structure calculation is processed on various input conditions from terminals.
	Application for maintenance work	For working without power supply, work application from terminals are transmitted to CSC. Replies to such applications are transmitted to terminals.

## 5-15 Portable Radio

### Configuration



Type ATR-150P1 Portable Radio

### Performance Specifications

General	
Frequency range	145 to 165 MHz
Number of channels	1 to 5
Power source	DC 7.5V $\pm$ 10%, 450 mA Ni-Cd battery pack
Battery life per charge	8 hours
Communication mode	2-way press-to-talk (simplex)
Temperature	-10 to +50°C
Size	165 mm (H) x 60 mm (W) x 38 mm (D)
Weight	520 g including battery pack

Table 1 Classification

Control method	Data transmission	Speed check		Brake	Characteristics
Inter-mittent	Contactator	Not equipped		Emergency	1. Less ability to follow signal indication change 2. Easy to extend adjoining lines 3. Low cost
	Magnet	On-ground	Spot	Emergency	
	Spot coil Inductor Transponder	On-board	Spot Continuous	Service and emergency	
Continuous	Track circuit Wires btw. rails	On-board	Continuous	Service and emergency	Contrary to the above

Table 2 Application

Control method	Data transmission	Speed check		Brake	Name of AWS or railways
Inter-mittent	Contactator	Not equipped		Emergency	(France) Crocodile
	Magnet	Not equipped		Emergency	(England) AWS
	Spot coil	Not equipped		Emergency	(Japan) ATS-S
		On-ground	Spot	Emergency	(Japan) Nagoya Railways
	Inductor	On-board	Continuous	Emergency	(Germany) Indusi-BWU
Transponder	On-board	Continuous	Service & emergency	(Japan) ATS-H (Egypt)	
Continuous	Track circuit	On-board	Continuous	Service	(Japan) Seibu Railways
	Wires btw. rails	On-board	Continuous	Service	(Germany) LZB



## 5-17 Remote Monitoring System

Table 1 shows examples of the equipment to be subjected to collective surveillance.

Fig. 1 shows an outline of the remote monitoring system. A sensor is attached to each item to be monitored. All the sensors on the facilities in the station yard are directly connected to the failure display board. Information of facilities located between stations is transmitted to the station by means of the central monitoring device and input to the failure display board. The failure display board prepares information to be transmitted to the center and inputs it to the CTC system. The failure information transmitted by the CTC system is displayed on the monitor board of the control center.

There are various types of central monitoring devices such as analog systems, frequency division types, time division systems, etc. Fig. 2 shows the principle of an analog type central monitoring device which can use a cable of even fairly poor transmission quality. When there is no failure of the facilities in the section to be monitored, local power source B is supplied to the station facility and CR relay is energized to indicate the correct condition. If some facility should fail, the sensor relay of the facility drops to cut off power source B, and connects resistors Rx and Ry to the circuit. The station facility, by means of power source A and the Wheatstone bridge, measures the value of Rx, and then, by means of the pole change relay, measures the value of Ry. Since there are 10 different values for each of Rx and Ry, a total of 100 conditions can be detected in combination.

Table 1 Facilities to be Monitored by the Remote Monitoring System

Name of facility	Item to be monitored	Serious failure	Slight failure
Signaling facilities (Station yard)			
Signals	Bulb filament burn-out		○
Points	Deviations of lock bar		○
	Faulty switching	○	
Interlocking device	Failure of control system	○	
	Failure of monitor unit		○
Signal power source	Failure of one system		○
	Total breakdown	○	
Cable	Poor insulation		○
(Facilities located between stations)			
Signals	Bulb filament burn-out		○
Level crossing facili- ties	Failure of control system	○	
	Failure of barrier motor		○
	Voltage drop		○
Telecommunication facilities			
Exchange	Failure	○	○
		Failure of 2 signal generators	Failure of 1 signal generator
Carrier system	Failure	○	○
		Failure of basic rack	Pilot level drop
Wireless transmitter and receiver	Failure	○	○
		Failure of power amplifier	Pilot level drop
Wireless terminal station facilities	Failure	○	○
		Failure of line amplifier	Pilot level drop
Power source facility	Failure of 1 system		
	Total breakdown	○	○
Air conditioning system	Failure	○	○
		Radio station	Exchange station
Electric clock	Failure		○
Communication cable	Poor insulation		○

Note: Monitoring for telecommunication facilities shall be carried out at the no maintenance staff stations.

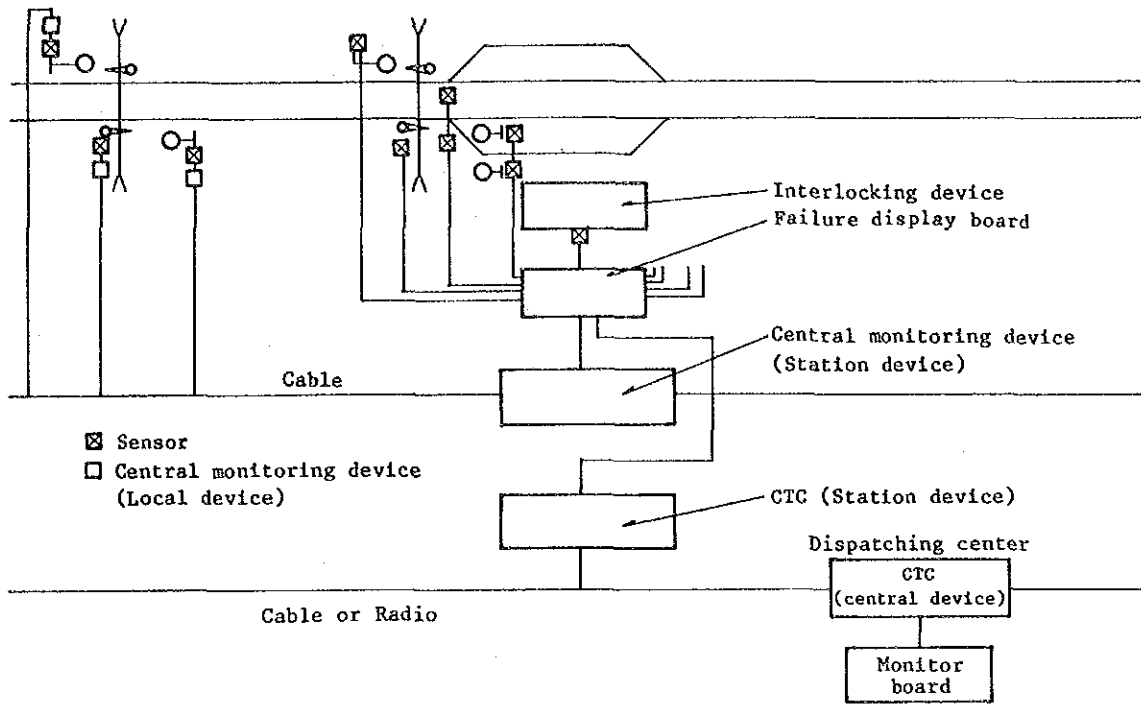


Fig. 1 Outline of Remote Monitoring System

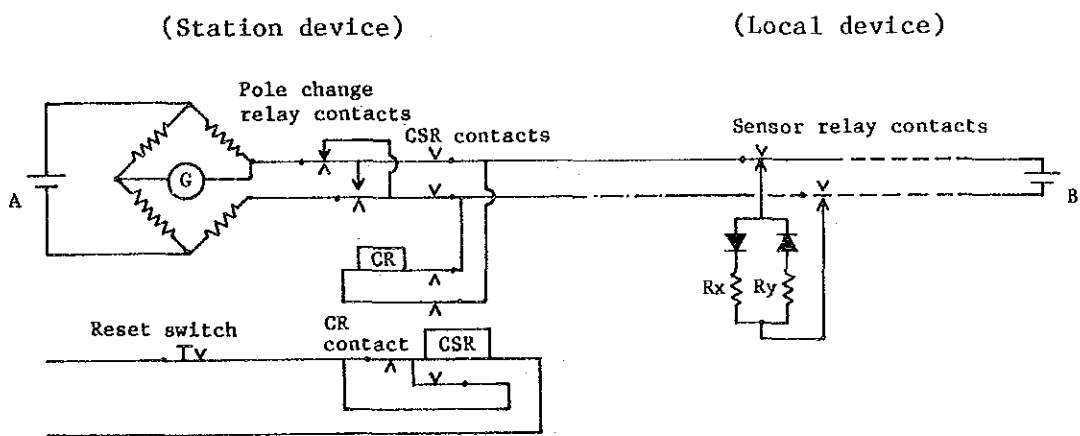


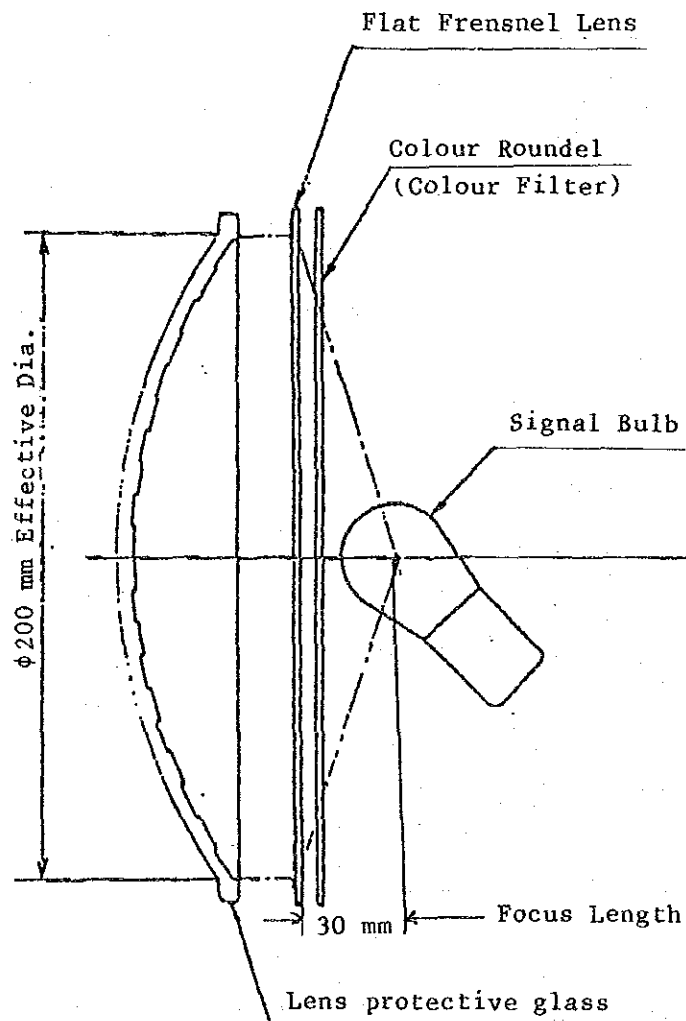
Fig. 2 Principle of Central Monitoring Device

5-18 Example of Signal Lens of Long Visibility

1. Major Particulars

Lens	Lens effective diameter	200 mm
	Composition	Flat type frensnel lens (with colour filter)
	Material	Polycarbonate
Signal bulb	Rate	30 V 15W/15W
	Luminousness	27 V 120 lm (only main filament)
Range visibility	Rated voltage x 90(%) 27 V	More than 1.5 Km
	Rated voltage x 73(%) 21.9V	More than 1.0 Km

2. Configuration



5-19 Relation between Turnout Number and Alignment of Locking Devices in JR

	Turnout number	Number of drive	Alignment	Type of machine	Characteristic	
					Max. switching force	Withstanding thrust force
Conventional Line	<16	1	Fig-1	NS-A	300 kg	Max. 2000 kg
	≥16	2	Fig-2	G-CL	300 kg	Max. 2000 kg
New Corridor	≥16	2	Fig-3	TS	800 kg	Max. 2000 kg

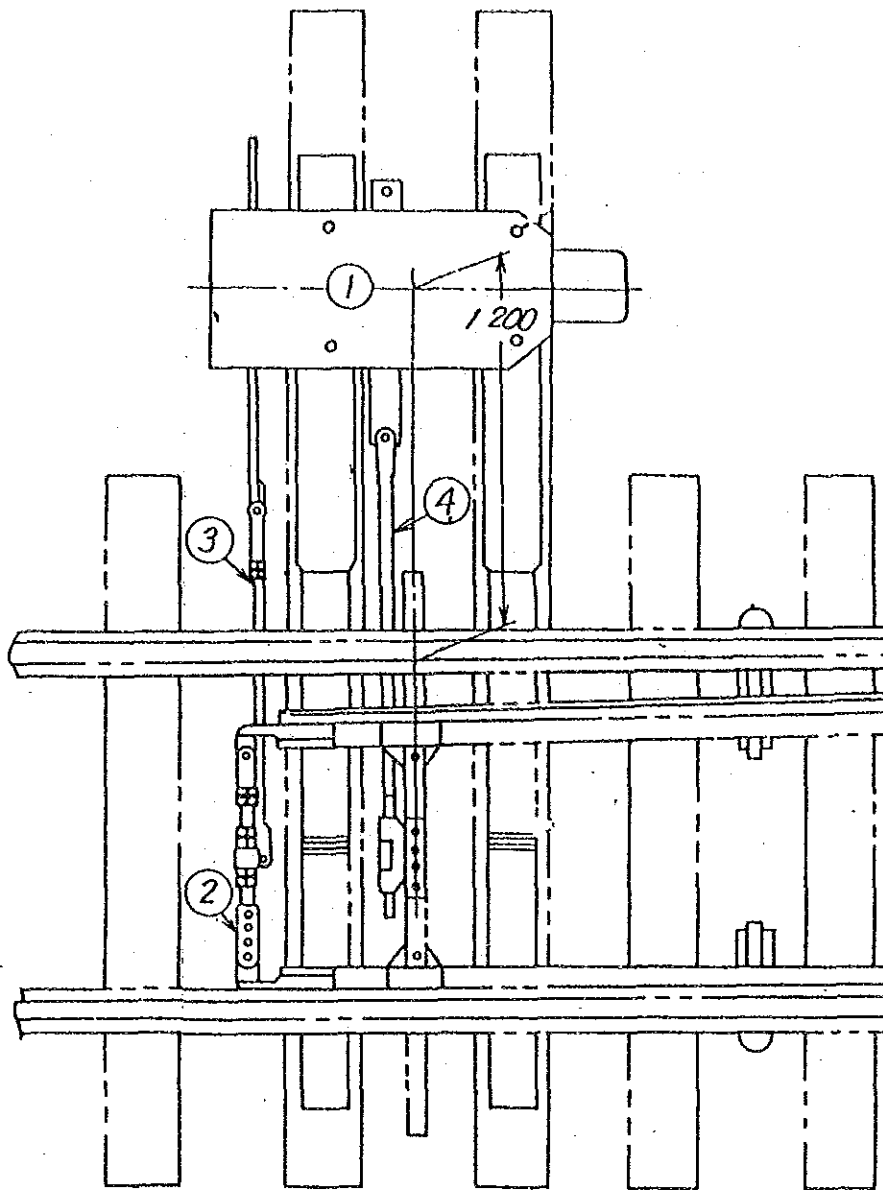


Fig. 1 Installation of Locking Device for NS-A Type Point Machine

No.	Description
①	Point machine
②	Lock stretcher bar
③	Lock rod
④	Drive rod

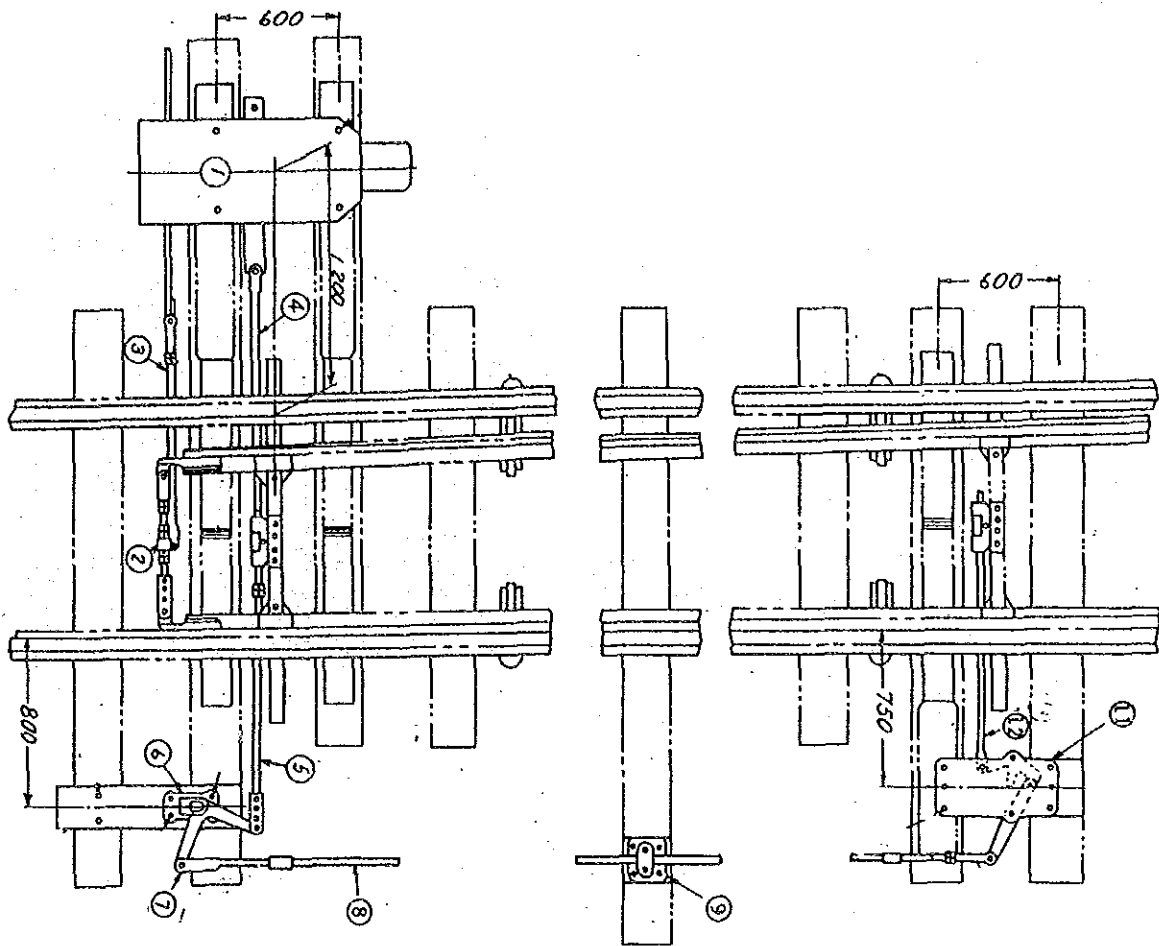


Fig. 2 Installation of Locking Device for G-CL Type Point Machine

No.	Description	No.	Description
①	Point machine	⑦	Jaw
②	Lock stretcher bar	⑧	Iron signal pipe
③	Lock rod	⑨	Rod carrier
④	Drive rod	⑩	Jaw
⑤	Insulation link	⑪	Escapement crank
⑥	Crank	⑫	Drive rod

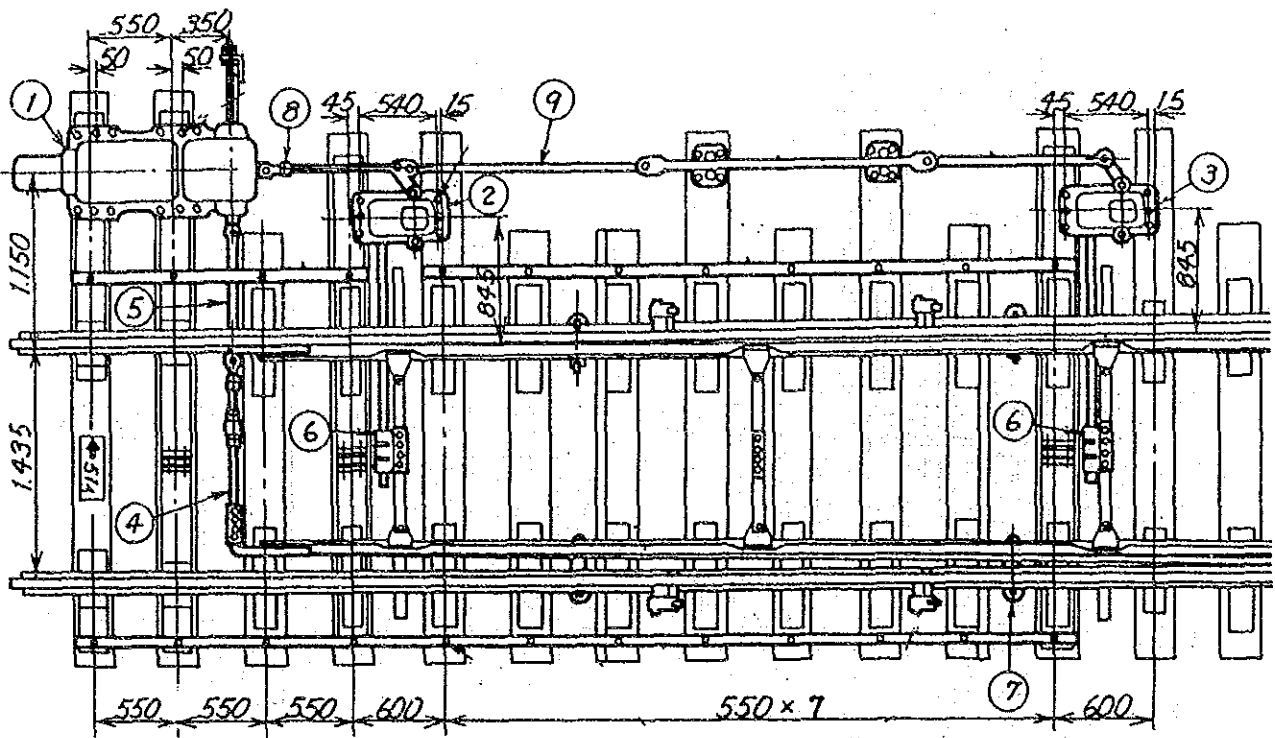


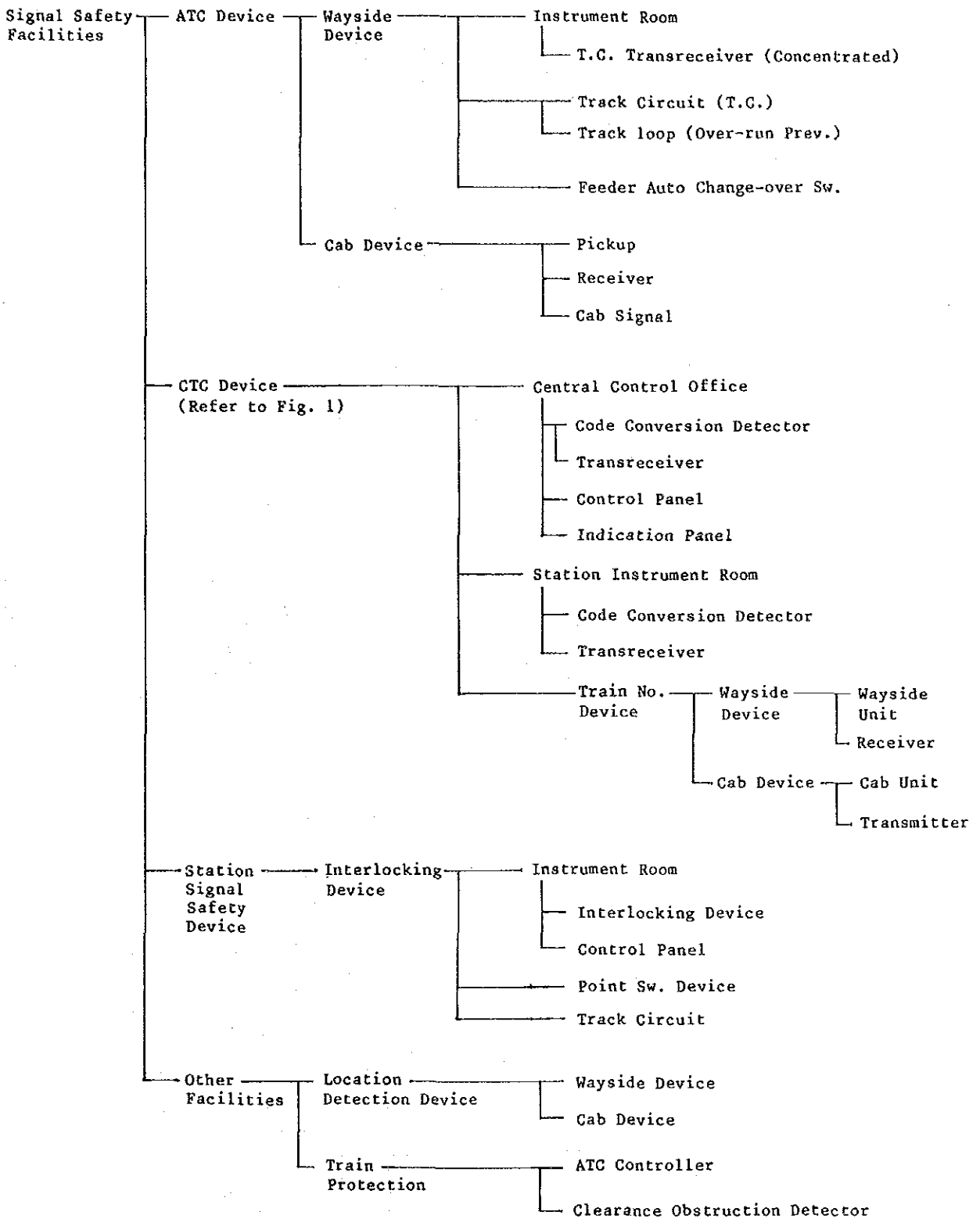
Fig. 3 Installation of Locking Device for TS Type Point Machine

No.	Description	No.	Description
①	Point machine	⑥	Drive lug
②	Escapement crank	⑦	Point wear preventor
③	Escapement crank	⑧	Link
④	Lock stretcher bar	⑨	Link
⑤	Rock rod		



5-20 Signalling System of the New Corridor

(1) Signalling



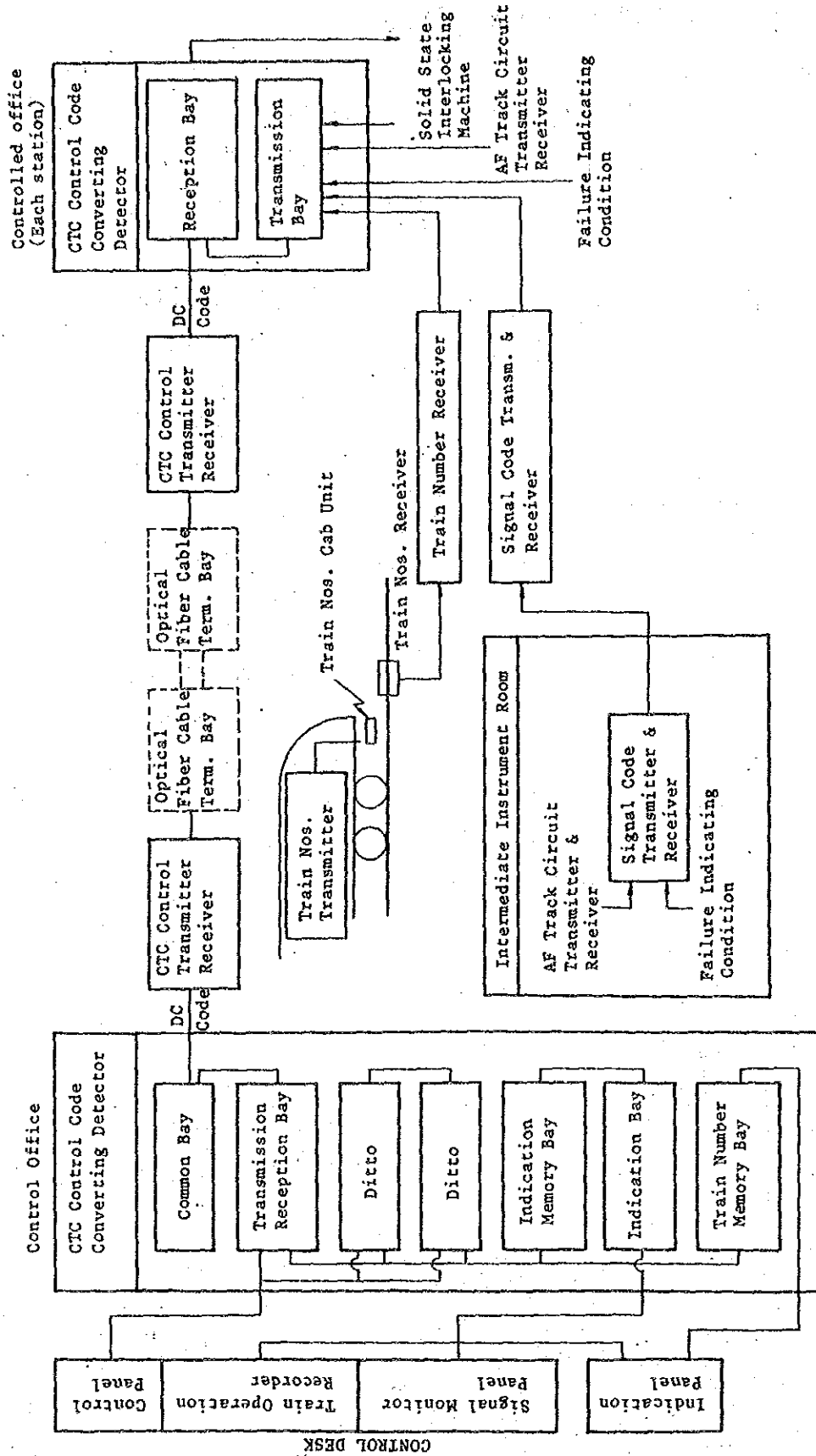


Fig. 1 Circuit Constitution Diagram of CTC Equipment

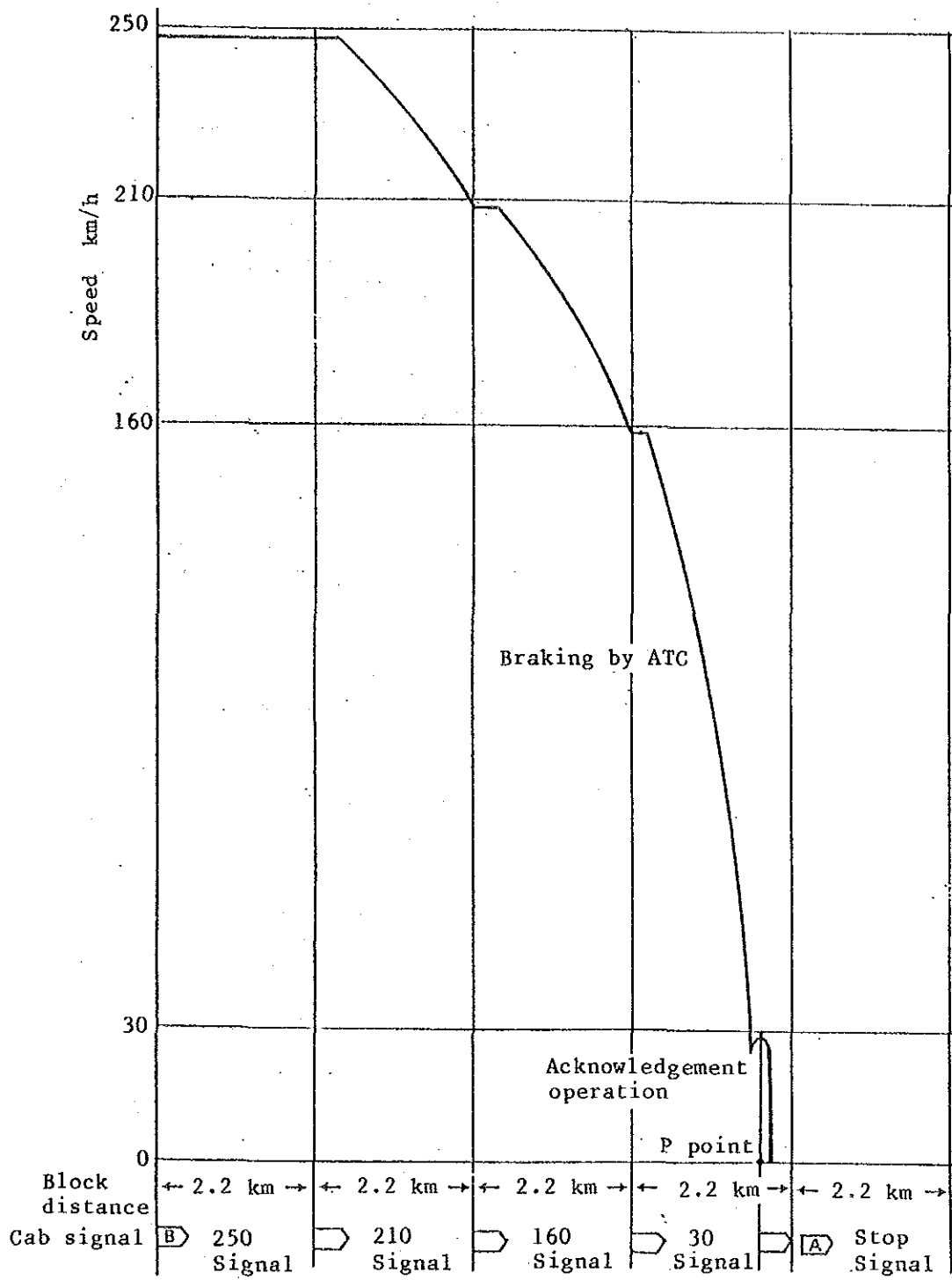
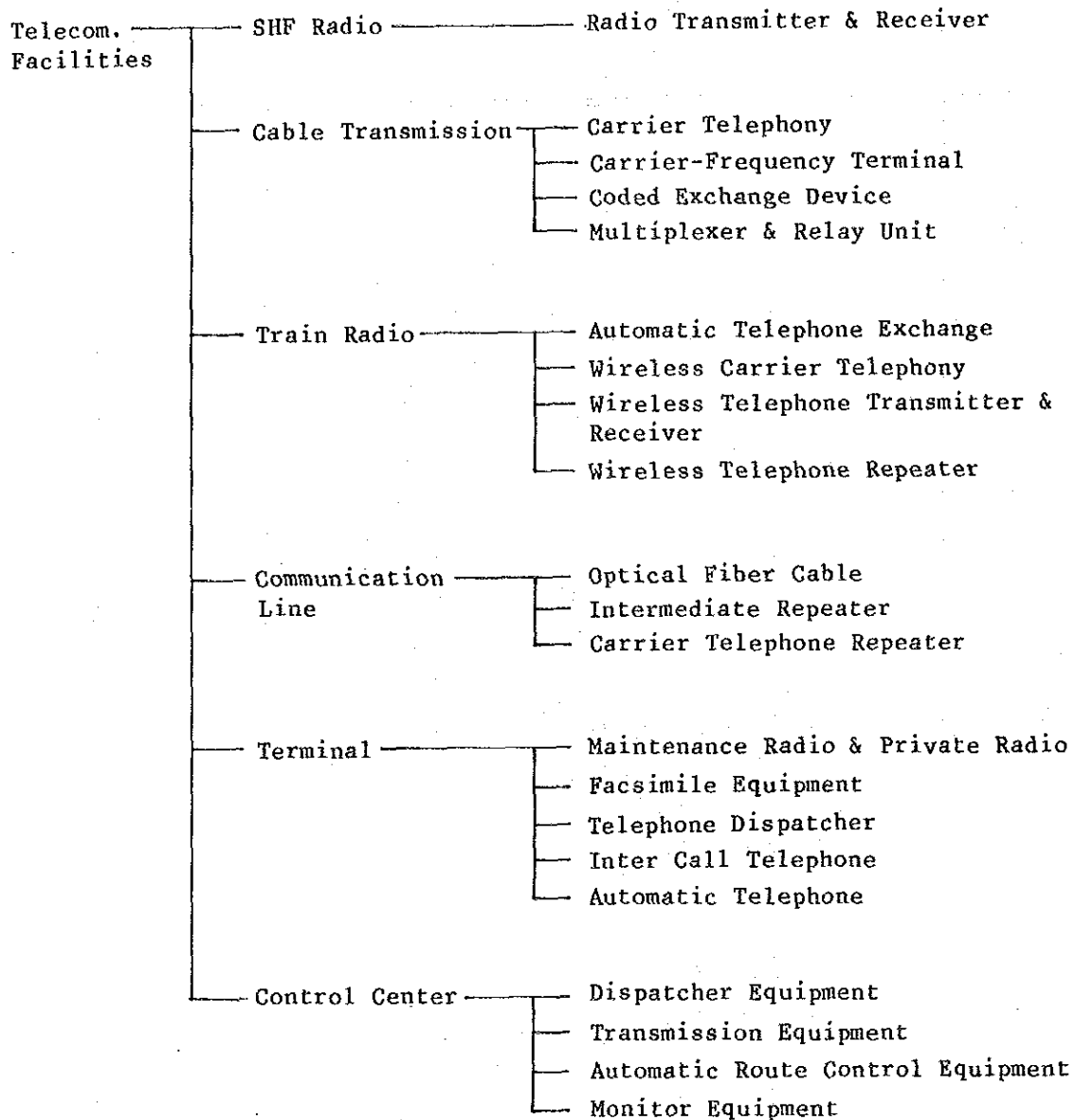


Fig. 2 Operating Curve by ATC (Between Stations)

5-21 Telecommunication System of the New Corridor



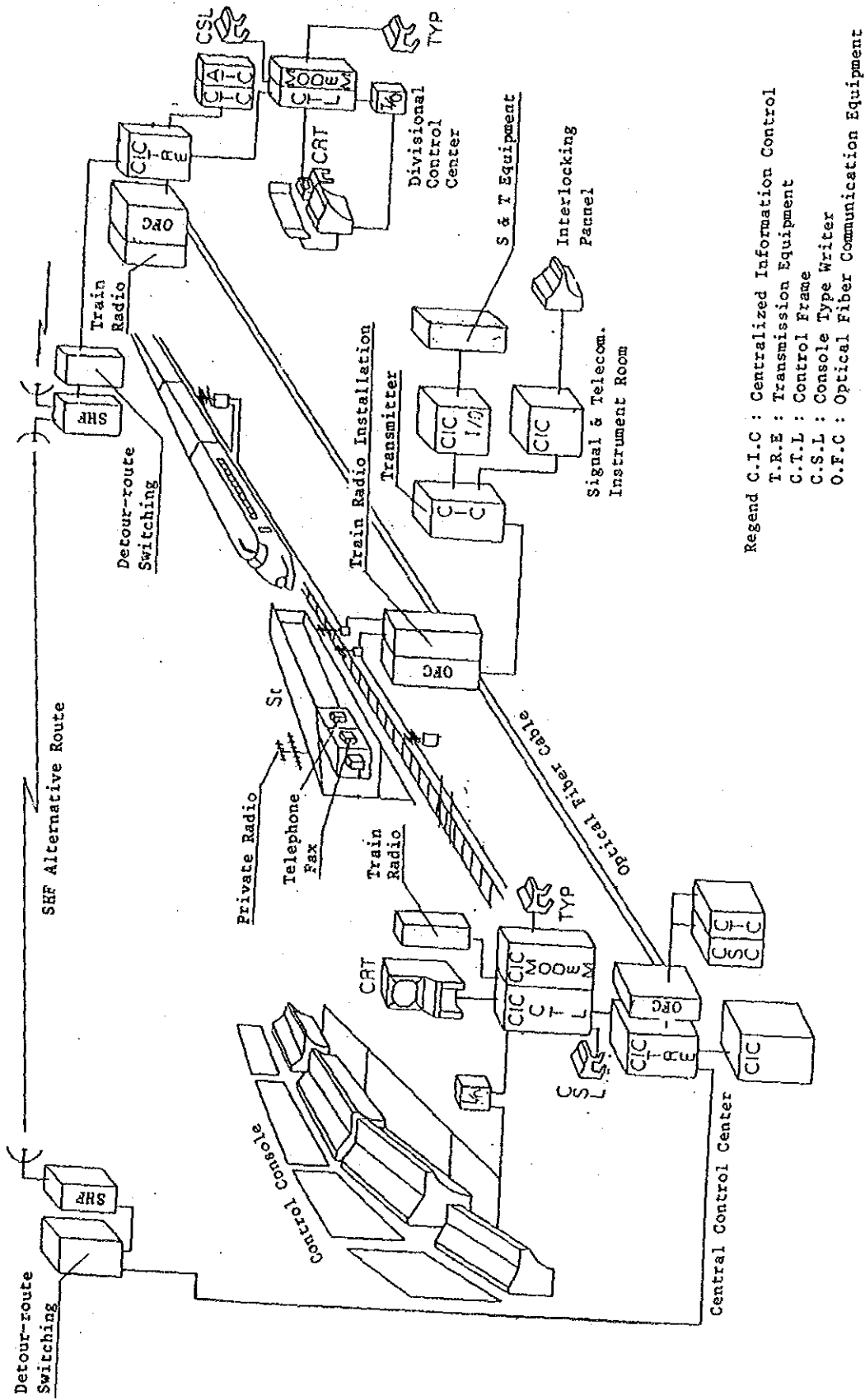


Fig. 1 Configuration of Telecommunication System

5-22 Typical Instruments for Repair and Maintenance of Signalling  
Electronic Devices

Equipment	Instrument	Cause
Solid-state interlocking	Logic analyzer	. Software errors
	Tester	. External errors (Field devices, operation handling)
	Synchroscope	
Electronic level crossing controller	Voltmeter	. Hardware failure (Processor, modules, sheets) . etc.
Centralized traffic control	Level meter	. Deterioration of modules and sheets
	wave analyzer	
	X-Y recorder	
	frequency-counter	. External noise
Automatic train control	Synchroscope	. Logical error
	signal generator	. etc.
A.F. track circuit (Transmitter & Receiver)		
Train number transmitter & Receiver	Delayed wave analyzer	. Hard and logical error

## 6-1 Countermeasures for Frequent Trippings of Feeder Circuit Breakers at Substation

The problem IR is now facing in supplying electric traction power is the fact that feeder circuit breakers at the substation make extremely frequent trippings -- the problem that should be solved immediately.

The numbers of breaker trippings are not the same, varying with the feeding zones and seasons. Some breakers trip more than 100 times a month, and others only 4 or 5 times.

For reference, the trippings of circuit breakers installed at JR's substations average 4 or 5 times a year, with the exceptional cases such as typhoons and other natural disasters.

### 1. Problems

These frequent trippings give rise to frequent suspensions of power supply to trains. Attention must be given to the following actual conditions:

- (1) Under the current system, the feeder circuit breaker, connected to the secondary side of substation transformer, is commonly used for both up and down lines; therefore, when a trouble happens to one line, the power for the another sound line must be suspended, making a power suspension chance double.
- (2) After circuit breaker tripping, the interrupters of SS/FP, SSP and SP will be manually closed one by one controlling from the center. Thus, this series of the closing work requires some minutes.

These trippings will bring about the following problems:

- (1) Interrupt the train operations.
- (2) Shorten a service life of a circuit breaker, necessitating more maintenance.

Unless these problems are solved, therefore, the trippings will cause a grave adverse effect in attaining the increase in track capacity and the 160 km/h high-speed train operation.

## 2. Causes

The causes of breaker trippings include:

- (1) Birds. Some records say the 70 ~ 80% of the total breaker trippings were due to birds.
- (2) Flashover of the air gap installed on the roof of electric locomotive (connected in parallel to the primary side of transformer)
- (3) Flashover of the OHE insulator, frequently happen during the foggy season of December and January, and in the heavily air polluted area.
- (4) False working of distance relay due to load current

## 3. Countermeasures

It will take long time and great effort to settle out all these matters. However, there are measures that can be taken immediately such as:

- (1) Measures to remove the causes of circuit breaker trippings.

### 1) In the bird-inhabited area:

- A large number of bird nests are found. So it is recommendable to take measures to prevent nesting at places which are liable to cause ground fault. (See Fig. 1.)

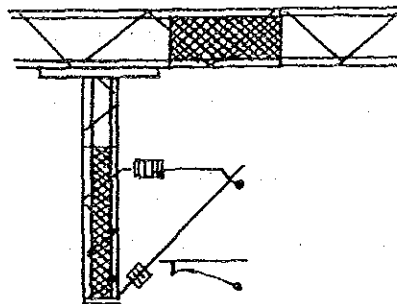


Fig. 1 Places Effective in Preventing against Bird Nests

For example, it would be effective to insert a net of insulation material, such as plastics, inside the beam.



- Strengthen the insulation, such as fixing an insulating plate below the bottom of beam or covering an insulating tube to the catenary wire, when the clearance between the bottom of beam and the catenary wire is small, especially at overbridge.
- 2) Change the air gap between horns provided on the roof of electric locomotive; adopt a gapless arrester for electric locomotive.
- 3) Review the setting of distance relays in use and improve its characteristics.

At present the MHO relay is used as a distance relay, and its selecting capability of load and fault currents is limited. Therefore, it is desired that a distant relay with parallelogram characteristics be developed as early as possible. (See Appendix 6-7.)

- 4) Survey the actual status of insulator flashovers by areas, seasons and causes, and clean or strengthen insulators in specific areas if required.

(2) Measures to shorten the power stopping time after tripping

- 1) Adopt the high-speed, automatic reclosing method for circuit breakers. This method recloses a circuit breaker automatically 0.5 second right after it trips. When reclosed and retripped, the circuit breaker will be locked for further action.

From JR's experiences, it can be expected that the adoption of this method makes it possible to reclose about 80% of the total breakers that have tripped. In other words, in most cases it shortens the power stopping time to mere 0.5 second. According to "Single Pole SF-6 Circuit Breakers 25 kV AC: Specification No ETI/PSI/66/Rev. 1 (9/84)," the rated operating sequence of the circuit breaker is specified to be "0-0.3 sec-CO-3 min-CO." Therefore, this 0.5 second time is applicable.

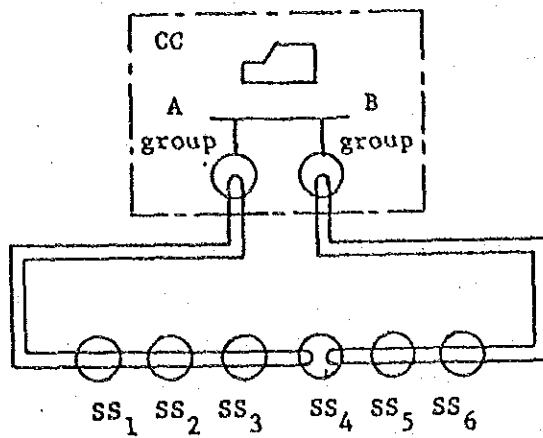
- 2) Make it automatic to operate the interrupters of SS/FP, SSP and SP sequentially. At present, interrupters are manually operated from the control center. The automation will reduce the interrupter operation time to the matter of seconds. This method is especially effective in the Delhi area where the feeding system is complicated with many interrupters installed.
- (3) Measures to shorten the time for detecting a fault point. As described above, the transient faults -- about 80% of the total circuit breaker trippings -- will be solved by adopting the high-speed, automatic reclosing method. However, it is necessary to detect the remaining lasting faults of 20%, by making a time-consuming patrol. Introduce fault locators at each substation and then any fault point will be located with 0.5-lkm accuracy, making it possible to drastically reduce the detecting time. Two methods are detailed as follows:
  - 1) In the existing feeding system where the up and down lines are connected in parallel at SP and SSP, the accuracy of a fault location becomes deteriorated. Therefore, after re-tripping in reclosing, open all interrupters of SP and SSP, close the interrupters of SS for the up and down lines separately, and then a fault point can be located with accuracy.
  - 2) Open all the parallel interrupters for up and down lines before the CB recloses in 0.5 second by providing low voltage relays to each SP and SSP. Then the fault point can be located with high accuracy at a time of re-tripping with feeding current comparators which are provided to each feeder line.

## 6-2 Substation Supervisory Remote Control System

The JR's latest substation supervisory remote control system using a microprocessor is outlined below:

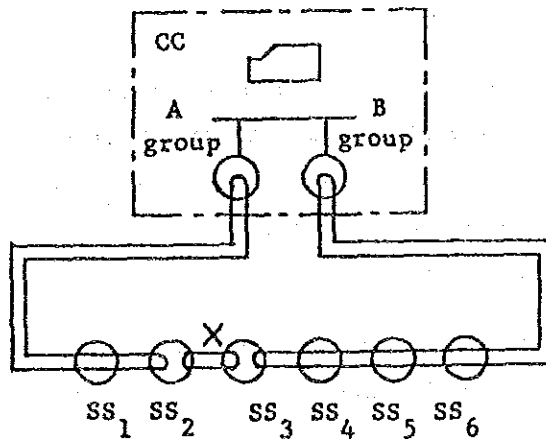
### 1. Features

- (1) A communication circuit is constructed in the form of a loop to heighten the reliability of transmission line connected to CC, SSs, SPs and SSPs. When a trouble arises in the line, the part in trouble will be automatically cut off, and at the same time the circuit will be automatically reformed; therefore, only one trouble will not hamper the operation of trains. Fig. 1 illustrates the configuration of communication circuit and a principle diagram showing how to deal with a circuit trouble when it happens.
- (2) The supervisory remote control system, using a microprocessor and LSI (Large Scale Intergrated Circuit), can control many items and collect a large volume of information;
  - 1) In addition to the function of controlling devices separately, it is capable of one-touch control of feeding circuit structure, and of overall control when suspending a feeding over a certain section, making the control simpler with smaller handling errors.
  - 2) It can compile information on many items of the controlled point so that dispatchers can make a right judgment.



a. Composition of Circuits When Normal

SS<sub>1</sub>, SS<sub>2</sub> and SS<sub>3</sub>      controlled by A group  
 SS<sub>4</sub>, SS<sub>5</sub> and SS<sub>6</sub>      controlled by B group



b. Recomposition of Circuits When in Trouble  
 on the X Marked Section

SS<sub>1</sub> and SS<sub>2</sub>                  controlled by A group  
 SS<sub>3</sub>, SS<sub>4</sub>, SS<sub>5</sub> and SS<sub>6</sub>      controlled by B group

Fig. 1 Composition and Recomposition of Circuits  
 When a Trouble Arises

- 3) Capable of printing out the time sequential record of controlling every device and their working conditions, also of the power consumption at each substation in the form of a daily report, making the equipment management easier.
  - 4) Capable of collecting various data necessary for maintenance of devices, such as the values of feeding voltage, load current, fault current, operating frequency of devices, and controlling frequency, and the number of temporary stagnations of the remote control system, making their maintenance more easy and efficient.
  - 5) Selfdiagnosis function, that is capability of detecting parts in trouble by itself, makes the system highly reliable.
- (3) Being static, the system is small in size. Having almost no movable parts, the system is easy to maintain and has a longer service life.

## 2. Block Diagram of System Composition

Fig. 2 shows the block diagram of the supervisory/remote control system. Main parts of the system are:

### (1) Control desk

By using CRT on control desk, it controls the power supply system and all the other devices.

1. Control desk
2. Remote control logic device
3. Common logic panel
4. Individual logic panel
5. Logic panel
6. Portable testing device
7. Automatic fault recorder
8. Printer
9. Maintenance data processing equipment
10. Switch-Board

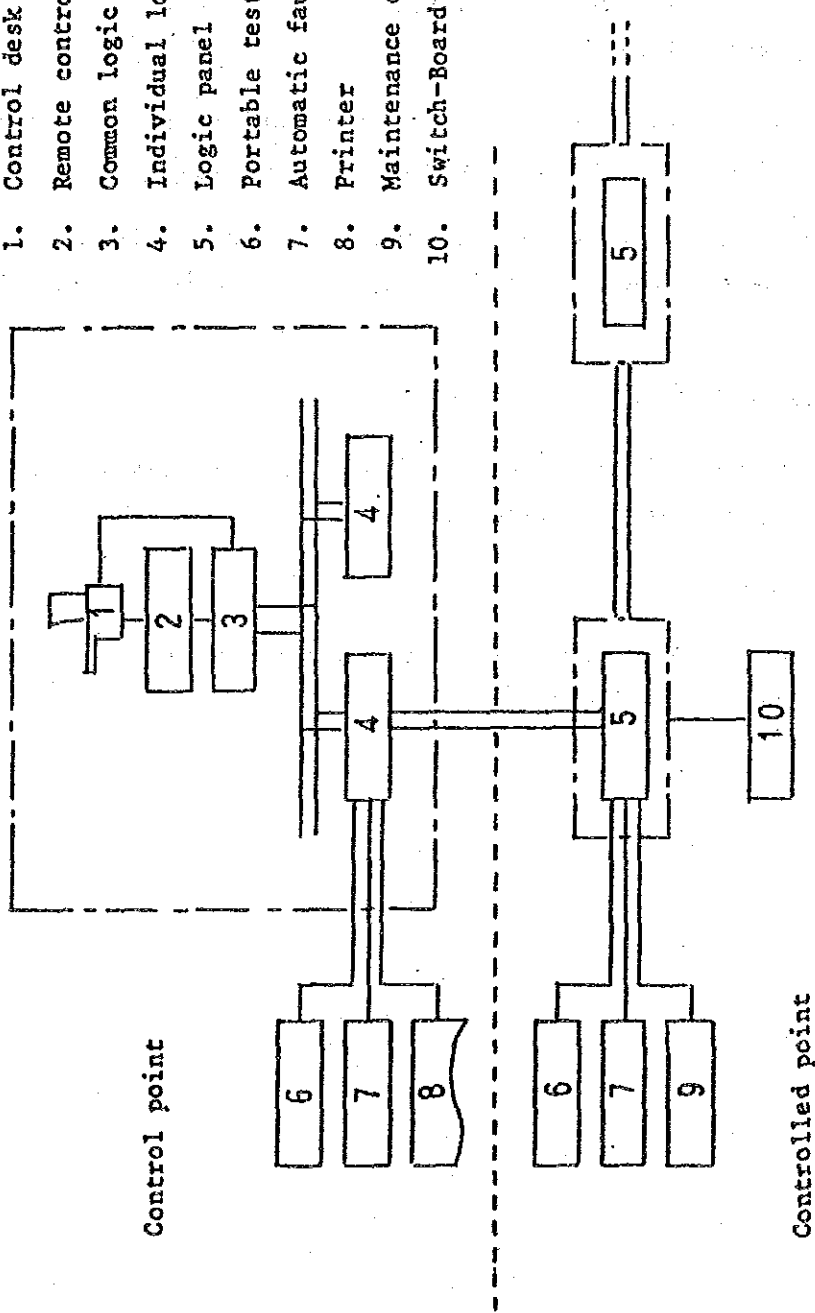


Fig. 2 Block Diagram of the Supervisory/Remote Control System

(2) Remote control logic device

This is a controlling purposes processor, capable of controlling devices automatically, separately and totally, and also of dealing with figure display to CRT.

(3) Common logic panel

This is a device for mutually making interface among control desk, remote control logic device, and individual logic device. It stores control information and output the conditions of equipment at a controlled post to CRT display or the control desk when receiving answer-back signals.

(4) Individual logic panel

It is provided for each group. It controls transmission of such information as supervision of the condition of communication lines, the collation of sending/receiving codes, and supervision of temporary stagnations of control signals. It also creates codes necessary for testing the system.

(5) Logic panel

It is provided at the controlled point. It works as the interfaces with the control center, adjacent controlled points and with the switch-board.

6-3 Outline of AT Feeding Circuit and Connections of Substation, Sectioning Post and Sub-sectioning Post

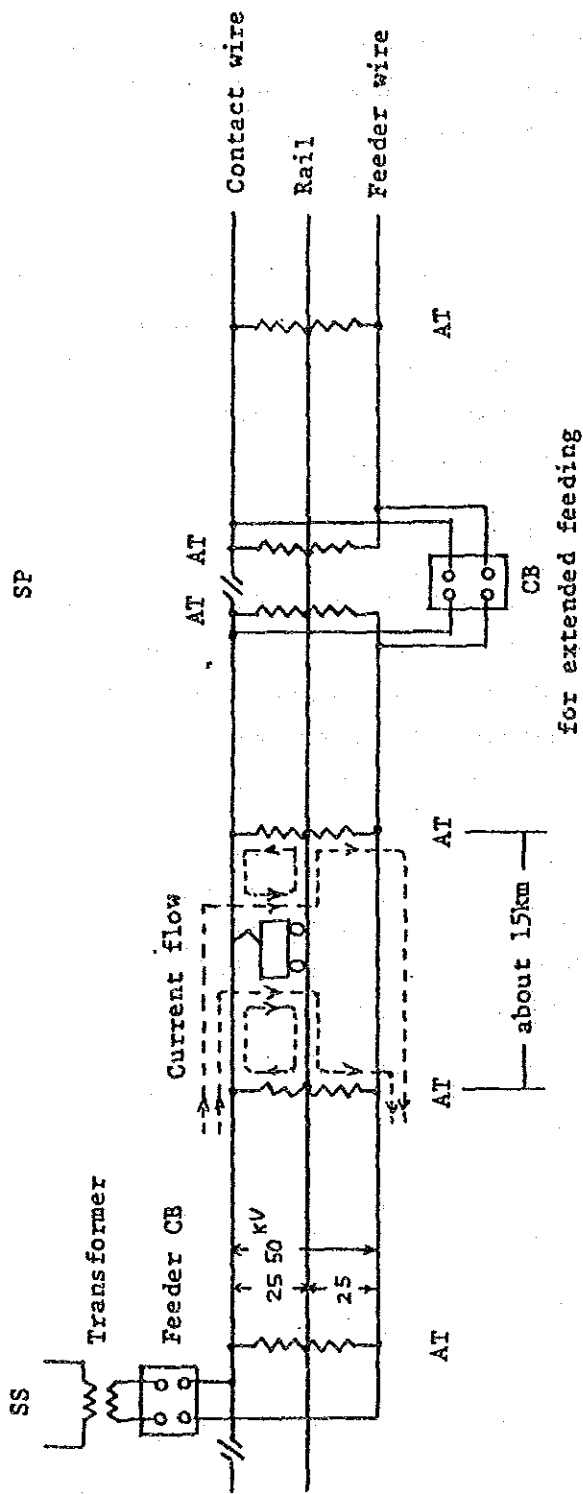


Fig. 1 Outline of AT Feeding Circuit



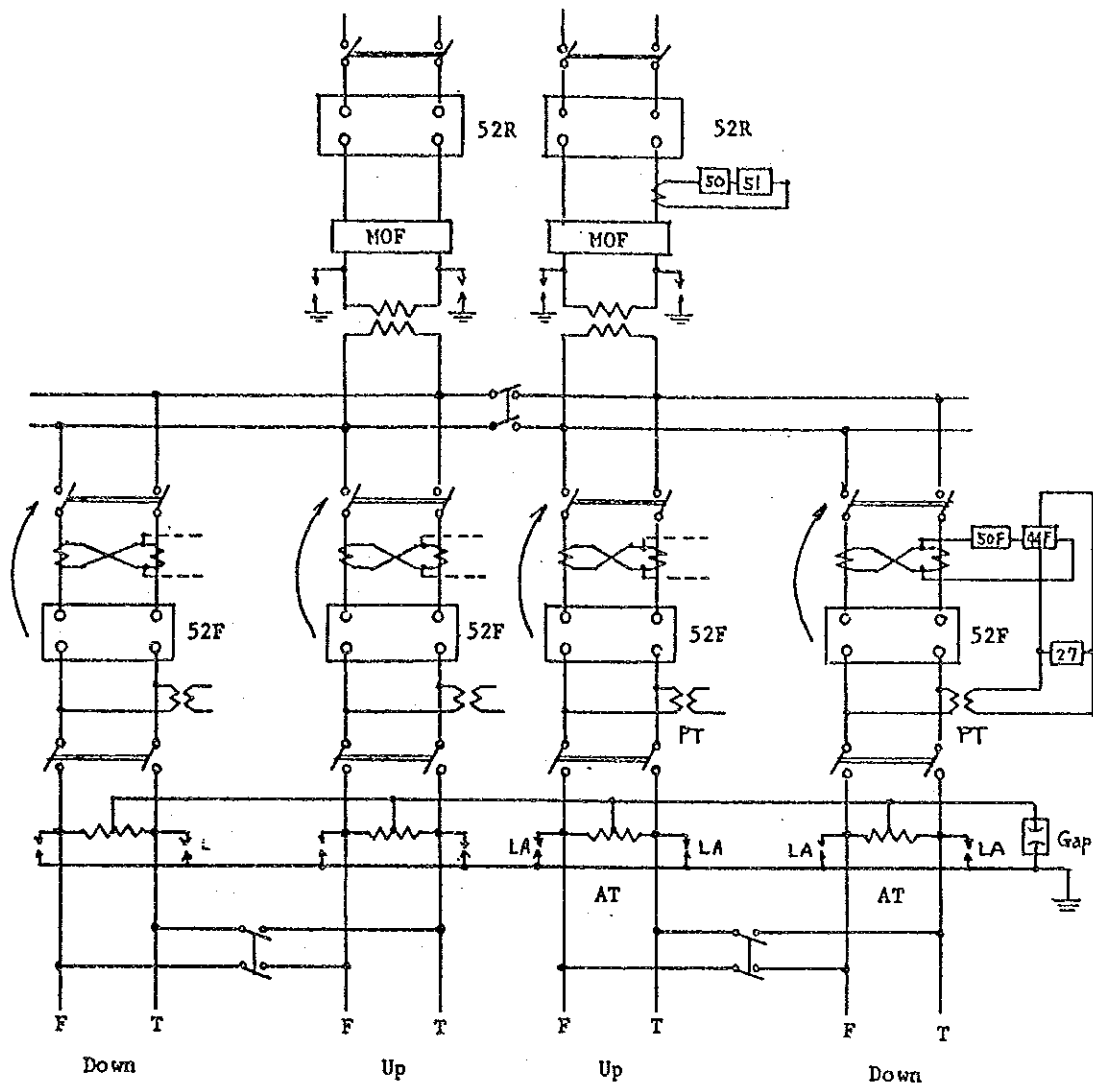


Fig. 2 Standard Schematic Diagram of Traction Substation for AT Feeding System

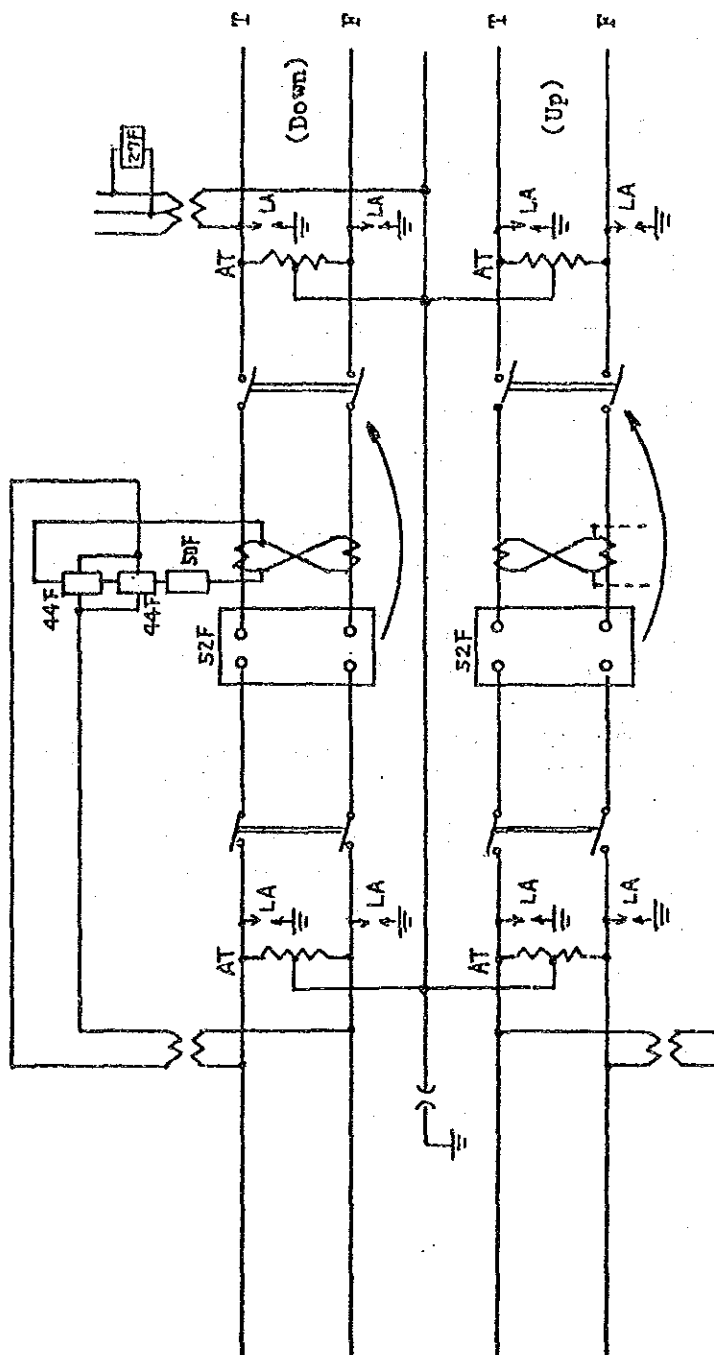


Fig. 3 Standard Schematic Diagram of  
Sectioning Post for AT Feeding System

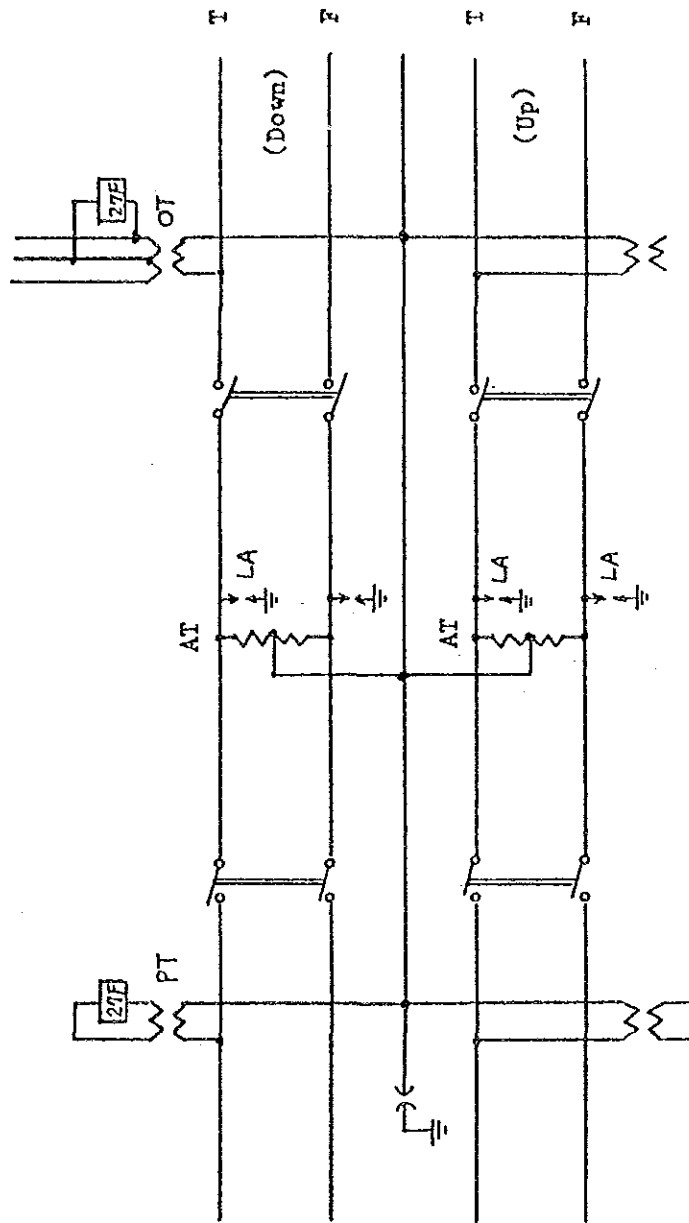


Fig. 4 Standard Schematic Diagram of Sub-Sectioning Post for AT Feeding System

#### 6-4 Shunt Capacitor Equipment

In cases where a shunt capacitor is to be installed at substation to improve the power factor of load current, the following points must be taken into account to prevent abnormal phenomena and damages to the shunt capacitor equipment.

##### 1. Important Items on Shunt Capacitor Equipment

- (1) Inductive reactance value of series reactor of shunt capacitor equipment

Fig. 1 shows the circuit of traction power supply, and Fig. 2 its equivalent circuit.

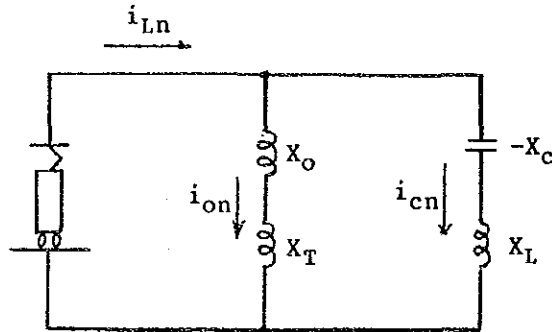
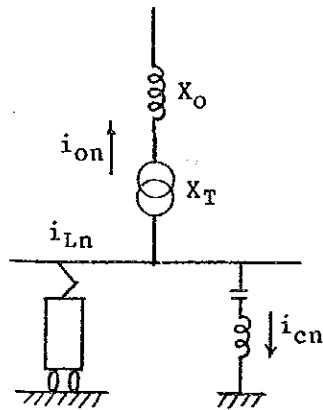


Fig. 1 Traction Power Supply Circuit

Fig. 2 Equivalent Circuit

- where  $X_O$  : Inductive reactance of power source  
 $X_T$  : Inductive reactance of main transformer  
 $-X_C$  : Capacitive reactance of shunt capacitor  
 $X_L$  : Inductive reactance of series reactor of shunt capacitor

When a study is to be made of high harmonic current in the traction power supply circuit, an electric motive unit is considered to be its source.

The following equation represents  $i_{cn}$  and  $i_{on}$ :

$$\left. \begin{aligned} i_{cn} &= \frac{(X_o + X_T)n}{(X_o + X_T)n + (nX_L - \frac{X_c}{n})} \cdot i_{Ln} \dots\dots\dots (1) \\ i_{on} &= i_{Ln} - i_{cn} \end{aligned} \right\}$$

where  $n$  : degree of high harmonic

Note the above equation, denomination, the second term. If  $(nX_L - X_c/n)$  turns to be minus,  $i_{cn}$  or  $i_{on}$  or both will become greater than  $i_{Ln}$ , and the high harmonic current generating from the electric motive unit will be amplified with the shunt capacitor equipment.

The load current contains high harmonic current which exceeds the 3rd harmonic current, such as  $I_3, I_5, I_7 \dots\dots$ ; therefore, it is necessary for the shunt capacitor equipment to be inductive in the frequency area above the 3rd high harmonic frequency ( $3 \times 50 = 150$  Hz).

Fig. 3 shows the characteristic of  $(nX_L - X_c/n)$  when  $X_L = 0.13 X_c$ .

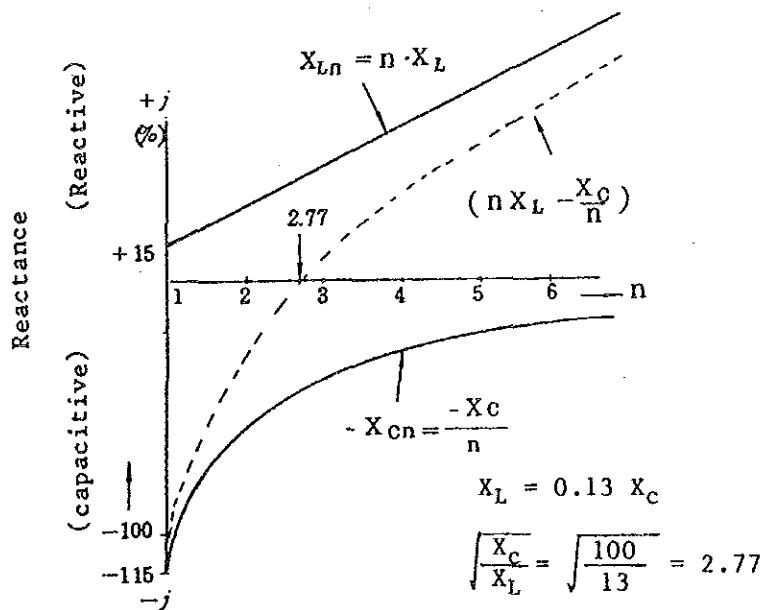


Fig. 3 Reactance of Shunt Capacitor Equipment vs. Frequency

(2) Transient phenomena

1) Inrush current when closed

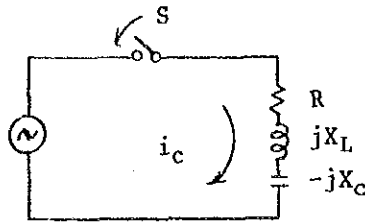


Fig. 4 Equivalent Circuit of Shunt Capacitor Equipment

When S is closed in the circuit of Fig. 4,  $i_c$  is expressed by the following equation:

$$\begin{aligned}
 i_c &= I_c (\sin \omega t - \epsilon^{-\alpha t} \frac{\omega_0}{\omega} \sin \omega_0 t) \\
 &= I_c \left\{ \sin \omega t - \epsilon^{-\alpha t} \frac{\sqrt{X_c}}{\sqrt{X_L}} \sin \left( \omega \sqrt{\frac{X_c}{X_L}} \right) t \right\} \dots (2)
 \end{aligned}$$

where

$I_c$  : rating current of shunt capacitor

$\omega$  : angular velocity (rad/sec)

$\omega_0 = 1 / \sqrt{LC}$  (rad/sec)

$X_c = 1/\omega c$  : capacitive reactance of capacitor at 50 Hz

$X_L = \omega L$  : inductive reactance of series reactor at 50 Hz

Fig. 5 shows wave forms of inrush current.

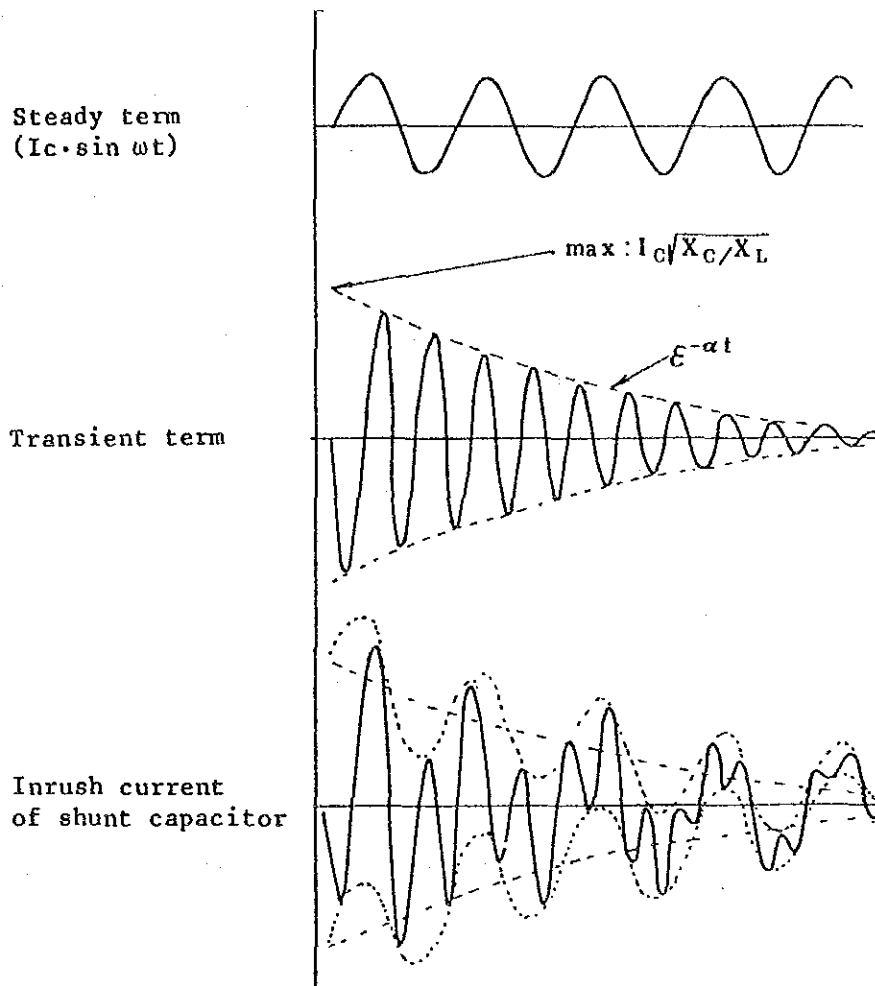


Fig. 5 Wave Forms of Inrush Current

Maximum theoretical value of inrush current and frequency are expressed by:

$$i_c \text{ max} = I_C \times \left( 1 + \sqrt{\frac{X_C}{X_L}} \right) \dots \dots \dots (3)$$

$$f_{ic} = 50 \times \sqrt{\frac{X_C}{X_L}}$$

When  $X_L = 0.13X_C$ ,  $i_c \text{ max}$  will be 3.8 times as large as the rated current, and frequency 2.8 times. Therefore, the capacitor must be capable of withstanding the inrush current.

Should the capacitor be equipped with a fuse, it is necessary for the fuse not to blow due to the inrush current. If a fuse in a certain unit capacitor is blown, the total capacitive reactance value,  $X_c$ , will increase, and the resonance frequency will become higher, and this will cause the amplification of high harmonic current. Basically, therefore, it is not recommendable to use a fuse in unit capacitor. When the unit capacitor is detected defective, it is necessary to cut off the whole shunt capacitor from the circuit with circuit breaker.

2) Transient over-voltage of capacitor

The capacitor must be capable of withstanding the transient over-voltage shown in Equation (4).

$$e_c (\max) = E_c (-\cos \omega t + \epsilon^{-\alpha t} \cos \omega \omega t) \dots \dots \dots (4)$$

3) Transient over-voltage of series reactor

The series reactor must be capable of withstanding the transient over-voltage expressed in Equation (5).

$$e_L (\max) = \omega L I_c \cos \omega t + \frac{1}{\omega c} I_c \epsilon^{-\alpha t} \cos \omega \omega t \dots \dots \dots (5)$$

4) Recovering voltage appeared to CB terminals when opened

In cases where CB is to be installed on the shunt capacitor equipment, it is necessary to use a CB which will not restrike, since recovery voltage, which is two times as large as the power source voltage, will arise between CB terminals when CB is opened.

(3) Ferranti effect

Install a shunt capacitor, and, when there is no train load, the voltage,  $(X_o + X_T) I_c$ , will go up (Ferranti effect), exceeding the power source voltage. It is necessary to keep this voltage within the allowable value.



where  $X_O$  : Inductive reactance of power source

$X_L$  : Leakage reactance of transformer

$I_c$  : Rating current of shunt capacitor

(4) Capacities of shunt capacitor and power factor

Assume the variations of the reactive power measured at a certain substation, as shown in Fig. 6 a. Arrange them in order from the largest, and Fig. 6 b. shows the density distribution of reactive power.

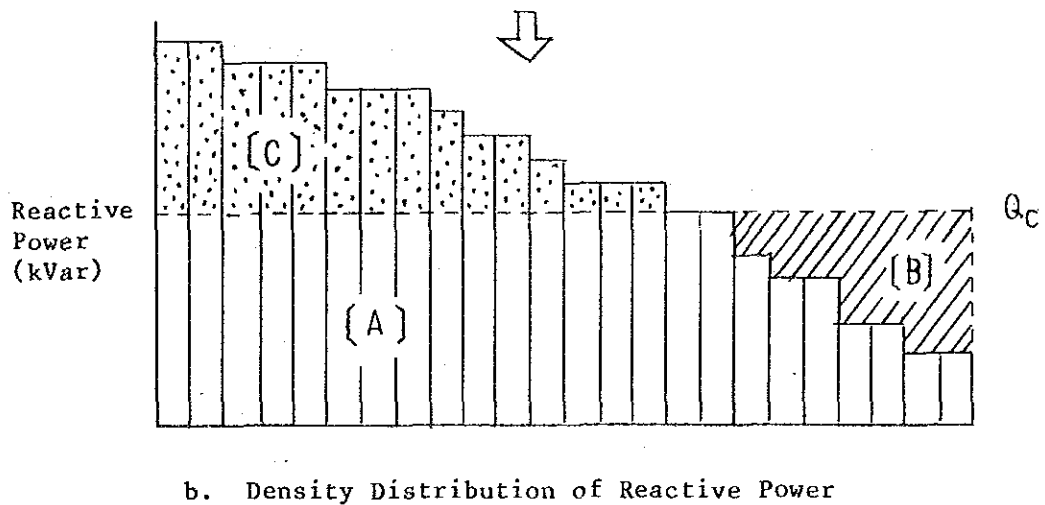
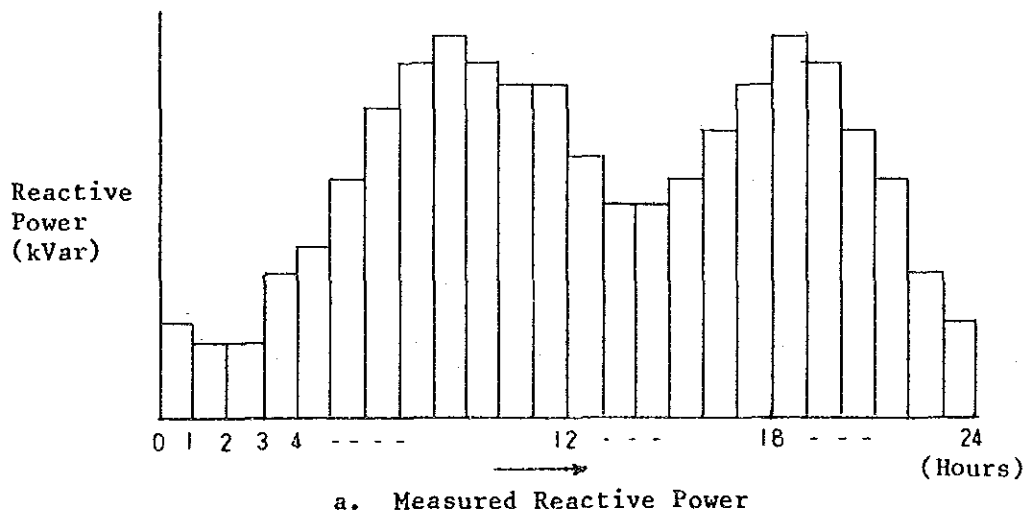


Fig. 6 Reactive Power Distribution

Install a shunt capacitor,  $Q_c$  value, and the power factor will improve from Equation (5) to Equation (6).




Power factor before improvement

$$\cos \theta_1 = \frac{P_L}{\sqrt{P_L^2 + Q_L^2}} = \frac{P_L}{\sqrt{P_L^2 + (A + C)^2}} \dots\dots\dots (5)$$

Power factor after improvement

$$\cos \theta_2 = \frac{P_L}{\sqrt{P_L^2 + (Q_L - KQ_C)^2}} = \frac{P_L}{\sqrt{P_L^2 + C^2}} \dots\dots\dots (6)$$

where  $K = \frac{A}{A + B}$

- A :  area (kVarH) H
- B :  area (kVarH) H
- C :  area (kVarH) H

2. Study on Shunt Capacitor Equipment at Panki SS

(1) Constants of the existing shunt capacitor equipment

1) Constants

- C : 16 units, 1022 kVar at 25 kV  
unit capacitor : 9.2 kVar, 7.5 kV
- L : 11.316Ω at 50 Hz, continuous current 49.2 A

2) Study

The following values are obtainable from the above constants.

a. Capacitive reactance of capacitors at 50 Hz

$$X_C = \frac{(25 \text{ kV})^2}{1022 \text{ kVar}} = 611.5 \Omega$$

b. Ratio of  $X_L$  to  $X_C$

$$X_L / X_C = 11.361 / 611.5 = 0.0186$$

(1.9% of  $X_C$ )

c. Resonance frequency

$$f = \frac{1}{2\pi\sqrt{LC}} = 366.8 \text{ Hz} = 7.34 \times 50 \text{ Hz}$$

(2) Problems

- 1) Over-current of shunt capacitor and high harmonic current interference with power source

The value of  $X_L$  is 1.9% of  $X_C$ , and resonance frequency is  $7.34 \times 50 = 366.8 \text{ Hz}$ . Therefore, the shunt capacitor amplifies 7th, 5th, and 3rd harmonic currents. In other words, it gives over-current to the shunt capacitor, and high harmonic current interference to the power source.

- 2) Blowing of unit capacitor fuse and breaking of capacitor

Since the value of series reactor is not appropriate, the probability of fuse blowing and capacitor breaking is high. Causes are:

- a. Over-current of shunt capacitor due to the amplification of high harmonic current shown in 1).
- b. As can be seen by Equation (3),  $i_C \text{ max}$  flows about 8 times larger than the rated current.
- c. The capacitor is breakable due to the over-current or over-voltage. The over-current in the above a. and b. will break the capacitor.
- d. When the fuse of a unit capacitor is gone, the resonance frequency of shunt capacitor equipment will become higher. As a result, the amplification of high harmonic current will be enhanced, and the inrush current enlarged. In other words, it can be assumed that capacitors will break one after another due to the domino effect.

### (3) Recommendations

- 1) The value of series reactor of shunt capacitor at the Panki Feeding Post is not appropriate. Therefore, it is suggested that this series reactor be improved immediately. Check on  $X_L$  of shunt capacitor equipment at other feeding posts and substations, and improve if necessary. It is recommendable that the value of  $X_L$  be 13-15% of  $X_C$ .
- 2) It is essential that the series reactor should not be saturated due to the fluctuation in load current and the transient phenomena that arise when the shunt capacitor equipment is closed. When the value of  $X_L$  becomes close to 11% of the value of  $X_C$ , parallel resonance in the 3rd harmonic frequency to the inductive reactance on the side of power source ( $(X_0 + X_T)$  in Fig. 1) might take place.
- 3) The use of a fuse is effective in protecting a unit capacitor, but pernicious to the shunt capacitor equipment. Therefore the current protection method must be re-studied.
- 4) In cases where CB is to be used for shunt capacitor equipment, it must be well capable of closing and opening the leading current.

### 6-5 Series Capacitor Equipment

In cases where a series capacitor is to be used to reduce the voltage drop due to inductive reactance of transformer or feeding circuit, important items that should be taken into account are as given below:

#### 1. Connection Method and Allowable Ohm Value of Series Capacitor

##### (1) Series capacitor for main transformer

##### 1) Connection method

To compensate the leakage reactance of main transformer, connect a series capacitor in series on the secondary side of transformer.

- a. The voltage compensation effect is the same even when a series capacitor is connected on the primary side of transformer, but this is not economical since the insulation level of the series capacitor against ground will be higher.
- b. In connecting a series capacitor on the secondary side of transformer, it is economical to connect it on the negative side as shown in Fig. 1.

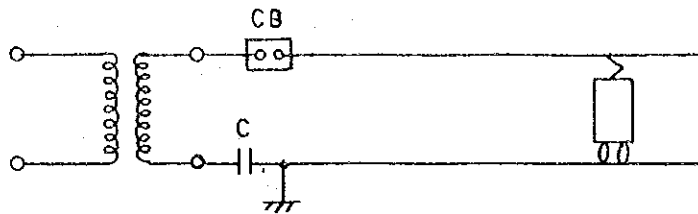


Fig. 1 Series Capacitor for Main Transformer

2) Ohm value

Appropriate ohm value at 50 Hz of series capacitor is 80-90% of the main transformer leakage reactance at 50 Hz. If the ohm value is made larger than this, an abnormal phenomenon, such as a fractional harmonic oscillation, will arise when CB is closed.

(2) Series capacitor for feeder circuit without BT

1) Connection method

Insert series capacitors in series with the contact wire and dispersedly according to the amount of load and the voltage value to be compensated, as shown in Fig. 2.

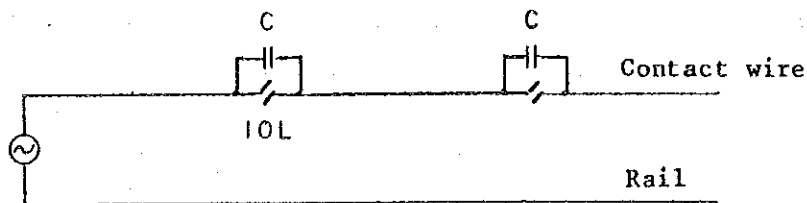


Fig. 2 Series Capacitors for Feeder Circuit without BT

2) Ohm value

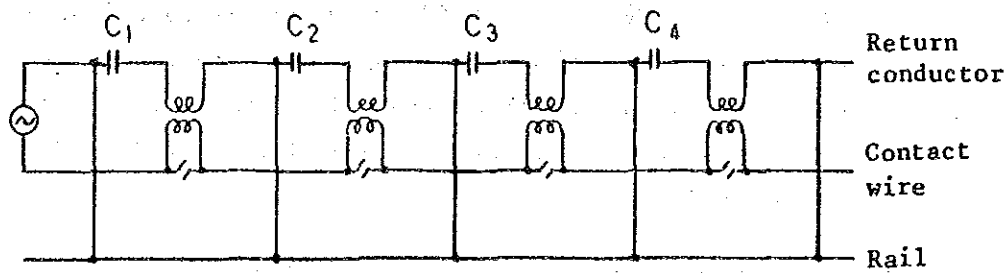
From JR experiences, appropriate ohm value at 50 Hz of series capacitor at a place is approximately  $5\ \Omega$ . That is, let the inductive reactance of return conductor is at  $0.5\ \Omega/\text{km}$ . A  $5\text{-}\Omega$  capacitor will be installed every 10 km.

(3) Series capacitor for feeder circuit with BT

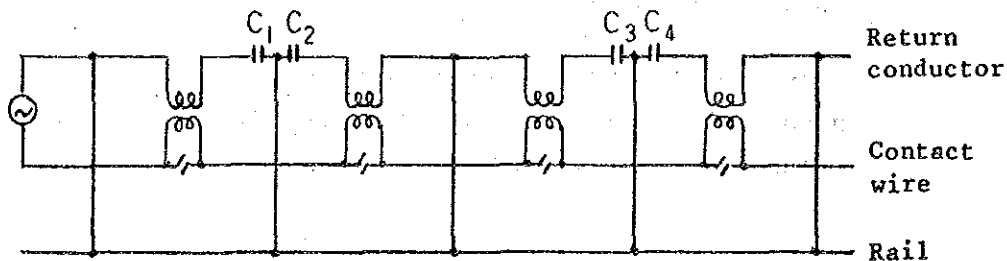
1) Connection method

a. Whether a series capacitor is connected on the side of contact wire or return conductor, the voltage compensation effect is the same; however, the latter is more economical.

b. The number of places where series capacitors are to be installed will be decided according to the size of load and the voltage value to be compensated. However, in cases where series capacitors are to be provided at every BT, install them in a concentrating way as shown in Fig. 3 b., rather than 3 a., because maintenance is easier.



a. Dispersing Installation



b. Concentrating Installation

Fig. 3 Series Capacitors for Feeder Circuit with BT

2) Ohm value

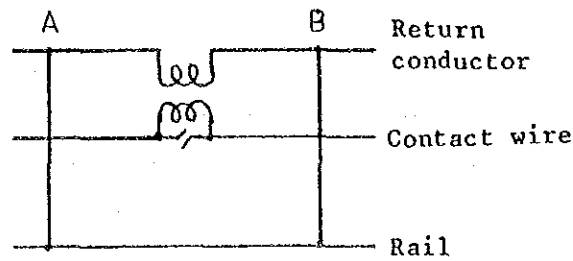


Fig. 4 BT Feeding Circuit

The ohm value of series capacitor to be inserted in a BT circuit will be the inductive reactance value of return conductor between A and B.

For reference, JR experiences show that the inductive reactance value of return conductor is approximately  $0.5\Omega / \text{km}$  at 50 Hz. That is, if the distance between boosting lines is 2.6 km, the value of capacitor to be inserted will be  $1.3\Omega$ .

2. Protection device

When a short-circuit fault occurs in a circuit where a series capacitor is installed, a short-circuit current of that circuit flows in that series capacitor. It is considered not economical to provide a series capacitor that is capable of withstanding this short-circuit current. As a countermeasure, gap and bypass contactor will usually be provided in parallel with the series capacitor.

Protective gap for use with series capacitor is to be provided with the following features:

- a. Uniform and stable sparking characteristics
- b. Robust construction with sufficient mechanical strength and short time over current characteristics
- c. Self arc quenching abilities.
- d. Minimum and easy maintenance requirements.

After sparking the gap, the bypass contactor is closed within 10 ms to bypass the gap.

Fig. 6 shows a circuit diagram for this application. The most remarkable difference from ordinary applications is that a device specially developed for the prevention of subharmonic oscillation due to frequent switching of no load traction transformer is incorporated with capacitor. The device comprises a saturable reactor and resistor connected in series, and delivers low impedance discharging circuit for the low frequency voltage across capacitor induced by inrush current of no load transformer.

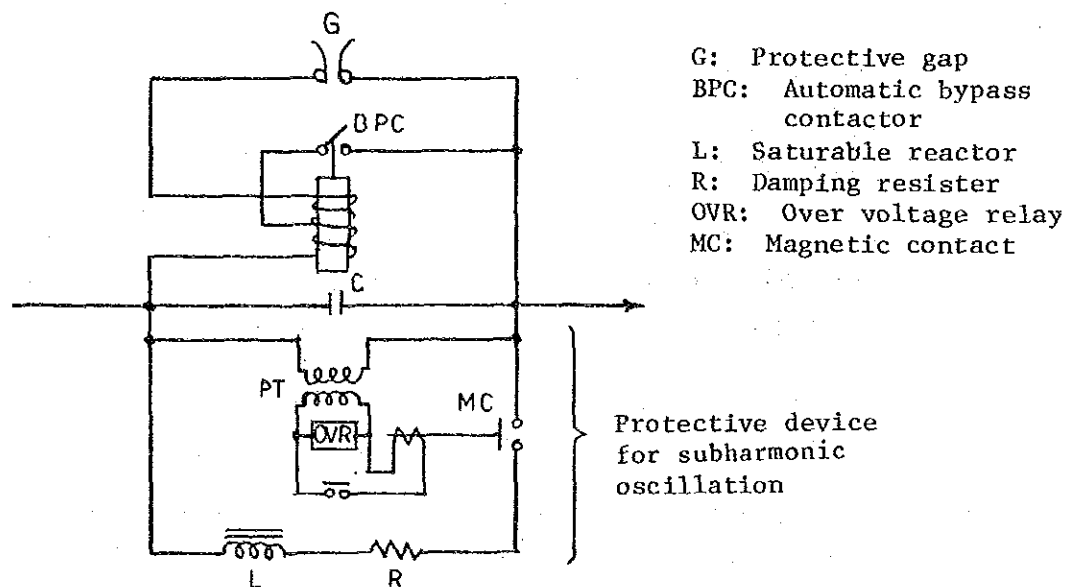


Fig. 6 Connection of Series Capacitor for AC Electrified Railway

#### 6-6 Thyristor Control Reactor (TCR)

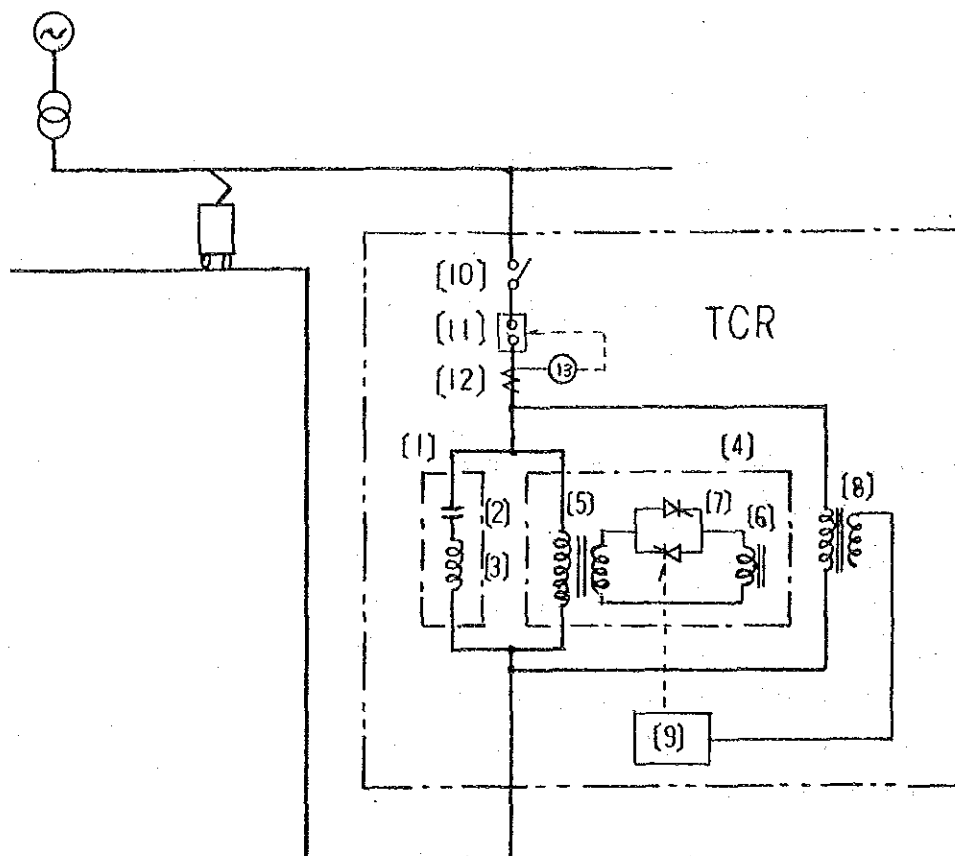
A study has been made of a TCR, shunt capacitor and thyristor-controlled shunt reactor provided at the end of feeding zone. Normally, keep the shunt capacitor and shunt reactor in parallel resonance. When the feeder voltage drops, the reactor will be accordingly automatically controlled by thyristor, and leading reactive power supplied to the feeding circuit. Consequently, the power factor seen from the substation will be improved, and the voltage drop in the feeder circuit reduced.



## 1. Composition of TCR

Fig. 1 shows the composition of TCR.

- (1) Shunt capacitor branch [1] is a capacitor in terms of a function, but, when to be used as a traction feeder circuit, it needs series reactor [3]. For the reason why the reactor is required and the reactance value required for the reactor, see Appendix 6-4, Shunt Capacitor Equipment.
- (2) In principle, it is enough to put the thyristors of inverse parallel connection and the reactor in series for shunt reactor branch [4].  
Actually, however, in designing hardware, since connecting thyristors directly with the 25 kV circuit will make the equipment expensive for their protection, provide transformer [5], set the secondary voltage of the transformer, for example, at 2,000 V, at which the thyristors are controllable, and connect thyristors [7] and reactor [6] with the secondary winding circuit.
- (3) Make the value of reactance, including the leakage reactance of transformer [5], so that shunt reactor branch [4] and shunt capacitor branch [1] will be in parallel resonance.
- (4) Conduct the control of TCR by detecting the feeder voltage with operating transformer [8].



- |                            |                              |
|----------------------------|------------------------------|
| [1] Shunt capacitor branch | [8] Operating transformer    |
| [2] Shunt capacitor        | [9] Thyristor control device |
| [3] Series reactor         | [10] Disconnecting switch    |
| [4] Shunt reactor branch   | [11] Circuit breaker         |
| [5] Transformer            | [12] Current transformer     |
| [6] Reactor                | [13] Over current relay      |
| [7] Thyristor              |                              |

Fig. 1 Connection Diagram of TCR

## 2. Outline Design of TCR

To study the features and effects of TCR, its approximate constants are required; therefore, an outline design is made of two kinds of capacities. Taking into account the load in the Section, the maximum leading current that TCR can supply is assumed to be at 300 A and 600 A.

Table 1 shows the main features of TCR.

Table 1 Main Features

Item	Feature	Rating of TCR		No. of Fig. 1	
		600 A	300 A		
Shunt Capacitor	Rating voltage	31.1 kV	31.1 kV	[2]	[1]
	Rating current	600 A	300 A		
	Rating capacity	18.6 MVA	9.3 MVA		
	Capacitive reactance	52.7Ω	105.4Ω		
Series reactor	Rating voltage	3.58 kV	3.58 kV	[3]	
	Instant voltage	27.5 kV	27.5 kV		
	Rating current	600 A	300 A		
	Rating capacity	2.15 MVA	1.07 MVA		
	Inductive reactance	6.85Ω	13.7Ω		
Transformer	Rating voltage (pri/second)	27.5/2 kV	27.5/2 kV	[5]	[4]
	Rating current (pri/second)	600/8,250A	300/4,125A		
	Rating capacity	16.5 MVA	8.25 MVA		
Reactor	Rating voltage	2 kV	2 kV	[6]	
	Rating current	8,250 A	4,125 A		
	Rating capacity	16.5 MVA	8.25 MVA		
	Inductive reactance	0.242Ω	0.484Ω		
Thyristers	Single phase, Inverse parallel connection			[7]	
	Phase control				
	Rating voltage	2 kV	2 kV		
	Rating current	8,250 A	4,125 A		
Operating transformer	Rating voltage (pri/second)	27.5kV/220V	27.5kV/220V	[8]	
	Rating capacity	10 kVA	10 kVA		
Thyristor control device	Voltage control			[9]	
Disconnecting switch	Rating voltage	27.5 kV	27.5 kV	[10]	
	Rating current	600 A	300 A		
Circuit breaker	Rating voltage	27.5 kV	27.5 kV	[11]	
	Rating current	600 A	300 A		
	GCB				

Given below for reference is the calculating process on the main equipment in the case of the rated current 600 A:

(1) Shunt capacitor, [2] of Fig. 1

Suppose inductive reactance of series capacitor is 13% of capacitive reactance of shunt capacitor;

- 1) Capacitive reactance at 50 Hz

$$X_c (1 - 0.13) = \frac{27.5 \times 10^3}{600}$$

$$X_c = 52.7 \Omega$$

- 2) Rating voltage = 27.5 kV x 1.13 = 31.1 kV

- 3) Rating capacity = 31.1 kV x 600 A = 18.6 MVA

(2) Series reactor, [3] of Fig. 1

- 1) Inductive reactance at 50 Hz

$$X_{SR} = 52.7 \times 0.13 = 6.85 \Omega$$

- 2) Instant voltage = 27.5 kV

- 3) Rating voltage = 27.5 x 0.13 = 3.58 kV

- 4) Rating capacity = 3.58 x 600 = 2.1 MVA

(3) Transformer, [5] of Fig. 1

- 1) Voltage ratio = 27.5 kV/2 kV = 13.75

- 2) Secondary winding current = 600 A x 13.75 = 8,250 A

- 3) Rating capacity = 2 kV x 8,250 A = 16.5 MVA

(4) Reactor, [6] of Fig. 1

- 1) Rating voltage = 2 kV

- 2) Rating current = 8,250 A

- 3) Inductive reactance = 2 kV/8,250 A = 0.242  $\Omega$ \*

\* Including transformer leakage impedance at 2 kV base.

4) Rating capacity = 2 kV x 8,250 A = 16.5 MVA

3. Precondition of Calculation

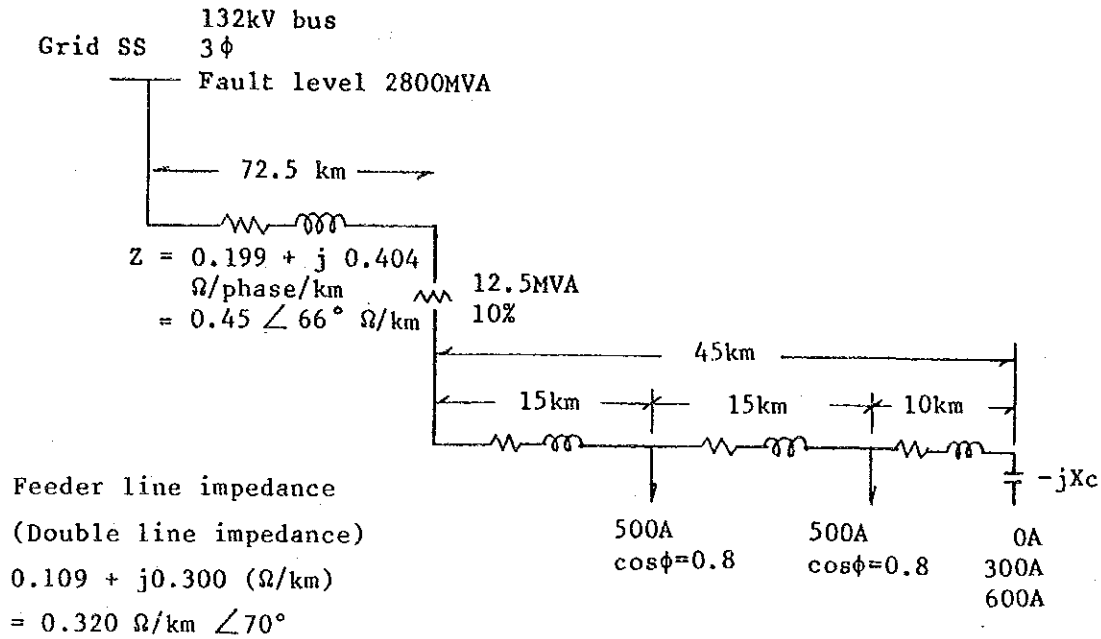


Fig. 2 Precondition of Calculation

Circuit constants are all converted to be at 27.5 kV base.

- 1) Power source impedance at 27.5 kV base,  $X_o$ :

$$X_o = j2 \frac{V^2}{P} = j2 \times \frac{27.5^2 \times 10^6}{2,800 \times 10^6} = j 0.54 \Omega$$

- 2) Transmission line impedance at 27.5 kV base,  $X_{TM}$ :

$$X_{TM} = 2 (0.199 + j0.404) \times \left(\frac{27.5}{132}\right)^2 \times 72.5$$

$$= 1.25 + j 2.54 \Omega$$

- 3) Transformer impedance at 27.5 kV base,  $X_T$ :

$$X_T = j \frac{V^2 \times \%Z}{100 \times P} = j \frac{27.5^2 \times 10^6 \times 10}{100 \times 12.5 \times 10^6} = j6.05 \Omega$$

- 4) Feeder line impedance,  $X_L$ :

$$(0.109 + j0.3) \times 15 = 1.635 + j4.5 \Omega / 15 \text{ km}$$

$$(0.109 + j0.3) \times 10 = 1.09 + j3.0 \Omega / 10 \text{ km}$$

5) Load impedance,  $Z_{L1}$ ,  $Z_{L2}$ :

The loads of the up and down lines are given as a whole: namely, impedance, about that for 500 A ( $\cos \phi = 0.8$ ), is provided each at the two points, 15 km and 30 km.

6) Capacitive reactance of shunt capacitor,  $X_c$ :

Capacitive reactance is so assumed that the current is to be about 300 A (and 600A).

Impedance map is shown in Fig. 3.

#### 4. Results of Calculation and Review

Fig. 4 shows the results of calculation.

(1) Improvement effect of feeder voltage

13.4 kV at the load point at the 30 km point without TCR provided will improve to be 18.1 kV when the leading current, 300 A, is supplied with TCR provided, and 22.4 kV when 600 A. The improvement effect of feeder voltage is remarkable. The voltage at the end of feeding zone will slightly rise above that at the secondary load point, raising no particular problem.

(2) Improvement effect of power factor

Assume the power factor of load is 0.8. The power factor from substation is 0.69 when TCR is not provided. This will improve to be 0.87 when the leading current, 300 A, is supplied with TCR provided, and 0.98 and 600 A. The improvement effect of power factor is as large as that of feeder voltage.

(3) Supply current reduction effect attended with power factor improvement

When TCR is not provided, the substation supply current will be the load current in total, but if the leading current, 300 A, is supplied, it will be reduced by 11% to 89%, and 600 A, by 13% to 87%, respectively.

(4) Power losses of TCR

See Fig. 1 and Table 1. One of the biggest TCR problems is the power losses of shunt reactor branch [4]. That is, in the case of 600 A, the capacity each of transformer [5] and reactor [6] is 16.5 MVA, the reactor having 8,250 A at 2 kV. In the case of 300 A, 4,125 A.

Assume that the total power loss due to transformer and reactor is 2%. Losses will be 330 kW when 600 A is on. Furthermore, thyristor loss, and 8 kW, if the forward drop is 1 V, must be added.

Actually, the current of reactor being controlled with thyristor when there is a load, these losses will not be always made; however, the value of losses as described above is considered too large.

Expenses to be required against power losses will become much larger than part of the demand charges reduced through the improvement of power factor.

(5) Cost of TCR

The cost of a 300 A TCR is higher than that of a substation to construct.

(6) Others

Studies should have been made of the control method of TRC, high harmonic current, and high harmonic voltage that appears in the feeder circuit, but they have been omitted because the problems involved in (4) and (5) are so important and serious.

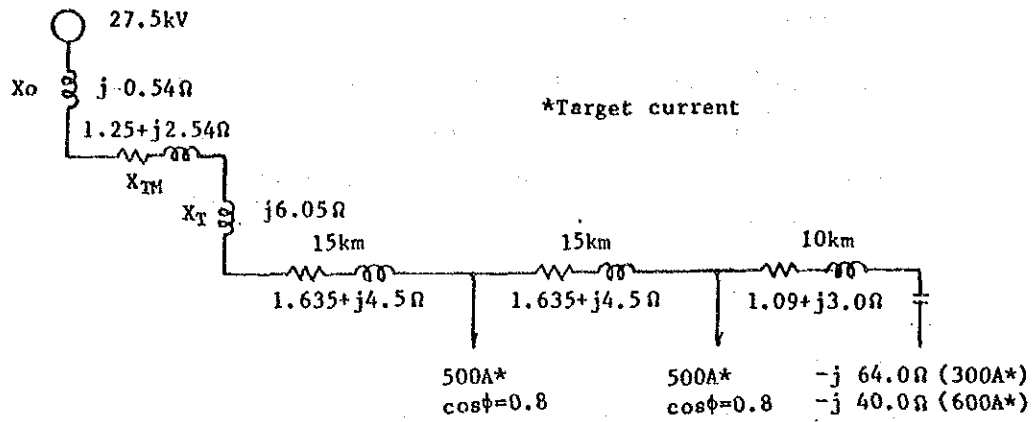


Fig. 3 Impedance Map

Ic	Voltage, current and power factor
OA (No compensation)	<p>SS 19.6kV, 984A, 15.4kV, 491A, 491A, 13.4kV, 494A, SP 13.4kV, Contact wire, Rail, <math>\cos\phi=0.69</math>, <math>\cos\phi=0.8</math>, <math>\cos\phi=0.8</math></p>
I = 300A	<p>21.9kV, 876A, 18.9kV, 416A, 500A, 18.1kV, 513A, 18.9kV, 296A, Contact wire, Rail, <math>\cos\phi=0.87</math>, <math>\cos\phi=0.8</math>, <math>\cos\phi=0.8</math></p>
I = 600A	<p>23.8kV, 854A, 21.9kV, 520A, 497A, 22.4kV, 509A, 24.2kV, 605A, Contact wire, Rail, <math>\cos\phi=0.98</math>, <math>\cos\phi=0.8</math>, <math>\cos\phi=0.8</math></p>

Fig. 4 Voltage, Current Distribution and Power Factor



## 5. Conclusion and Recommendations

TCR will improve the power factor and also will be effective in reducing the voltage drop; however, it is considered not practical to use it because its power losses is strikingly large and its cost is much higher than a substation.

To improve the power factor, it is much better to install shunt capacitors at substation. See Appendix 6-4.

For reducing the voltage drop, it is recommendable that series capacitor to compensate the leakage reactance of main transformer and the inductive reactance in the feeder circuit be provided. See Appendix 6-5.

In any event, for the Section where the future load current is expected to increase two times or more than the present one, the best solution is to add 6 more substations.

## 6-7 Distance Relay

What are most basically required for distance relay? They are:

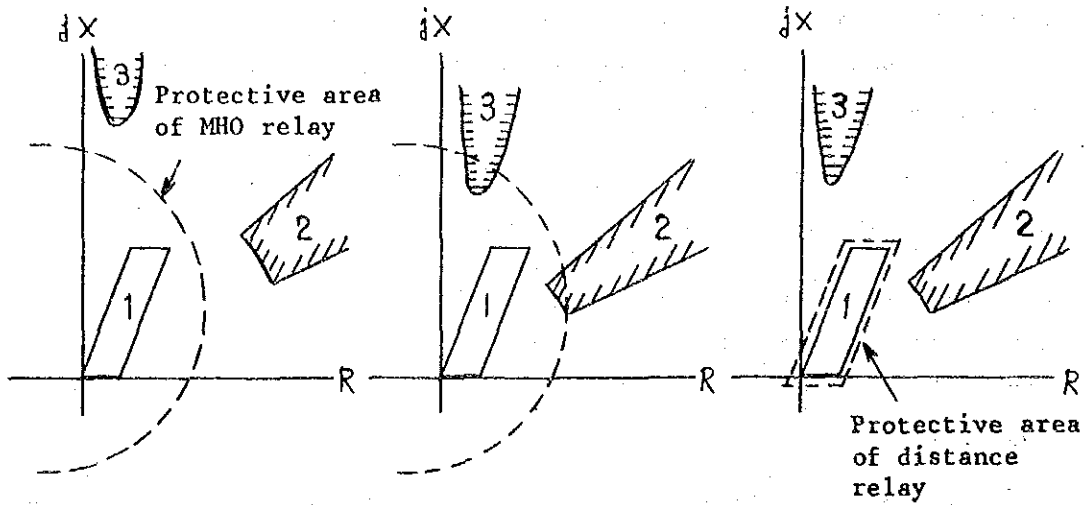
- assured detection of feeder circuit faults; and
- non-malfunction due to load current and exciting inrush current to no load transformer of rolling stock.

The MHO relay is now used as a distance relay at IR's substations. As is shown in Fig. 1 a. the MHO relay is capable of selecting the fault current when the load current is small, but not capable when the load current is large as shown in Fig. 1 b.

To solve this problem, the distance relay of semiconductor static having parallelogram characteristics has been developed. Fig. 1 c. shows the characteristics.

It is convenient for this semiconductor static type distance relay to obtain the protection area desired, but if high harmonic component is contained in the feeder voltage/current, this protection area might be changed; therefore, this point must be taken into account for designing.

- 1: Fault current zone
- 2: Load current zone
- 3: Exciting inrush current zone



- a. Selection between load and fault current when load current is small
- b. Selection between load and fault current when load current increases
- c. Protection area of parallelogram type distance relay

Fig. 1 Protection Area of Distance Relay

## 6-8 Automatic Inspection Device for Substation Equipment

On JR's existing lines, the automatic inspection device is used to inspect switchboards at substations, sectioning posts and sub-sectioning posts automatically and efficiently. There are two types of device, one fixed aboard the motorcar and the portable.

### 1. Switch-boards to be Inspected

At AC substation: Main switch-board, power receiving and sending switch-board, transformer switch-board, AC feeding switch-board, and high-tension power distribution switch-board.

At DC substation: In addition to the foregoing switch-boards, rectifier switch-board, and DC feeding switch-board.

### 2. Kinds of Inspection

#### (1) Overall inspection

In the form of various signals such as operating command signals and fault detecting signals, voltage and current are to be sent from the inspection device to the switch-board, and the functions of the switch-board, that is, whether or not the mechanical/electrical interlocking and fault indication have been performed correctly within the allowable time, are checked. Every sequence of the switch-board functions and the operations of equipment are inspected. Take the closing of a circuit breaker for example, it is actually closed by command signal, response time measured and recorded. Depending on the type of switch-board, the number of items to be inspected ranges from 15 to 20.

Inspection results are to be judged in such a way as given below:

- Good : Switch-board and other equipment have functioned correctly within the allowable time.
- Caution: Response has been made as expected, but timing not appropriate.
- Bad : No response.

When judged to be "Caution" or "Bad", the circuits concerned are to be inspected again individually, necessary adjustment and repair made.

(2) Protective relay inspection

The operational characteristics of protective relay are to be inspected. The inspection is to be conducted when the protective relay has been found abnormal during the overall inspection or when it is deemed necessary otherwise. Voltage/current generator for inspecting the protective relay and other instruments are provided on the operating panel of the inspection device.

3. Inspection Method

Connect the inspection device with the switch-board to be inspected by a special cable of 120 cores and a coupler. To do this, the switch-board must be equipped with a receptacle, with some modification of circuit connection to enable automatic inspection.

4. Construction

Fig. 1 is a block diagram, outlining the construction of the automatic inspection device.

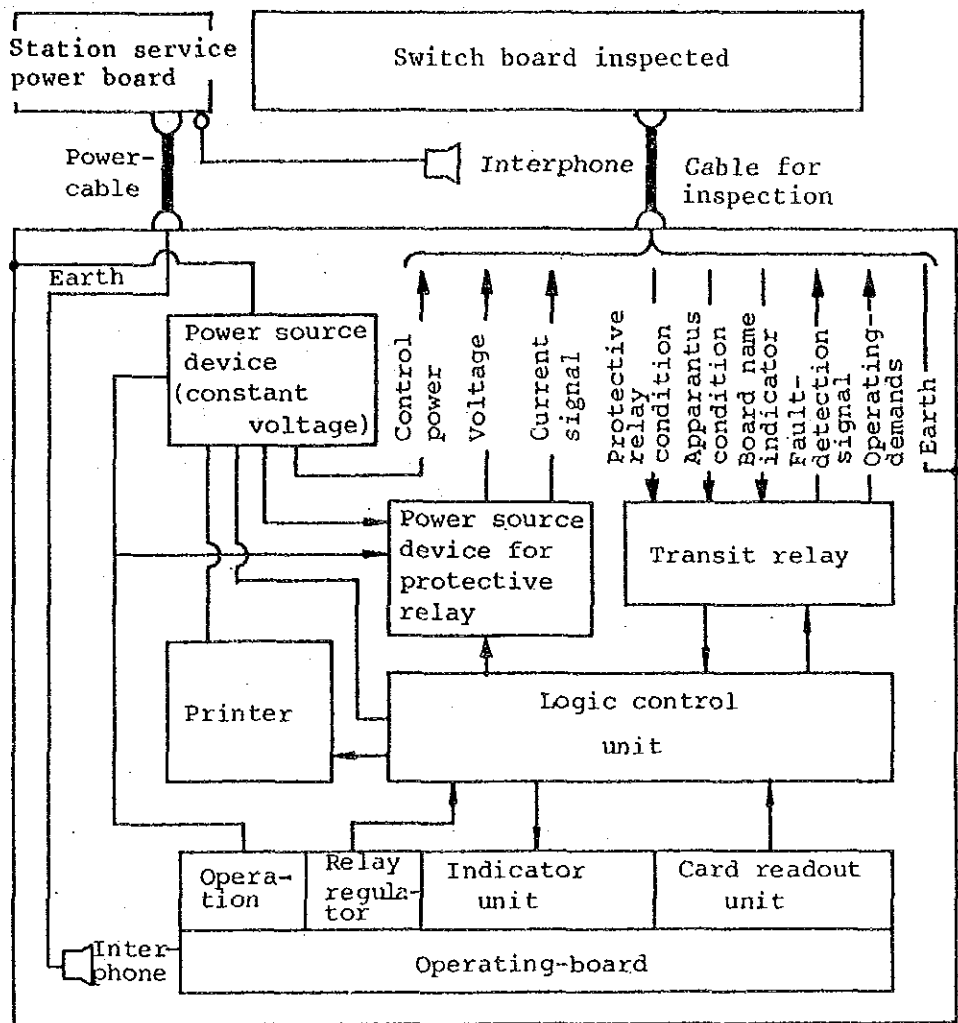


Fig. 1 Block Diagram of Automatic Inspection Device for Substation Equipment

## 5. Effects

- (1) Operations and characteristics of substation main equipment, such as mechanical/electrical interlocking, protective relays, circuit breakers, disconnecting switches, can be checked under the same conditions as actual.
- (2) All data are to be automatically recorded. Therefore, it is possible to prepare figures and data for maintenance. Comparison of previous and present data will serve to judge the deteriorating status of equipment and forecast the occurrence of failure.
- (3) Since no circuit disconnection or dismantlement of protective relay terminals is required inspection is highly reliable; that is, if the terminals are dismantled for inspection, there might be a chance for them to be loosely tightened or circuits to be misconnected, resulting in failures.
- (4) With the use of the automatic inspection device, the inspection time may be greatly reduced, from the average three hours to only 10 minutes for a team of three inspectors to inspect one switch-board.

## 6-9 Performance of Simple Catenary System

### 1. Wave Propagation Velocity and Train Speed

In order to collect current with contact wire in good order and without trouble, it is necessary to keep stable contact force between the contact wire and the pantograph.

When a train runs with the pantograph sliding the contact wire, the contact wire is distorted and the distorted waves propagate in it. In case the train speed is the same or faster than its propagation velocity, the contact wire behind of the pantograph will vibrate heavily as shown in Fig. 1.

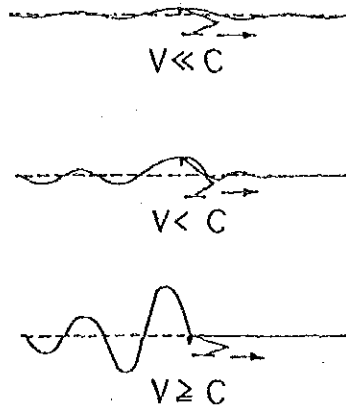


Fig. 1 Models of Contact Wire Waves

Under the condition of  $V \geq C$ , an abnormally big force will work between the pantograph and the contact wire, and either of them may be damages. Theoretically, therefore, the speed less than the wave propagation velocity allows the current collection with pantograph. Generally, a speed, some 70% of the wave propagation velocity is considered to be the maximum allowable speed.

$C$ , the wave propagation velocity, is obtained using the following formula:

$$C = \sqrt{T/\rho} \dots\dots\dots (A)$$

where  $T$ : Wires tension (N)

$\rho$ : Mass of unit length of OHE wires (kg/m)

## 2. Spring Constant

Since the catenary wire is supported at every supporting point, it is difficult for them to move at the supporting point, but easy inbetween the span. Fig. 2 shows the features of static uplift of three catenary systems - simple, stitched and high tension simple - when a constant force is added.

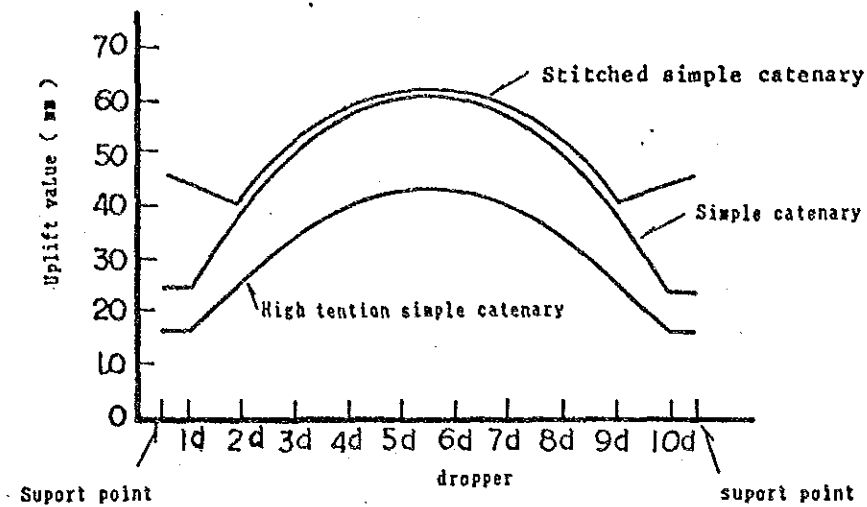


Fig. 2 Static Uplift Characteristics  
 (in cases 50 m span, uplift force 98N (10 kgf))

These curves can be considered to be the locuses of pantograph contact strips when they move very slowly, so slowly to the extent that their vibrations are negligible. This curve is attributable that the spring constant varies within the span.

It is the smallest in the middle of the span, and the largest at the supporting point.

### 3. Resonance Velocity

One of the most serious problems involved in the interaction between catenary and pantograph systems is a large contact loss that arises repeatedly over each span. This contact loss occurs due to the mechanical interaction of the catenary and pantograph systems. In general,  $V_c$ , the resonance velocity, at which the vertical movement of the pantograph becomes extremely large, is expressed by the following formula:

$$V_c = \frac{S}{2\pi} \sqrt{\frac{K}{M} \left(1 - \frac{1}{2} \epsilon^2\right)} \dots\dots (B)$$



where  $\bar{K}$ : The average value of spring constant

$\epsilon$ : Variation ratio of spring constant

$$\epsilon = (K_{\max} - K_{\min})/2\bar{K}$$

S: Span length

M: The total equivalent masses of pantograph, catenary and contact wires.

There are two ways of increasing  $V_c$  in the above formula. One is to make  $\bar{K}$  larger, and the other to make M smaller.

#### 4. Resonance of OHE System and Pantograph

The movements of contact wire and catenary wire on a simple or compound catenary system are almost the same. Namely, the OHE system has natural vibration where its wave length is the same as the span length, between the supporting points where the catenary wire is fixed. While the pantograph shows the complicated vertical movement due to the correlation between different static uplift values at different points in the span and the natural vibration cycle. Fig. 3 shows the pantograph locuses by train speed on simple catenary system.

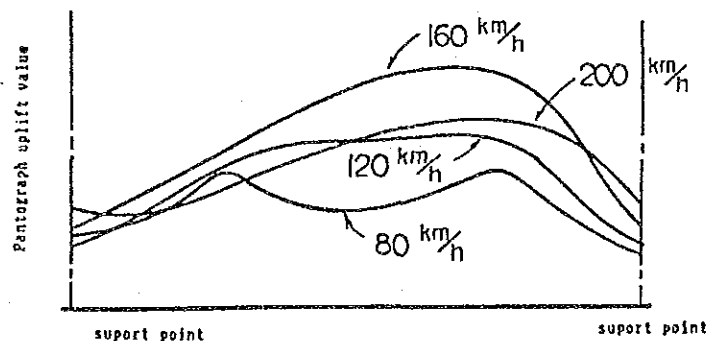


Fig. 3 Pantograph Locuses of Simple Catenary System

The vertical movement of the pantograph like this will bring about a change in contact force against the contact wire due to the inertia of pantograph, and, when this change is extremely big, will give rise to a large contact loss. And this is what is called the resonance of a single pantograph. Fig. 4 illustrates the contact loss rate, and uplift value, actually measured on JR's simple catenary systems.

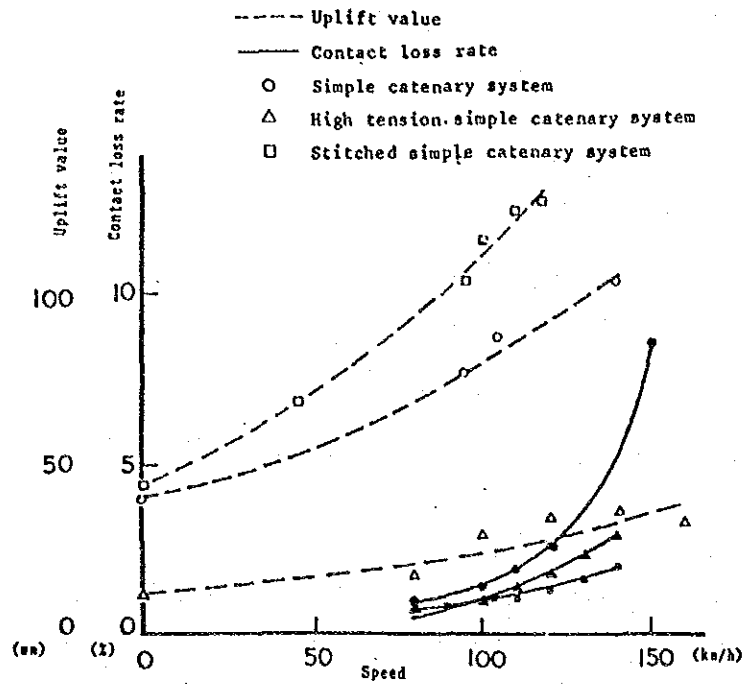


Fig. 4 Uplift Value and Contact Loss Rate Actually Measured on JR's Simple Catenary Systems

As can be seen in Fig. 4, the contact loss rates of both the stitched simple catenary and the high tension simple catenary systems are better than that of simple catenary system.

When a train with plural pantographs runs, plural pantograph resonances will arise due to the different mechanism. This is caused by the coincidence between the natural vibration cycle of contact wire and the running cycle of pantograph. Therefore, the rear pantograph, the worse will have the worse current collection characteristics.

6-10 JR's Shinkansen OHE under AT Feeding System

Table 1 The Features of JR's Shinkansen OHE

Type of catenary system	High tension compound
AT feeder wire	ACSR 330 mm <sup>2</sup>
Protective wire	ACSR 95 mm <sup>2</sup>
Catenary wire	St 180 mm <sup>2</sup>
Auxiliary catenary wire	Cu 150 mm <sup>2</sup>
Contact wire	Cu-sn 170 mm <sup>2</sup>
Tension length	1500 m
Regulated or unregulated	Regulated
Span length	50 m
Stagger	+15 cm
Height of contact wire	5.0 m
Section on main line	Insulated overlaps
Current carrying capacity	1020 Amps

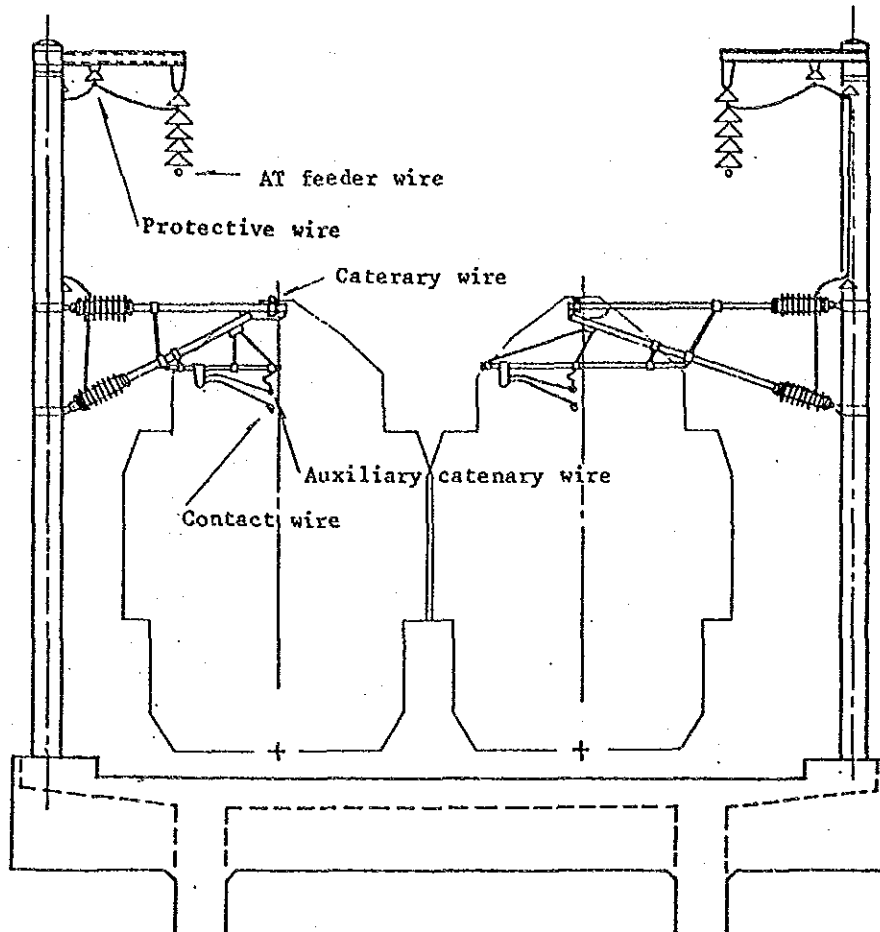


Fig. 1 JR's Shinkansen OHE Under AT Feeding System





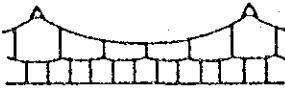
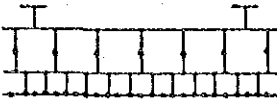
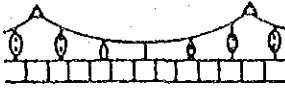
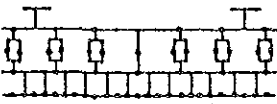
#### 6-11 Outline of Computer Simulation Technique on OHE Characteristics

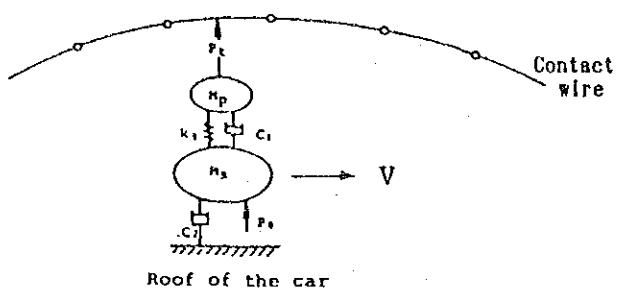
JR does a great deal of analysis through computer simulation for solving complicated phenomena of current collection such as in the case of overlapping, hard spots, and deformed catenary systems.

A catenary line is composed of such fittings as droppers and hangers attached to wires such as contact wire and catenary wire, etc. Also the pantograph is a complicated assembly of a slider, a pan, retaining springs, a main frame, main springs, dampers, etc.

It is almost impossible to analyze theoretically such complicated structures as they are, while the simulation method enables us to handle the system as it is. For this purpose, therefore, a suitable model is required. The Fig. 1 illustrates the models of overhead system and a pantograph.

The most important thing in a simulation method is how well reality can be expressed; and this is pursued by comparing the test results with an actual value.

Kind of system	Real Installation	Analyzed model	Code
Simple			N.S
Stitched Simple			S.S
Compound			N.C
Composed Compound			C.C

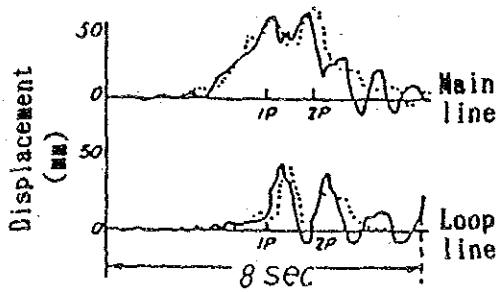


- Pt: Contact force between contact wire and pantograph
- Po: Uplift force of pantograph
- Mp: Equivalent mass of pantograph
- Ms: Equivalent mass of main frame
- K1: Spring constant of pantograph
- C1: Damping constant between pan and main frame
- C2: Damping constant between main frame and foundation frame

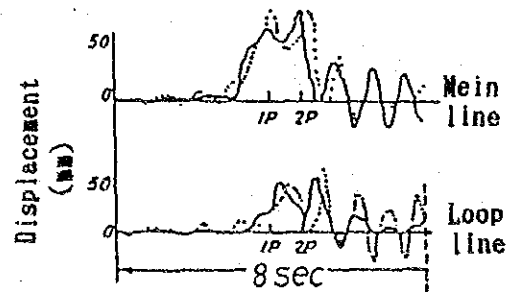
Fig. 1 Simulation Models of Overhead Contact System and Pantograph

Fig. 2 illustrates a comparison of the measured value by test with the result of simulation at the displacement of the turn out in case of varied train speed. The results show how well the displacement coincide. The simulation method is established through such confirmation. Using this method, research is being done on the influence of speed, pantograph interval and uplift on the overhead system. Contact loss ratio, pantograph's up and down motion, contact force as well as the uplift can be grasped through the simulation method, which are very useful to find out the actual dynamic characteristics of OHE system and pantographs.

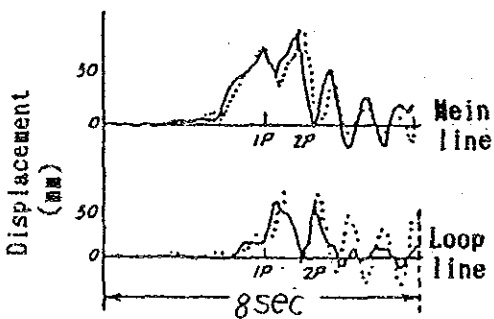
V = 60Km/h  
L = 18.75m



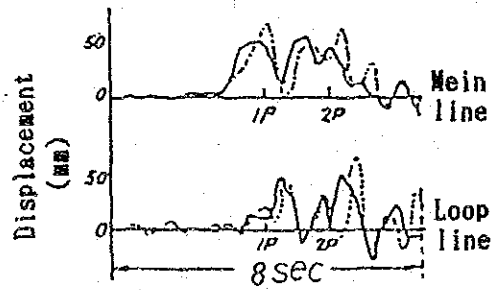
V = 80Km/h  
L = 18.75m



V = 70Km/h  
L = 18.75m



V = 70Km/h  
L = 31.25m



v : Speed

L : Distance between the first and second pantographs

1P: Passing time of the first pantograph

2P: Passing time of the second pantograph

Fig. 2 Comparison of Measured Value with Simulation Result

Fig. 2 shows a comparison of the uplift waveform, while Fig. 3 is a comparison of the maximum values of uplift at each position. In either case it can be seen that they coincide well with the measured values.

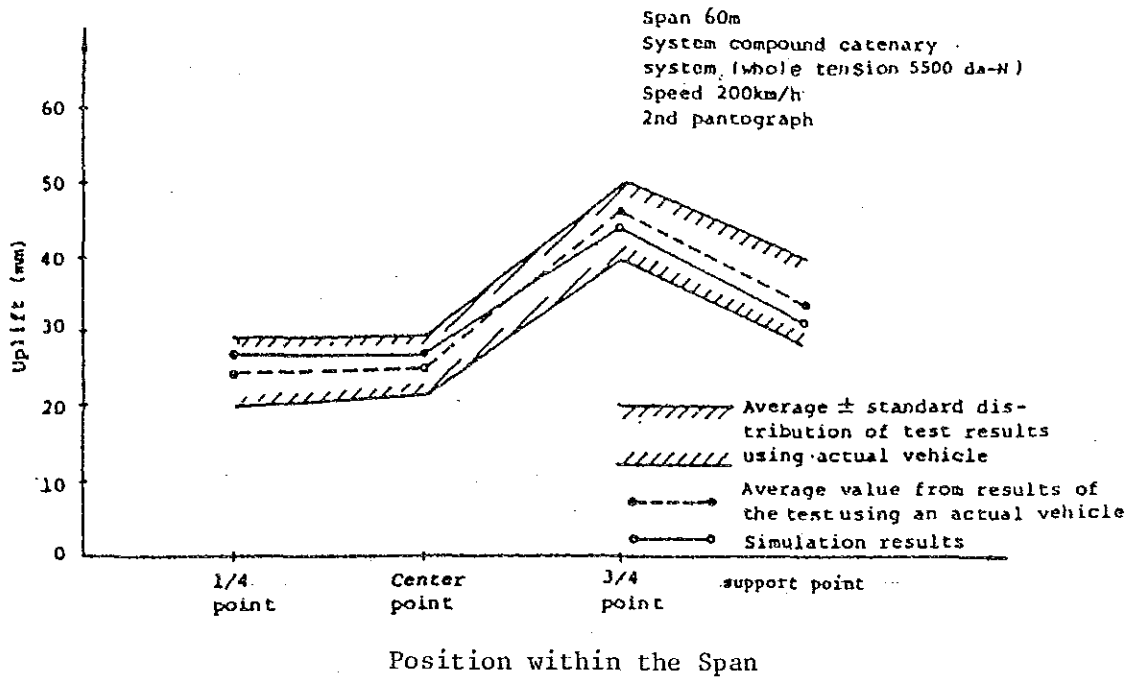


Fig. 3 Measured and Simulated Uplift Values of High Tension Compound Catenary System

6-12 Simulation Contents in Reference to OHE Characteristics at the Speed of 160 km/h

1) Existing OHE system

a) Basic conditions

For computer calculation, the OHE system is supposed to be composed of 8 spans, the both ends of which being fixed.

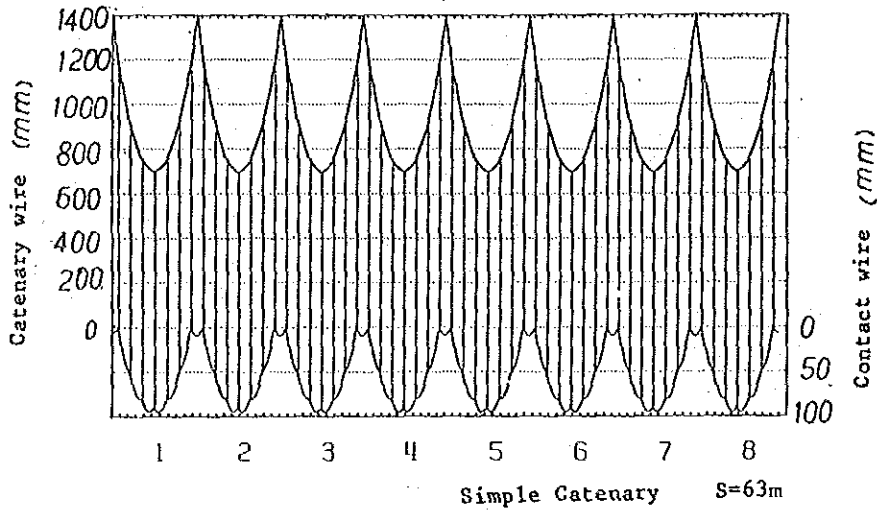


Fig. 1 OHE System Model

It is assumed that the pantograph AM-12 is a single-mass model with 32 kg equivalent mass and that the pantograph uplift force is 65 N (6.5 kgf) when the car is at static condition and 114 N when running at the speed of 160 km/h. Fig. 2 shows the pantograph model.

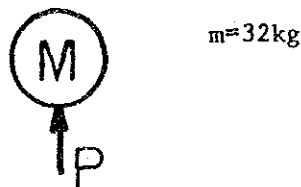


Fig. 2 Pantograph Model



b) Results

Fig. 3 shows the pantograph locus and contact force in reference to the existing OHE system.

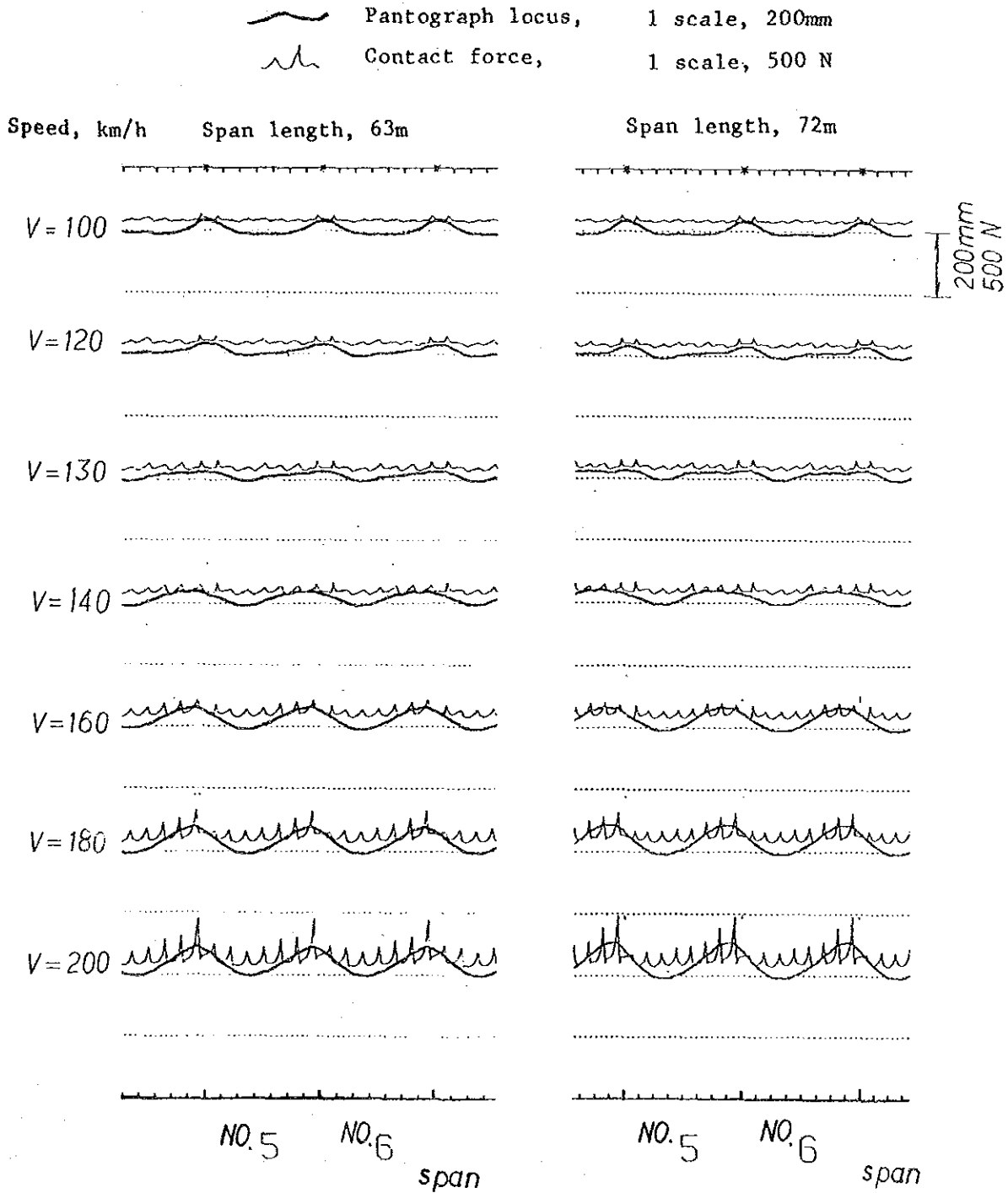


Fig. 3 Pantograph Locus and Contact Force

As can be seen, the faster the up-and-down motion of pantograph, the larger the vibration amplitude, and also the faster the speed, the stronger the contact force.

Fig. 4 shows the correlation between contact loss ratio and speed, and Fig. 5 that between pantograph vibration amplitude and speed. The contact loss ratio is less than 3% when the speed is 160 km/h, and the pantograph vibration amplitude is 80 mm when 160 km/h.

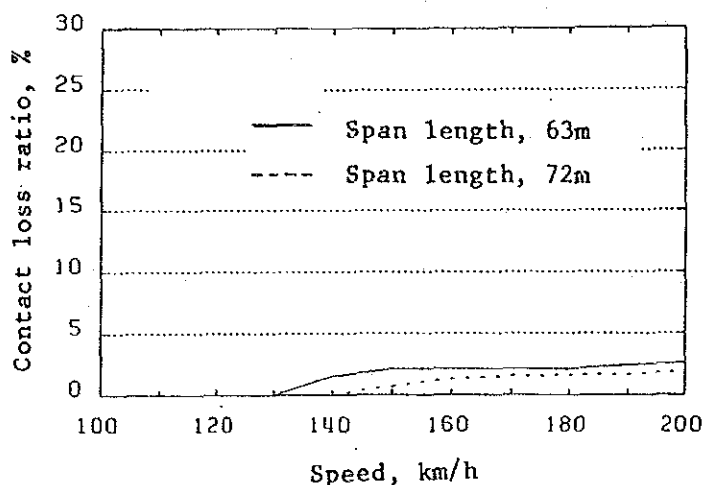


Fig. 4 Contact Loss Ratio vs. Speed

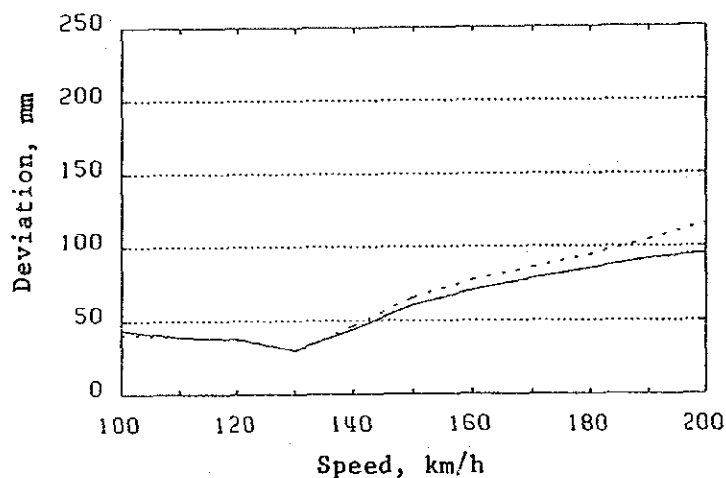


Fig. 5 Pantograph Vibration Amplitude vs. Speed

Fig. 6 shows the uplift at each point in a span moving with time passing. The uplift moves 63 m (the length of one span) in about 2.2 seconds when the speed is 100 km/h, and also 63 m in about 1.4 seconds when 160 km/h. Residual vibration barely occurs when the speed is 100 km/h, but it does when 160 km/h.

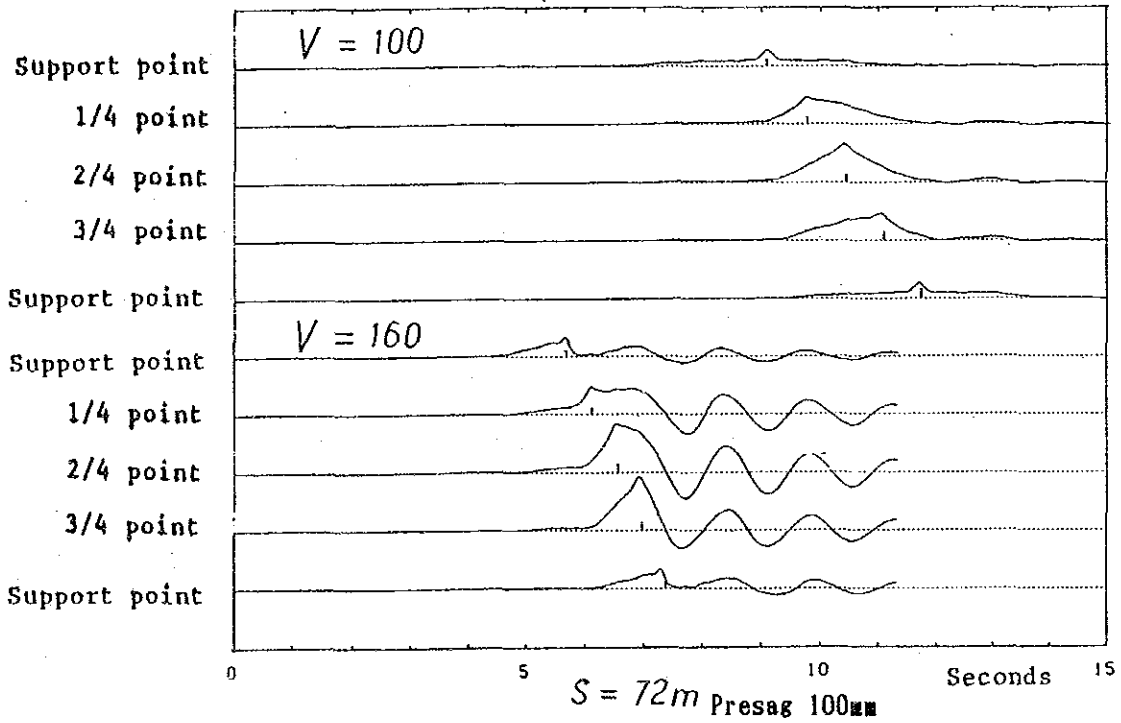
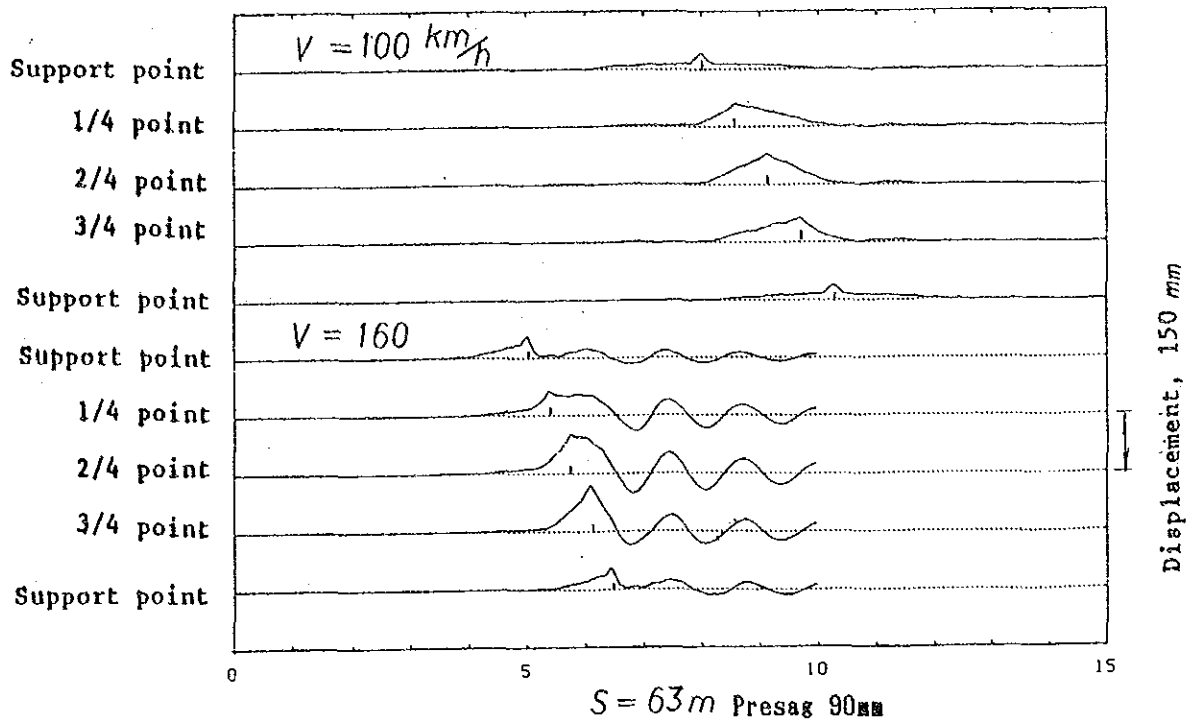


Fig. 6 Uplift and Vibration at Each Point in a Span



- Span length 63 m/72 m
- Presag 90 mm/100 mm
- Contact wire gradient ratio 0
- Dropper distance 9 m, equal distance for easier calculation
- Number of running pantographs 1
- Pantograph type AM-12
- Pantograph equivalent mass 32 kg
- Pantograph uplift force at static 65 N
- Pantograph uplift force at 160 km/h 114 N\*1

\*1 Aerodynamic lift at high speeds is taken into account, lift characteristics is assumed to be the same as PSl6.

Table 1 Shows the Pantograph running speeds and uplift forces.

Table 1 Pantograph Running Speeds and Uplift Forces

Running speed, km/h	100	110	120	130	140	150	160	170	180	190	200
Uplift force, N	84	88	93	97	102	108	114	120	127	134	141

## 2) Upgraded OHE system

### a) Simulation conditions

Simulation conditions are the same as those in 1)-c), except that the tension each of catenary wire and contact wire is changed from 1,000 kgf to 1,200 kgf.

### b) Simulation results

Pantograph locus and contact force are shown in Fig. 8, pantograph running speed vs. contact lost in Fig. 9, and pantograph running speed vs. vibration amplitude in Fig. 10.

The pantograph locus and contact force show the same tendency as that shown in Fig. 3 of the existing OHE system simulation. That is, the faster the pantograph running speed, the larger the pantograph vibration amplitude and contact force.

Fig. 9 shows the contact loss smaller than that in Fig. 4. The contact loss at the speed of 160 km/h is about 2% when the span length is 63 m, and 0.5% 72 m. These values are fairly better than 2.1% and 1.2%, respectively, in the case of the existing OHE system simulation.

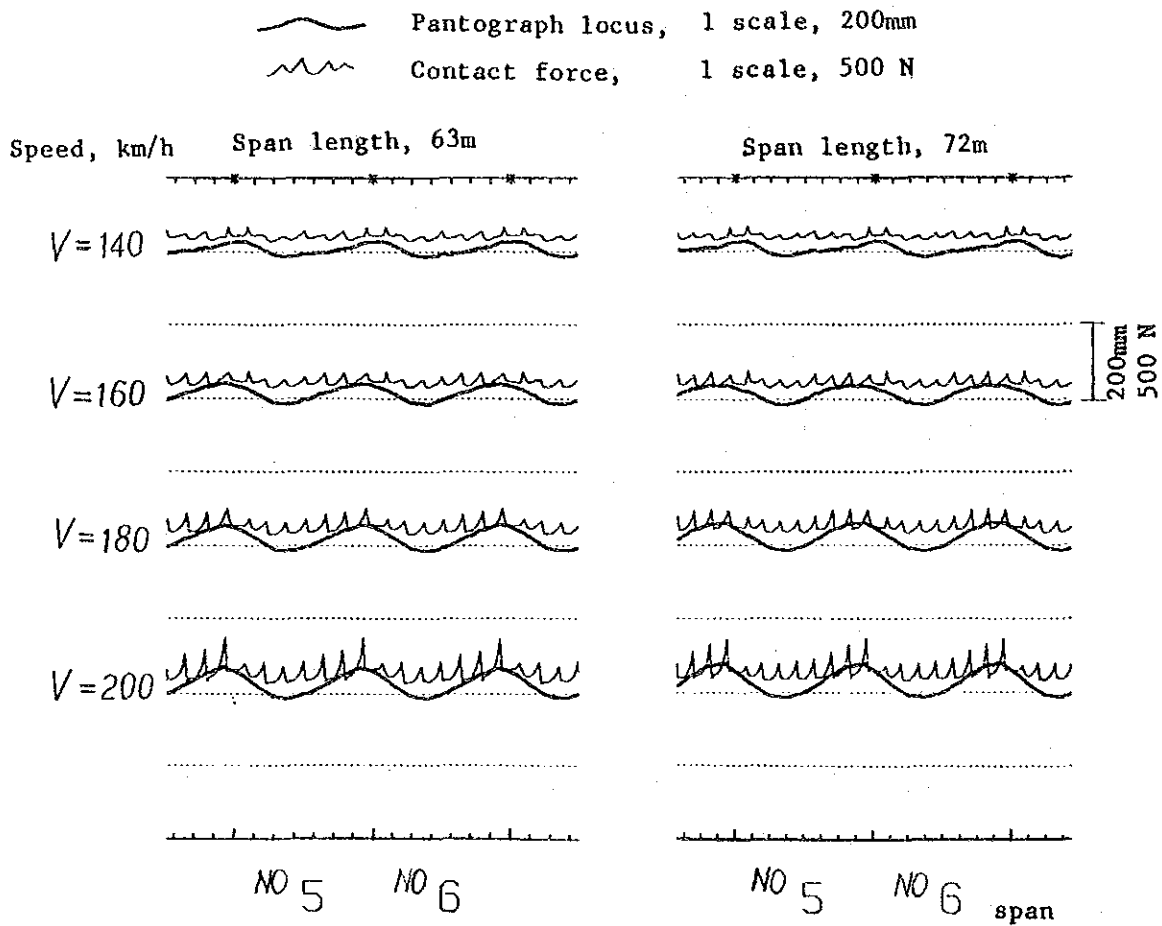


Fig. 8 Pantograph Locus and Contact Force

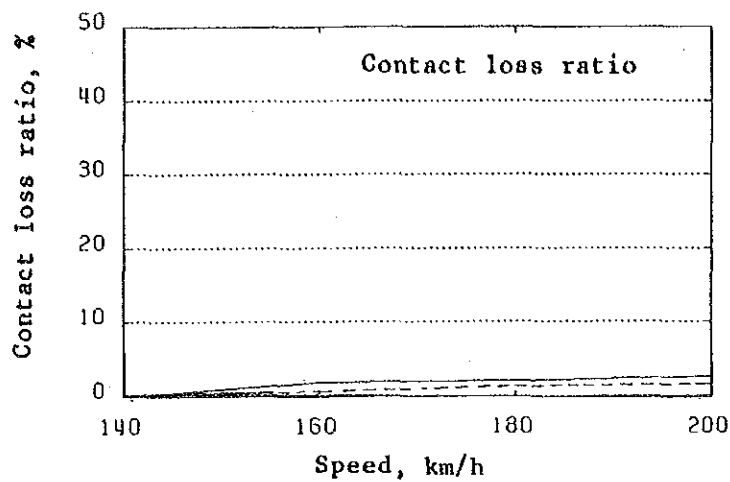


Fig. 9 Pantograph Running Speed vs. Contact Loss

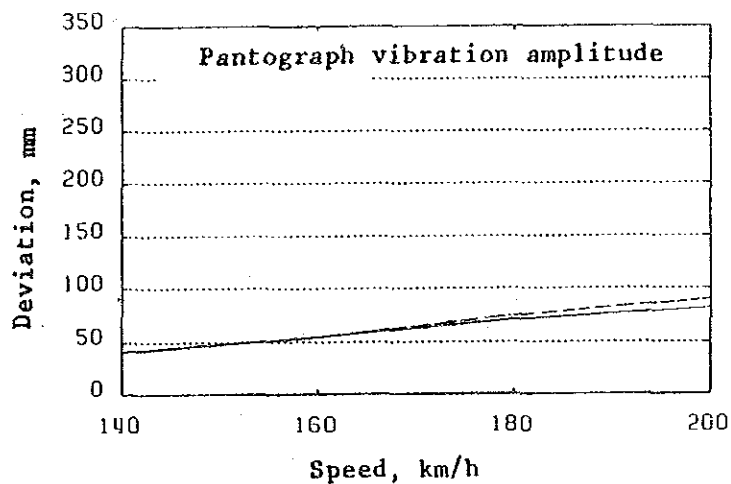


Fig. 10 Pantograph Running Speed vs. Vibration Amplitude

The pantograph vibration amplitude is about 55 mm at the speed of 160 km/h, about two-thirds of 80 mm on the existing OHE system.

Fig. 11 shows the uplift at each point in a span along with the time.

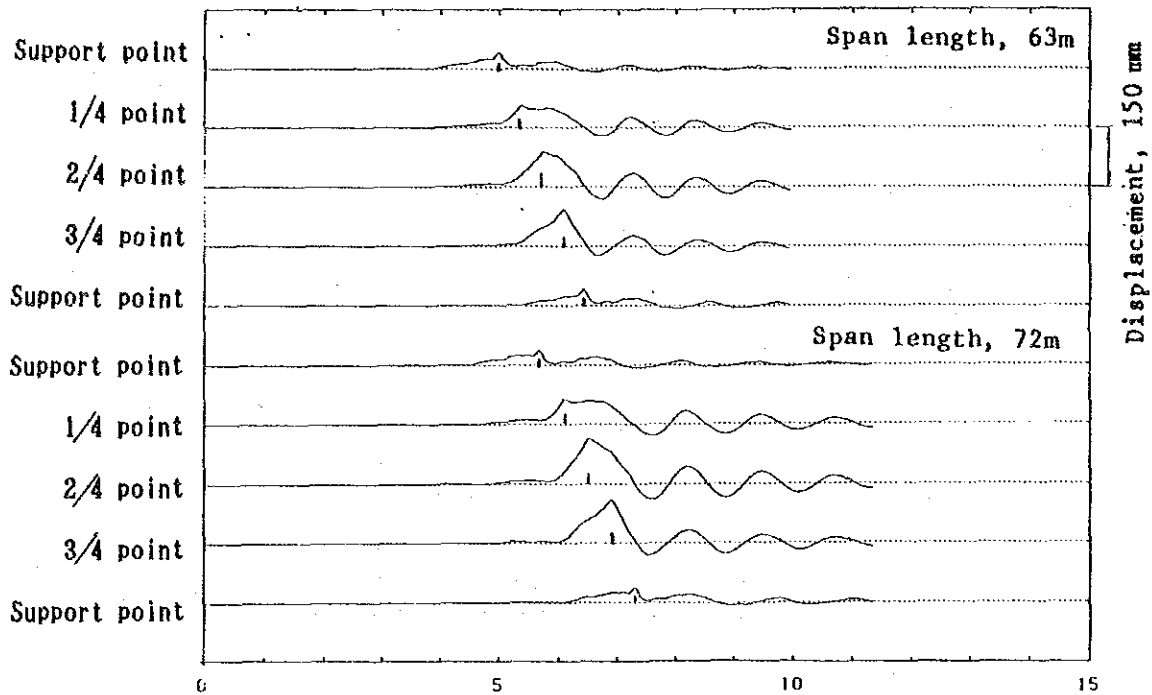


Fig. 11 Uplift at Each Point in a Span and Vibration

Residual vibration exists at the speed of 160 km/h, and this vibration shows the phenomenon similar to that on the existing OHE system (see Fig. 6). Tables 4.4.3-2 and 4.4.3-3 show the natural vibration. As can be seen from these figures, the vibration cycles on the upgraded OHE system are somewhat shorter than those on the existing OHE system.

Fig. 12 shows the relations between the uplift at each point in a span and the speed.



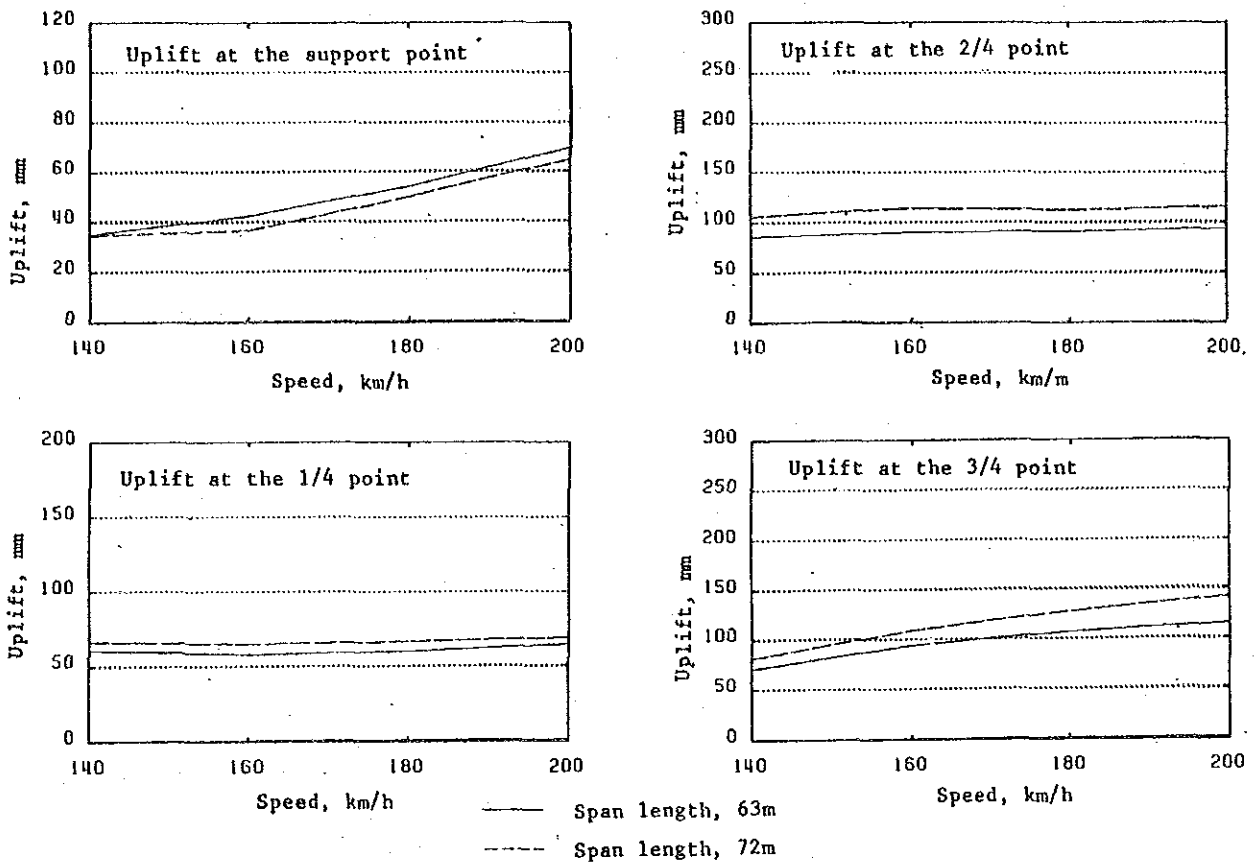


Fig. 12 Uplift at Each Point in a Span and Speed

The uplift at the support point is about 40 mm at the speed of 160 km/h. In other words, this uplift on the upgraded OHE system is smaller compared with that of about 55 mm on the existing OHE system in Fig. 7; and the uplift each at the 1/4 point, the 2/4 point (the span center) and the 3/4 point is also smaller than that in Fig. 7.

3) Two-pantograph running (at upgraded OHE system)

a) Results

Fig. 13 shows the pantograph locus and contact force when the speed is 160 km/h. Both pantographs are of AM-12 type; No. 1 is the front

pantograph, and No. 2 the rear. The distance between pantographs each in Diagrams A and B is 21 m, and C and D 34 m; the span each in A and C is 63 m, and in B and D 72 m.

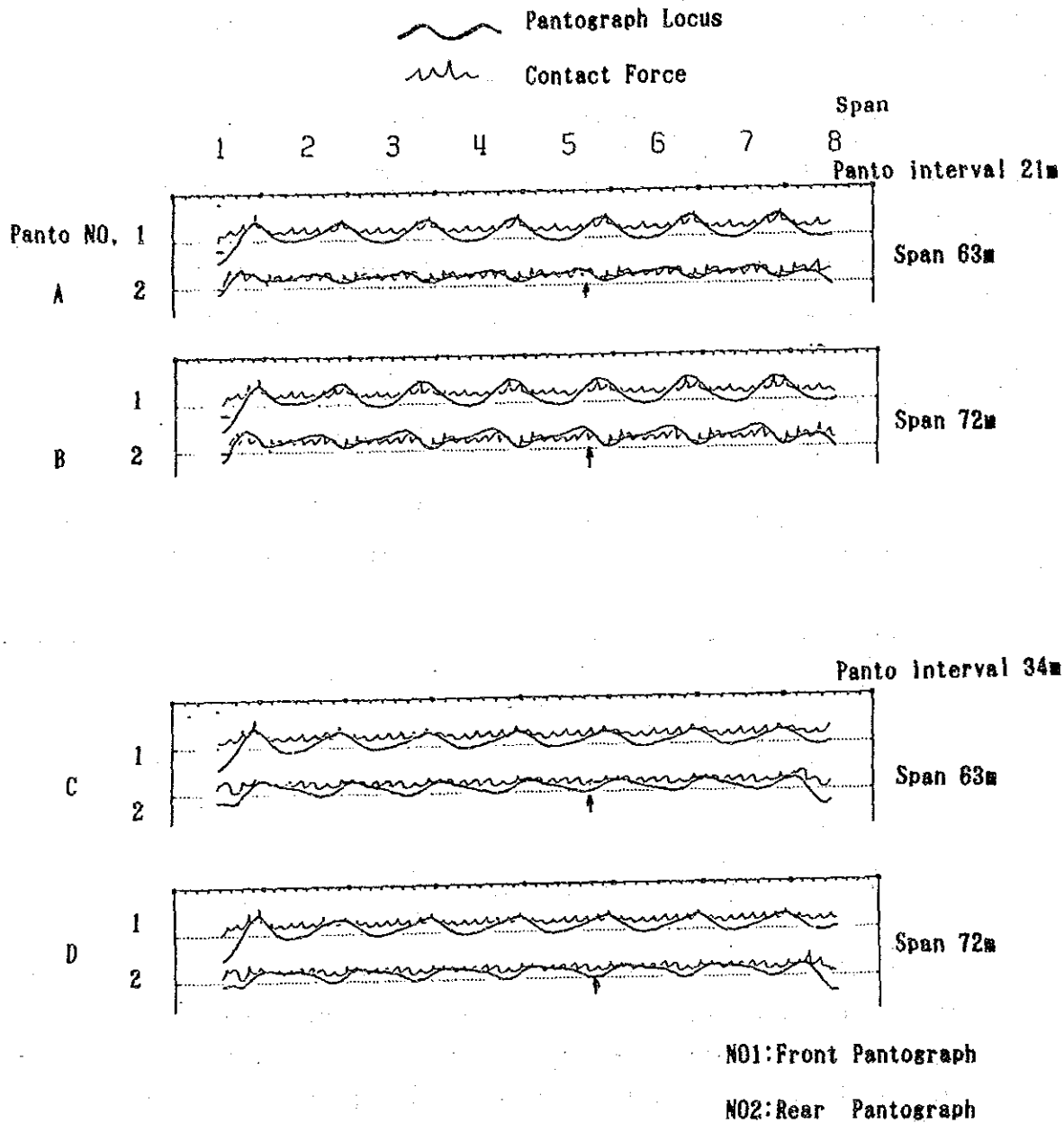


Fig. 13 Pantograph Locus and Contact Force

As can be seen in both the 63 m and 72 m spans, where the distance is 21 m the contact wire is uplifted by the rear pantograph together with the residual vibration, and where 34 m the rear pantograph is passing when the phase of vibration is in reverse (arrow marks).

Fig. 14 shows the relations between the uplift at each point in a span and the pantograph interval along with the time. As can be seen in Fig. 14 in the case that the two trains, one with 21 m pantographs interval and the other with 34 m, are running in a 63 m span at the speed of 160 km, the uplift by the former is larger than that by the latter. In the 34 m intervals residual vibration remaining after the rear pantograph has passed is little. This is because the rear pantograph has passed when the vibration phase of the OHE system is in reverse. On the other hand, there arises some residual vibration in the 21 m interval due to the vibration of OHE system overlapped.

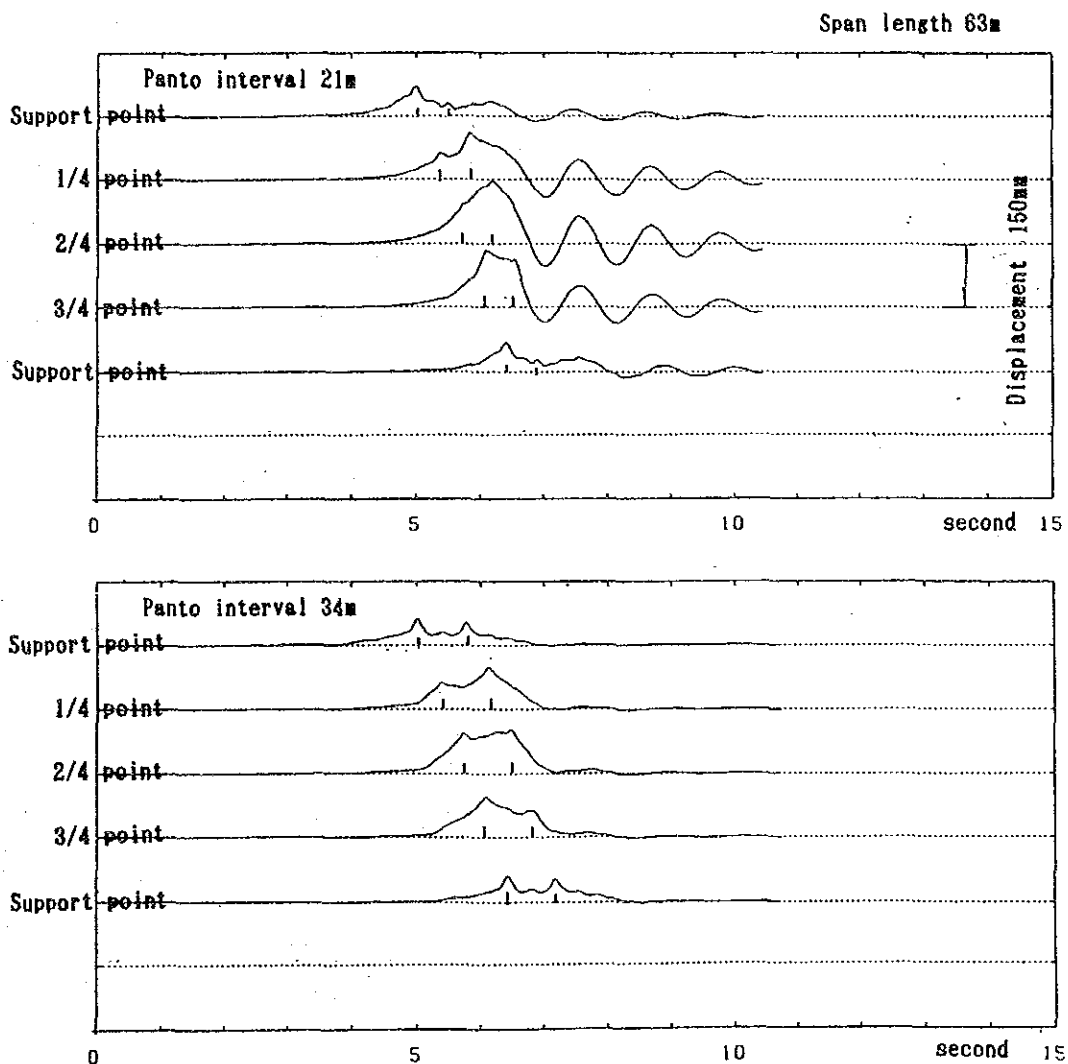


Fig. 14 Uplift at Each Point in a Span and Pantograph Interval

6-13 Computer Simulation Made on Pantographs of Different Mass for Various OHE System (72 m Span)

Computer simulation has been made on the following three combinations:

- (i) Catenary : Simple without presag  
Tension : 1,000 kgf x 2  
Pantograph : AM-12, 32 kg (equivalent mass)
- (ii) Catenary : Simple with presag 100 mm  
Tension : 1,000 kgf x 2  
Pantograph : AM-12, 32 kg (equivalent mass)
- (iii) Catenary : Simple without presag  
Tension : 1,000 kgf x 2  
Pantograph : PS-16, 18 kg (equivalent mass)

Other calculation conditions are the same as those in Appendix 6-12(1).

- As simulation results, Fig. 1 on contact loss shows almost the same tendency up to the speed of 170 km/h referring to both (ii) combination, and (iii) combination. This means that catenary with presag or pantograph of light equivalent mass (PS-16 type) are effective in suppressing contact loss.

On the other hand, in the case of (i) combination, the contact loss rate is about 5% at 160 km/h.

- Fig. 2 on vibration amplitude shows that the amplitude of vibration made by (ii) combination is the smallest. This means that the pantograph is capable of running nearly at a fixed height.

In the case of the catenary without presag, the vibration amplitude of pantograph becomes larger. Fig. 3 shows, however, that even with the catenary without presag, change in contact force is small if the equivalent mass of the pantograph is light. This means that the following characteristics of light pantograph to contact wire is good. Therefore, the contact loss (Fig. 1) as in (ii) and (iii) will show the same tendency.

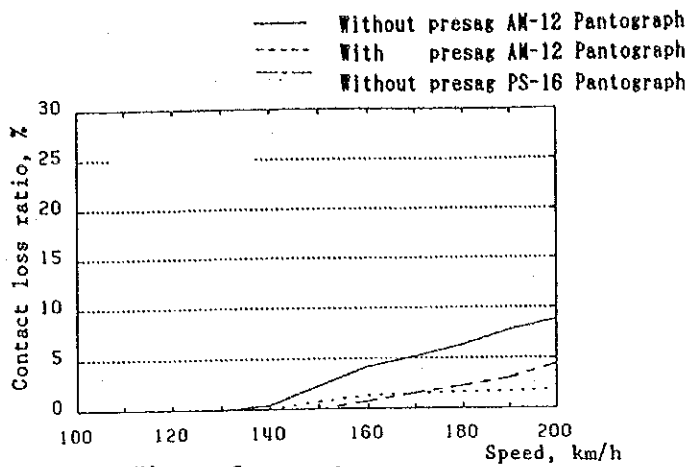


Fig. 1 Contact loss

Fig. 1

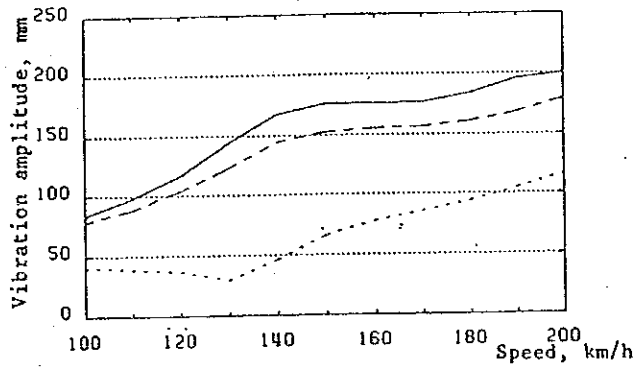


Fig. 2

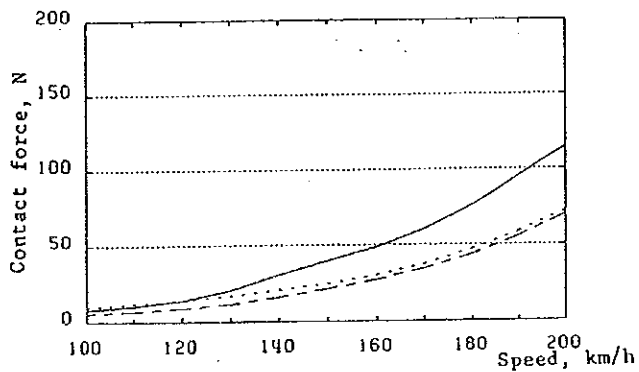


Fig. 3

- Fig. 4 shows the uplift of contact wire at each point given within a span. The faster the speed, the larger is the uplift at the supporting point; however, when the pantograph is light, the uplift is smaller even with the high speed.

In the case of the OHE with presag, the uplift each at the 2/4 point (the center of the span) and the 3/4 is small. This means that the presag is effective in suppressing the uplift of contact wire. Comparing the uplifts at the 2/4 point (the span center) and the 3/4 point, the speed becoming faster, the point where the uplift is maximum moves to the 3/4 point side. (Refer to Appendix 6-9, Fig. 3)

- In the area where the train runs at high speeds, the OHE with presag and pantograph of light equivalent mass is effective to achieve good current collection.

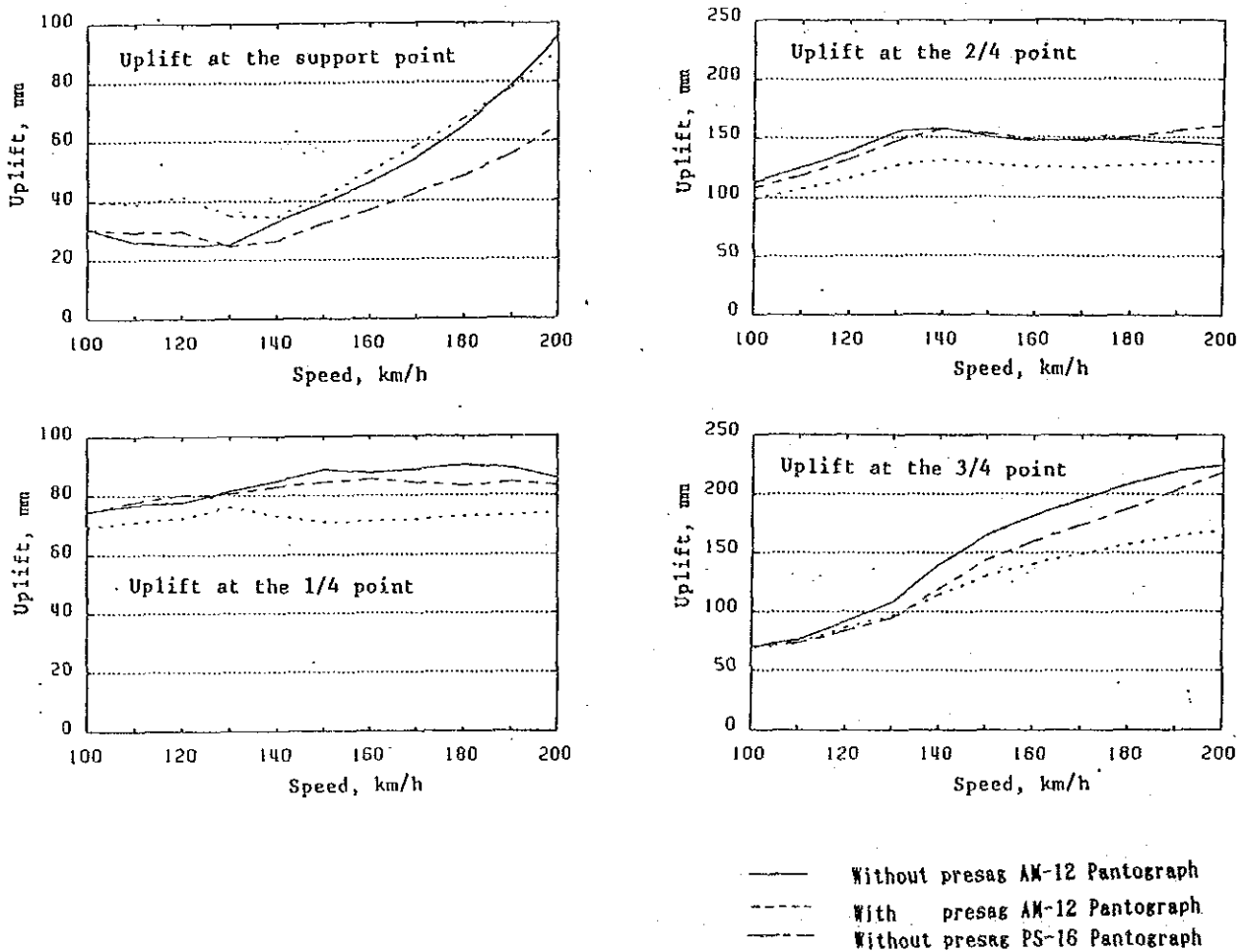


Fig. 4 Uplift of Contact Wire vs. Speed

## 6-14 Contact Loss

Contact loss means that the contact force of pantograph becoming zero or the contact wire and pantograph are separated affected by hard spot.

The contact loss usually accompanies spark discharge, which brings about a rise in temperature and partial wear to both the pantograph and contact wire. It also brings about surge voltage to the main circuit, threatening insulation. It can be classified by causes, as given below:

### (1) Cyclic contact loss at the support point

Contact loss period is approximately 0.01 to 0.1 second. It occurs cyclically per span. When a span length is short, multipantographs run closely, or due to the lowered tension of OHE system, it continues over several or more than ten spans. This is considered resulted from the pantograph and catenary system excessively used, which must be prevented.

### (2) Contact loss due to non-continuous point

This contact loss occurs when a pantograph shoe is hit by hard spot repeatedly, being a typical one on the OHE system, medium in size and continued for 0.001 ~ 0.01 second.

To prevent this contact loss, it is necessary to reduce the hardness of the spot. Overlap is an cause of hard spot together with, dropper, splicer, etc.

### (3) Contact loss due to vibration

The pantograph shoe and contact wire have their own natural vibration characteristics.

When either the pantograph shoe or contact wire vibrates, one cannot follow the other with the same vibration, causing contact loss. The contact loss period is 0.001 second or less, repeating cycle approximately 0.01 second, and continues 10 ~ 100 times.

## 6-15 Outline of the Electric Inspection Car of JR

The electric inspection car efficiently performs inspections of the OHE equipment, which previously required much labor, at a regular train operation speed.

Its appearance and measuring equipment are shown in Photograph 1 and 2.

### 1) Items measured

#### (a) Abrasion of contact wire

By grasping the abrasion conditions of contact wires, a replacement program is made to prevent the breaking troubles of contact wires.

The abrasion conditions of contact wires are continuously measured by the optical equipment whose main features are as follows.

- (1) Measuring can be made by day or night.
- (2) Four contact wires can be simultaneously measured.
- (3) Accuracy of measurement is 0.2 mm on wear width.

#### (b) Height of contact wire

For proper current-collecting the pantograph requires the uniform contact wire height.

The main axle of the pantograph is rotated by the up-and-down movement of the pantograph corresponding to the change in the contact wire height. The dynamic height of the contact wire above the railroad surface is continuously measured by detecting the rotating angle of the main axle.

#### (c) Deviation of contact wire

The installation of contact wire with proper deviation is one of the requirements to maintain good current-collecting characteristics.

The same optical measuring equipment as in the case of the abrasion measurement detects deviation of contact wire.



(d) Obstacles in the way of the pantograph driving

The obstacle detector catches obstacles against the pantograph passage as well as wrongly fitted angles of the OHE fittings (steady arms, pull-off fittings).

The pan of the pantograph is equipped with an antenna with a micro-switch which gives a signal when the fitting of the contact system hits the antenna.

(e) Hard spot

In the case of the contact wire having a partially heavy part, or having some bad points, the pantograph will be jolted causing contact loss or a partial wear of the contact wire.

The hard spot detector detects acceleration in the forward-backward and upward-downward directions of the pan head through a wire strain gauge-type accelerometer on the reverse side of the pan.

2) Data processing

The data measured and processed by the electric inspection car are effectively utilized for maintenance and control of the overhead contact system to secure safety in train operation.

The electric inspection car is equipped with data processing apparatus mainly composed of a mini-computer for the purpose of immediate processing the measured data during train operation.

The processed data is output in digital & analogue. The digital data is output by two terminal devices, (1) a high speed printer (whole data output at each span) and (2) typewriter (alarming data output).

Moreover, the entire data obtained are recorded in a magnetic tape in analogue by the data recorder and are effectively utilized for time sequential control of the contact wire abrasion.

3) Measurement period

Seven electric inspection cars are stationed on conventional lines throughout Japan.

The number of measuring inspection is 4 times a year in each line.

For Shinkansen lines, inspection cars in two sets are employed on the Tokaido & Sanyo Shinkansen Lines, and also two other sets on the Tohoku & Joetsu Shinkansen. The running speed is 210 ~ 240 km/h and the frequency of measuring inspections is about once a week.

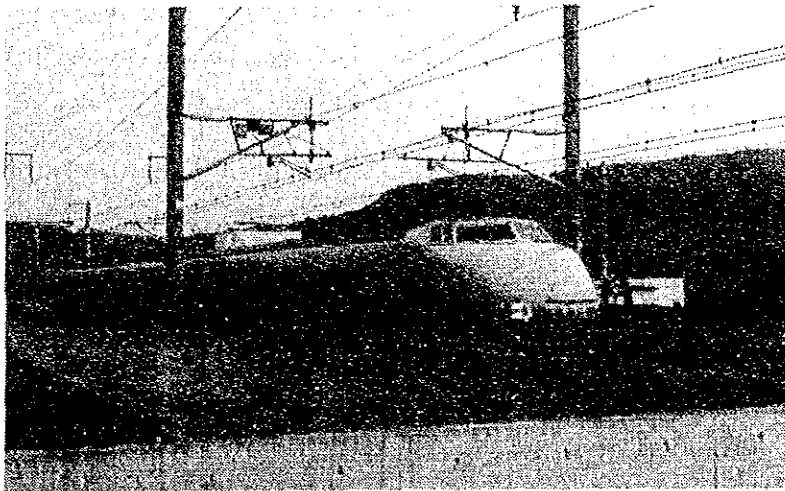


Photo 1 Electric Equipment and Track Inspection Train

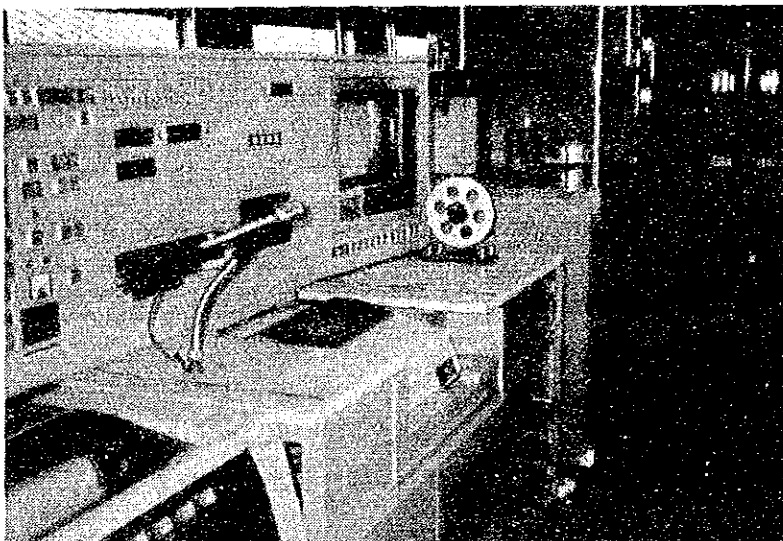


Photo 2 Measuring Equipment

7-1 Presumed Investment to be Made in the 7th 5 Year Plan by 1990 on the Section

1. Track and structure

(1) Extension of loop lines

Kanpur (up), Dankaur (up) ..... (Sanctioned)

(2) Construction of loop lines

Saraibhopat and 5 other stations ..... (Sanctioned)

Mandrak and 9 other stations ..... (Programmed)

Balrai and 4 other stations ..... (Proposed)

(3) Construction of emergency crossovers

Jalesar Road and 7 other stations ..... (Sanctioned)

Balrai and 11 other stations ..... (Programmed)

Jinjhak and 9 other stations ..... (Proposed)

(4) Construction of hot axle sidings

Saraibhopat and 2 other stations ..... (Sanctioned)

Jalesar Road and 2 other stations ..... (Programmed)

Dadri and 8 other stations ..... (Proposed)

(5) Track renewal work

Replacement of sleeper (P,R,C)

Dn 69.8 km ..... (Proposed)

Up 81.0 km ..... (Proposed)

(6) Extension of platform (to hold 25 coaches)

Kanpur  
Etawah  
Tundla  
Aligarh

} ..... (Programmed)

2. Signalling and telecommunications

(1) Construction of block huts

Samhon - Achalda and 4 other places ..... (Sanctioned)

- (2) Automatic signalling
- Tundla ~ Mitawali ..... (Sanctioned)
- Aligarh ~ Dankhan ..... (Programmed)

- (3) Auxiliary warning system
- Delhi ~ Mughalsarai (part of the section) ..... (Sanctioned)

- (4) SHF plan
- The nation wide SHF network plan is being studied by I.R.

### 3. Substation

- (1) Substation construction plans
- Pura and 5 other places ..... (Sanctioned)

### 4. Rolling stock

<u>EL</u>	(unit)
Express train (passenger) .....	3
Ordinary train (freight) .....	6
<u>Coach</u>	(make-up)
Express train .....	3
<u>Wagon</u>	(make-up)
Ordinary train .....	6





























8-4 Financial Analysis for the Delhi - Kanpur Railway Project - Case (B)

( UNIT : 1000 RS )

	1995	1996	1997	1998	1999	2000	2001	2002	2003	2004	2005	2006	2007	2008	2009	2010	2011	2012	2013	2014	2015	2016	2017	2018	2019	2020	2021	2022		
OPERATING PROFIT	0	0	0	0	0	1534077	1670011	1805946	1941880	2077815	2211521	2379287	2547053	2714819	2882586	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	
OPERATING REVENUE	0	0	0	0	0	3426767	3603594	3780422	3957249	4134076	4310903	4523312	4735721	4948129	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	
NEW CORRIDOR	0	0	0	0	0	2088796	3157029	3317263	3477497	3637731	3797064	3985099	4172235	4359370	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505
SUPER EXPRESS	0	0	0	0	0	429971	446585	463158	479752	496345	512930	538213	563486	588760	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034
LONG EXPRESS	0	0	0	0	0	1658825	2711244	2854105	2977745	3071386	3264134	3414325	3568345	3770610	3932471	3932471	3932471	3932471	3932471	3932471	3932471	3932471	3932471	3932471	3932471	3932471	3932471	3932471	3932471	3932471
TOTAL	0	0	0	0	0	3426767	3603594	3780422	3957249	4134076	4310903	4523312	4735721	4948129	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	
OPERATING EXPENSE	0	0	0	0	0	1892690	1933583	1974476	2015368	2056261	2099382	2144025	2188667	2233310	2277953	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	
NEW CORRIDOR	0	0	0	0	0	1892690	1933583	1974476	2015368	2056261	2099382	2144025	2188667	2233310	2277953	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565
WORKING COST	0	0	0	0	0	1127710	1159254	1190797	1222341	1253885	1286408	1320449	1354491	1388534	1422576	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189
MAINTENANCE COST	0	0	0	0	0	575599	582255	588912	595568	602224	609756	617288	624820	632352	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884
PERSONNEL COST	0	0	0	0	0	98300	99971	101633	103296	104958	106722	108381	110000	111638	113277	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018
ELEC COST	0	0	0	0	0	453802	477027	500252	523477	546702	569927	594799	619671	644543	669415	694287	694287	694287	694287	694287	694287	694287	694287	694287	694287	694287	694287	694287	694287	694287
DEPRECIATION	0	0	0	0	0	764980	774329	783678	793027	802376	812976	823576	834176	844776	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376
INVESTMENT	1695620	4144908	6122981	7604521	2820692	192660	192660	192660	192660	192660	217680	217680	217680	217680	2021925	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
FOREIGN TOTAL	0	393240	1088340	1088340	170880	0	0	0	0	0	0	0	0	0	544300	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
LOCAL TOTAL	1695620	3751668	5024641	6506181	2849812	192660	192660	192660	192660	192660	217680	217680	217680	217680	1477625	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ELECTRIFICATION	0	414140	769240	751340	309630	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
FOREIGN CURRENCY	0	0	79600	79600	39800	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
LOCAL CURRENCY	0	414140	689640	671740	269830	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
SIGNALS & TELECON	0	1279716	1279716	1279716	428572	0	0	0	0	0	0	0	0	0	1804245	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
FOREIGN CURRENCY	0	393240	393240	393240	131080	0	0	0	0	0	0	0	0	0	544300	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
LOCAL CURRENCY	0	886476	886476	886476	295492	0	0	0	0	0	0	0	0	0	1259945	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
CIVIL WORK	1540580	2234130	2234130	2389210	480150	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
FOREIGN CURRENCY	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
LOCAL CURRENCY	1540580	2234130	2234130	2389210	480150	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
LAND ACQ & COMP	155040	216920	165240	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
FOREIGN CURRENCY	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
LOCAL CURRENCY	155040	216920	165240	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
ROLLING STOCK	0	0	1674655	3184255	1604340	192660	192660	192660	192660	192660	217680	217680	217680	217680	217680	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
FOREIGN CURRENCY	0	0	625500	625500	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
LOCAL CURRENCY	0	0	1049155	2558755	1604340	192660	192660	192660	192660	192660	217680	217680	217680	217680	217680	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
-SALVAGE VALUE INT. DURING CONST.	115456	428159	919885	1588919	2088428	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
FINANCE PROGRAM																														
FINANCE TOTAL	1811076	4573065	7042666	9193440	4889120	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
BORROWING	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
REPAYMENT	1811076	8384141	13426807	22620246	27509366	27509366	27509366	27509366	27509366	27509366	27509366	27509366	27509366	27509366	27509366	27381913	27214459	27067005	26919551	26772097	26624643	26477190	26329736	26182282	26034828	25887374	25739921	25592467	25445013	
INTEREST	116456	428159	919885	1588919	2088428	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724	2168724
FINANCE IN FOREIGN CCY	0	401521	1132745	1164551	250259	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
BORROWING	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
REPAYMENT	0	401521	1534266	2698817	2949076	2949076	2949076	2949076	2949076	2949076	2949076	2949076	2949076	2949076	2949076	2801623	2654169	2508715	2359281	2211807	2064353	1918900	1769446	1621992	1474538	1327084	117			

	2007	2008	2009	2010	2011	2012	2013	2014	2015	2016	2017	2018	2019	2020	2021	2022	2023	2024
2547053	2714819	2882586	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973
4735721	4048129	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538
4172235	4359370	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505	4546505
563486	588700	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034	614034
4735721	4048129	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538	5160538
2188667	2233310	2277953	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565
2188667	2233310	2277953	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565	2304565
1354491	1388534	1422576	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189	1449189
624820	632352	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884	639884
110000	111638	113277	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018	115018
819071	844543	869415	894287	894287	894287	894287	894287	894287	894287	894287	894287	894287	894287	894287	894287	894287	894287	894287
834176	844776	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376
217680	217680	2021925	0	0	0	0	0	0	0	0	0	1804245	0	8595120	175620	175620	175620	175620
0	0	544300	0	0	0	0	0	0	0	0	0	544300	0	1894000	0	0	0	0
217680	217680	1477625	0	0	0	0	0	0	0	0	0	1259945	0	6701120	175620	175620	175620	175620
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	887750	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	199000	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	688750	0	0	0	0
0	0	1804245	0	0	0	0	0	0	0	0	0	1804245	0	1231400	0	0	0	0
0	0	544300	0	0	0	0	0	0	0	0	0	544300	0	444000	0	0	0	0
0	0	1259945	0	0	0	0	0	0	0	0	0	1259945	0	787400	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
217680	217680	217680	0	0	0	0	0	0	0	0	0	0	0	6475970	175620	175620	175620	175620
0	0	0	0	0	0	0	0	0	0	0	0	0	0	1251000	0	0	0	0
217680	217680	217680	0	0	0	0	0	0	0	0	0	0	0	5224970	175620	175620	175620	175620
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	13063155
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
27509366	27509366	27509366	27361913	27214459	27067005	26919551	26772097	26624643	26477190	26329736	26182282	26034828	25887374	25739921	25592467	25445013	25297559	25150105
2168724	2168724	2168724	2165683	2161628	2157573	2153518	2149463	2145408	2141353	2137298	2133243	2129188	2125133	2121078	2117023	2112968	2108913	2104858
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
2949076	2949076	2949076	2801623	2654169	2506715	2359261	2211807	2064353	1916900	1769446	1621992	1474538	1327084	1179631	1032177	884723	737269	590215
81100	81100	81100	78058	74003	69948	65893	61838	57783	53728	49674	45619	41564	37509	33454	29399	25344	21289	17234
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290	24560290
2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625	2087625
994825	1173191	-452887	1398213	1402268	1406323	1410378	1414433	1418487	1422542	1426597	-373593	1434707	-7156358	1267197	1271252	1275307	1279362	1283417
3590576	4763768	4311080	5709293	7111560	8517883	9928261	11342693	12761181	14183723	15610320	15236728	16671435	9515078	10782275	12053527	13328835	14614132	15949480
3381230	3559596	3737962	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349
2547053	2714819	2882586	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973	2855973
834176	844776	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376	855376
2386404	2386404	4190649	2313137	2300082	2305027	2300972	2296917	2292862	2288807	2284752	4084942	2276842	10867707	2444152	2440097	2436042	-10831168	-10831168
217680	217680	2021925	0	0	0	0	0	0	0	0	0	1804245	0	8595120	175620	175620	175620	-12887535
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
2168724	2168724	2168724	2165683	2161628	2157573	2153518	2149463	2145408	2141353	2137298	2133243	2129188	2125133	2121078	2117023	2112968	2108913	2104858
3163550	3341910	1716037	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	3711349	1907104	3711349	-4883771	3535729	3535729	3535729	16508885
9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86	9.86

